## Industrial Encoders \& Accessories Catalog

Issue No. 8

## 50th fansiversary Edjeios

YEARS OF QUALITY

## encoder solutions that Just make sense.

## Company History

Encoder Products Company, Inc. is a leading designer and world-wide manufacturer of motion sensing devices. Founded in 1969 by William Watt, EPC began operations with a small line of custom encoders. Today, EPC's popular Accu-Coder ${ }^{\text {M }}$ brand is the most complete line of incremental and absolute shaft encoders in the industry. Our core philosophy is that each and every customer deserves quality products, superior customer service, and expert support.

## Business Partnerships

Fostering long-term business partnerships with satisfied customers is what we do best, and is at the heart of our mission. We take pride in providing superior customer service and supplying our customers with encoders that function precisely, dependably, and flawlessly. Listening to our customers needs, and designing products that provide solutions for them, is a key to our success.

## Setting the Standard

At EPC, we concentrate on encoders, and we have a long list of "firsts" to our name.

- First to design the cube style encoder, now an industry standard.
- First to resolve mounting installation problems by providing a flexiblemounting system.
- First to include Opto-ASIC technology, which virtually eliminates miscounts by eliminating electrical noise and enhancing signal quality.
- First to provide an encoder that operates at $120^{\circ} \mathrm{C}$.
- First to provide 6000 CPR in a $1.5^{\prime \prime}$ diameter encoder.
- First to provide a 3 year standard warranty because we stand proudly behind the reliability of each of our products.

We will continue to do what we do best so that you can have the very best encoder for the job.

## Solving Problems

We believe that an encoder supplier should solve problems, not cause them. Since 1969, we have been solving encoder problems with our custom designs, faster delivery, and reliable products - which set us apart from the competition.

## Custom Encoders Our Specialty

Through years of experience, we understand that each industrial environment is different and that you need an encoder that fits your specific situation. Ultimately, this means not having to make due with someone else's specifications or configurations, but having your own custom designed unit. Many of our customers have come to depend on us for this special area of customization, because we can design and deliver custom encoders faster than most suppliers' standard products; standard delivery time for most products is just 4 to 6 days business days, and we offer same-day expedite options on many products.

## ISO 9001 Quality Systems

At EPC, quality is designed into every product. Before it's offered for sale, each new Accu-Coder ${ }^{\text {rM }}$ model is fully tested against EPC's exacting quality standards. But quality doesn't stop at design: during the manufacturing process, each Accu-Coder ${ }^{\text {rM }}$ is subjected to a series of stringent quality control tests to ensure you are receiving the best encoder available. Our quality system has successfully been audited to the requirements of ISO 9001:2015, an internationally recognized standard for comprehensive Quality Systems. By paying close attention to detail, our Accu-Coder ${ }^{\text {rM }}$ brand has become known throughout the industry for quality and reliability.



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## QUICK SELECTION GUIDE

## ABSOLUTE ENCODERS



Model A58HE

- EtherCAT Deterministic Communication: CoE, FoE, EoE
- 58 mm Diameter Package
- Hollow Bore Construction
- Durable Magnetic Technology



## Pg 16

Ø36 mm
Model A36SB

- Multiturn or Single Turn Absolute Encoder
- Durable Magnetic Technology
- Standard Size 36 mm Package (1.42")
- SSI and CANopen Communications
- New Turns Counting TechnologyNo Gears or Batteries


Ø2.5"

## Pg 22

Model 925

- Industrial Housed 2.5" Single Turn Absolute
- Gray, Natural Binary, and Excess Gray Codes
- Shaft Sizes to $0.375^{\prime \prime}$, or 10 mm
- Flange and Servo Mounts
- Sealing Up to IP67



## Model A58SE

- EtherCAT Deterministic Communication: CoE, FoE, EoE
- 58 mm Diameter Package
- Shaft Unit with 2 Mounting Options
- Durable Magnetic Technology


## Pg 14



## Model A36HB

- Multiturn or Single Turn Absolute Encoder
- Durable Magnetic Technology
- Standard Size 36 mm Package (1.42")
- SSI and CANopen Communications
- New Turns Counting TechnologyNo Gears or Batteries

ø2.5"


## Model A25SB

- Standard size 25 package ( $2.5^{\prime \prime} \times 2.5^{\prime \prime}$ )
- Durable magnetic technology - no gears or batteries
- Servo and flange mounting
- Multi-turn absolute encoder (14-bit/39-bit)


## LINEAR MEASUREMENT SOLUTIONS

## INCREMENTAL THRU-BORE \& MOTOR MOUNT ENCODERS



## Pg 40

Ø1.5"
Model 15T/H

- Resolutions to 10,000 CPR
- Up to 12 Pole Commutation Available
- Bore Sizes to $0.375^{\prime \prime}$, or 10 mm
- Operating Temps from $-40^{\circ}$ to $120^{\circ} \mathrm{C}$
- Sealing Up to IP64


## Pg 50



Ø2.25"
Model 225A/Q

- Single Channel \& Quadrature
- Economical Tachometer
- Motor Feedback
- Bore Sizes to $0.875^{\prime \prime}$, or 22 mm


## Pg 58



## Model 58TF/HF

- 58 mm package available in thru-bore or hollow bore
- Resolutions from 1 to 65,536 CPR
- 6 different output types
- 32 different waveforms available


Model 770

- Fits NEMA Frame Size 56C Thru 184C
- Resolutions to 4096 CPR
- Bore Sizes to 1.00 ", or 24 mm
- Large Selection of Connector Options
- Operating Temps from $0^{\circ}$ to $100^{\circ} \mathrm{C}$


Ø1.5"

## Pg 44

Model 755A

- Resolutions to 30,000 CPR
- Bore Sizes to 0.750 ", or 14 mm
- A Variety of Flexible Mounting Brackets
- Operating Temps from $-40^{\circ}$ to $100^{\circ} \mathrm{C}$
- Frequencies to 1 MHz


## Pg 52



Ø2.5"

## Model 25T/H

- Replaces 2.0" to 3.5" Encoders
- Resolutions to 10,000 CPR
- Bore Sizes to 1.125 ", or 28 mm
- Versatile Flexible Mounting Options
- Operating Temps from $-40^{\circ}$ to $105^{\circ} \mathrm{C}$


Model 775

- Slim Profile - to $1.36^{\prime \prime}$ Thru-Bores
- Resolutions to 4096 CPR
- Bore Sizes to 1.875 ", or 43 mm
- Large Selection of Connector Options
- Operating Temps from $0^{\circ}$ to $100^{\circ} \mathrm{C}$



## Model 771

- Fits NEMA Frame Size 182TC Thru 256TC
- Standard Double C-Face
- Resolutions to 4096 CPR
- Bore Sizes to $1.875^{\prime \prime}$, or 43 mm
- Optional protective cover affords IP65 Sea


## Pg 46



Ø2.0"
Model 260

- Resolutions to 10,000 CPR
- Bore Sizes to $0.625^{\prime \prime}$, or 15 mm
- A Variety of Flexible Mounting Brackets
- Operating Temps from $-40^{\circ}$ to $120^{\circ} \mathrm{C}$
- Sealing Up to IP64


## Pg 54



Model 58TP/HP Programmable

- Programmable with USB Module or Factory Configured when Ordered
- Programmable Resolution from 1 to 65,536 CPR
- Programmable output type and waveform


Model 776

- Slim Profile - to $1.36^{\prime \prime}$ Thru-Bores
- Resolutions to 4096 CPR
- Bore Sizes to $1.875^{\prime \prime}$, or 43 mm
- Large Selection of Connector Options
- Operating Temps from $0^{\circ}$ to $100^{\circ} \mathrm{C}$


## QUICK SELECTION GUIDE

## INCREMENTAL SHAFT ENCODERS



Pg $70-77$
Ø2.25"
Models 711, 715 \& 716

- The Original Cube Encoders
- Single Channel, Quadrature and Timed Pulse
- Five Versatile Heavy Duty Housing Styles
- Resolutions to 10,000 CPR
- Single and Double Shaft Options



## Pg 84

Ø2.0"

## Model 702

- 80 lb . Max. Radial and Axial Load
- Resolutions to 30,000 CPR
- Shaft Sizes to 0.375 ", or 10 mm
- Operating Temps from $-40^{\circ}$ to $100^{\circ} \mathrm{C}$
- Sealing Up to IP67


Pg 78
Ø1.5"
Model 15S

- Resolutions to 10,000 CPR
- Up to 12 Pole Commutation Available
- Wide Variety of Mounting Options
- Operating Temps from $-40^{\circ}$ to $120^{\circ} \mathrm{C}$
- Sealing Up to IP64


Pg 88
Model 25SP Programmable

- Programmable waveform, output type, and resolution
- Resolutions from 1 to 65,536 CPR (262,144 quadrature counts)
- 2.7 MHz max frequency
- Designed for industrial environments
- Sealing Up to IP67


Pg 82
Ø1.5"
Model 755A

- Resolutions to 30,000 CPR
- Frequencies to 1 MHz
- A Variety of Servo and Flange Mounts
- Available with In-Line M12 Connectors
- Operating Temps from $-40^{\circ}$ to $100^{\circ} \mathrm{C}$



## Pg 92

$\varnothing 2.5 "$

## Model 25SF

- Resolutions from 1 to 65,536 CPR (262,144 quadrature counts)
- 32 waveforms to choose from
- 6 different output types available
- 2.7 MHz max frequency
- Designed for industrial environments
- Sealing Up to IP67


Pg 94
Ø2.5"
Model 725

- Industrial Isolated Flex Housing Available
- Standard and Industrial Housing Available
- Resolutions to 30,000 CPR
- Operating Temps from $-40^{\circ}$ to $100^{\circ} \mathrm{C}$
- Sealing Up to IP67


Pg 98
Ø58 mm

## Model 758

- 80 lb . Max. Radial and Axial Load
- Resolutions to 30,000 CPR
- Clamping or Synchro Flange Options
- Operating Temps from $-40^{\circ}$ to $100^{\circ} \mathrm{C}$
- Sealing Up to IP67


Pg 100
Model 802S

- 2.0" Industrial 316 Stainless Steel Housing - 80 lb . Max. Radial and Axial Load
- Resolutions to 30,000 CPR
- Shaft Sizes to $0.375^{\prime \prime}$, or 10 mm
- Sealing Up to IP67


Pg 102
$Ø 58$ mm

## Model 858S

- 58 mm Industrial 316 Stainless Steel Housing
- 80 lb . Max. Radial and Axial Load
- Resolutions to 30,000 CPR
- Clamping or Synchro Flange Options
- Sealing Up to IP67


Pg 104
Ø6.5"

## Model 865T

- Fits NEMA Frame Size 56C Thru 184C Motors
- Slim 1" Profile Housing in 316 Stainless Steel
- Resolutions to 4096 CPR
- Bore Sizes to 1.00 ", or 24 mm
- Sealing Up to IP66 with Optional Cover


## INCREMENTAL MODULE AND MODULAR ENCODERS



Pg 106
Ø30 mm
Model 30M

- Resolutions to 1024 CPR
- Optional 2, 4 or 8 -pole commutation
- Sealing options to IP69K
- Temperature range $-40^{\circ}$ to $120^{\circ} \mathrm{C}$


Pg 108
Ø30 mm
Model 30MT

- Resolutions to 1024 CPR
- Threaded housing
- Sealing options to IP69K
- Temperature range $-40^{\circ}$ to $120^{\circ} \mathrm{C}$


Pg 112
Ø2.0"
Model 121

- Patented Auto Aligning Modular Encoder
- Up to 12 Pole Commutation Available
- Bore Sizes to $0.625^{\prime \prime}$, or 15 mm
- Ideal for higher speed motor applications
- Resolutions to 2540 CPR

Call Sales \& Customer Service at 800-366-5412
EPC is open for business from 8:00 am to 7:30 pm EST/ 5:00 am to 4:30 pm PST.

## ENCODER BASICS

## What is an encoder?

An encoder is a sensing device that provides feedback from the physical world - it converts motion to an electrical signal that can be read by some type of control device, such as a counter or PLC. The control device can then use that signal to control a conditional event, such as activating a print head to create a mark at a specific location.

Encoders use different types of technologies to create a signal. Some common encoder technologies are: mechanical, magnetic, resistive, and optical. Currently, the most common technology employed by encoders is optical.

Encoders may produce either incremental or absolute signals. Incremental signals do not indicate specific position, only that the position has changed. Absolute encoders, on the other hand, use a different "word" for each position, meaning that an absolute encoder provides both the indication that the position has changed and an indication of the absolute position of the encoder.

Incremental encoders are available in two basic output types, single channel and quadrature, shown below.


A single channel encoder, often called a tachometer, is normally used in systems that rotate in only one direction and require simple position and velocity information.

Quadrature encoders have dual channels (A and B), phased 90 electrical degrees apart. These two output signals determine the direction or rotation by detecting the leading or lagging signal in their phase relationship. Quadrature encoders provide very high speed bi-directional information for very complex motion control applications.

## How an incremental encoder square wave is produced:

The inset diagram outlines the basic construction of an incremental encoder. A beam of light emitted from an LED passes through a transparent disk patterned with opaque lines. The light beam is picked up by a photodiode array, also known as a photosensor. The photosensor responds to the light beam, producing a sinusoidal wave form, which is transformed into a square wave or pulse train. This pulse signal is then sent to the counter or controller, which will then send the signal to produce the desired function.

The diagram is for a typical rotary encoder. Incremental encoders can provide a once-per-revolution pulse (often called the index, marker, or reference) that occurs at the same mechanical point of the encoder shaft revolution. This pulse is on a separate output channel $(Z)$ from the signal channel or quadrature outputs. The index pulse is often used to position motion control applications to a known mechanical reference.

Resolution is a term used to describe the Cycles Per Revolution (CPR) for incremental encoders. Each incremental encoder has a defined number of cycles that are generated for each 360 degree revolution of the shaft. These cycles are monitored by a counter or motion controller and converted to counts for position or velocity control. The diagram shows how the whole encoder comes together.

If you still have questions as to how an encoder works in your specific application, please call us. When you contact EPC, you talk to engineers and encoder experts for your toughest encoder questions.

## TYPICAL USAGE

Motor Feedback is the most common use for rotary encoders. In this type of application, an encoder is either mounted directly to the motor, or indirectly using a measuring wheel or chain-and-sprocket arrangement. The parameter of interest is primarily the speed of the motor.

Web Tensioning is an application in which the encoder is not usually mounted to the drive motor, but to one of the tensioning arm rollers. Any unevenness in the speed of this roller indicates that proper web tension is not being maintained and must be adjusted. The rotating speed of the tensioning roller is fed back to the controller, which then adjusts the drive motor so that web material is kept at an even tension.

Cut-to-Length is a very practical application of an encoder combined with simple mathematics. If, for example, a system were to be designed with a roller that is exactly one foot in circumference, the roller would feed one foot of material for every revolution of the roller. An encoder mounted to the roller would reflect this situation and could tell a controller how much material had been fed through the roller. The resolution of the encoder would also directly reflect the accuracy of the cut. In the above example, 96 CPR would yield cuts to an $1 / 8$ "accuracy.

Elevators are just one example where encoders can perform a dual role: they can determine the position of the elevator through a mathematical calculation; and they can determine the speed of travel of the elevator.

Registration Mark Timing uses encoders to determine the position of a unit relative to a known point, and then to determine the unit's speed relative to that mark. Radar antenna rotation is a good example of this type of application.

In Backstop Gauging, the encoder is used to make sure that the unit, typically a machine tool, does not exceed a pre-set position or direction of travel. Very often, this is combined with a determination of the speed of travel of the table, tool head, or similar component. Filling applications is just one example where Table Positioning is critical since the item being filled must arrive at filling tube at the same time the fluid control is turned on.

Conveying is another common industry where encoders are widely used. They may be attached to the motor, to intermediate axle shafts, or to both. Encoders are an especially effective feedback device where the positioning and/or speed of multielement conveying systems must be carefully coordinated.

Spooling (sometimes referred to as Level Wind) is another application where encoders can prove invaluable. Not only is it necessary for the speed of the supply and take-up reels to be kept in proper relation to each other, but often the amount of material being spooled must also be tracked.

Electronics is just one industry that widely uses encoders in pick-and-place applications, where many of the capabilities of encoders (rate, position, speed, velocity) can often be found combined in a single system.


## ENCODER SELECTION CONSIDERATIONS

## Modular vs. Bearing Encoders

When deciding whether a modular or bearing encoder is the best solution for your application, consider these factors:

1. First and foremost, shaft end float and total indicated runout (TIR) must be within the encoder's specifications. This is so important that if you don't have (or can't get) this information, or don't trust what you have, an encoder with bearings is strongly recommended since it will be a much safer choice.
2. Modular encoders can be a good choice for high-speed applications - above 10,000 RPM - because there are no speed limitations dictated by encoder bearings. For example, EPC's Accu-CoderTM Model 121 Modular Encoder has been successfully operated at speeds in excess of 40,000 RPM. The speed limiting factor is the maximum frequency of the encoder (which is a function of disk resolution), RPMs, and the signal processing circuitry. Most encoder manufacturers include maximum frequency in product specifications.
3. If the motor is to be used under considerable mechanical load, where the motor bearings could experience extra wear, then an encoder with bearings would be the better choice. Remember, the bearings of the host device serve as the bearings of the modular encoder.
4. Modular encoders are difficult to seal. If your application requires washdown, or if the operating environment is dirty, dusty or wet, then an encoder with bearings and seals should be your first consideration. Such environments effectively rule out modular encoders, unless external protection, such as an IP sealed motor cover, is used.
5. If your application requirements combine high maximum frequency (> 200kHz), high temperature ( $100^{\circ} \mathrm{C}$ or higher), and higher resolution (> 2048 CPR ), then an encoder with bearings is recommended. For long term reliability, this combination of factors requires the air-gap between the disk and sensor to be very narrow and tightly controlled. An encoder with bearings simply provides a more stable optical platform.
6. Lower resolutions (up to 1024 CPR) are more forgiving of end float and TIR, and are often well-suited for modular applications if the operating environment is appropriate.
7. If you plan to use numerous encoders, then the relatively lower price of a modular encoder could save you some money. On the other hand, the greater durability and easier installation of an encoder with bearings might be worth a slightly higher unit price. In any case, carefully weigh the factors of long term support costs versus lower acquisition costs before making your final decision.

## Quick Selection Chart

| Parameter | Attribute | Use Modular | Use Encoder with <br> Bearings |
| :--- | :--- | :--- | :--- |
| Motor shaft end float and TIR | Within the encoder manufacturer's specifications | Yes | Yes |
| Motor shaft end float and TIR | Outside the encoder manufacturer's specifications | No | Yes |
| Motor shaft end float and TIR | Don't have the information or don't trust | Not suggested | Suggested |
| High-speed applications | Above 10,000 RPM | Good possibility | Not suggested |
| Severe duty application | Motor bearings have extra load and wear | Not suggested | Suggested |
| Dirty environment | May need seals | Not suggested | Suggested |
| Combination of high frequency <br> response, temperature, CPR <br> Lower resolution requirement | $>200 \mathrm{kHz},>100^{\circ}$ C, >2048 CPR | Not suggested | Suggested |
| Number of units needed | <1024 cycles per revolution | Good possibility | Good |

# INTRODUCTION TO ABSOLUTE ENCODERS 

Absolute encoders differ from incremental encoders in how they report position information. Both types of encoders provide a signal to indicate a change mechanical position; however, where incremental encoders provide a series of pulses to indicate an incremental change in position as the shaft rotates, an absolute encoder provides a unique value indication of the position of the shaft. This allows an absolute encoder to report its exact position as soon as the system powers up, while an incremental encoder would need to return to a known position.

Absolute encoders provide position information for a rotating shaft within either a single rotation (single turn), or over the course of multiple rotations (multi-turn). The encoder provides a unique digital code or bit for


A selection of absolute encoders available from EPC each increment of shaft rotation. Multi-turn absolute encoders store turns-counting information for instant retrieval, even after power down. EPC offers both single turn and multi-turn absolute encoders with a variety of housing sizes, bore diameters, signal types and resolutions (see pages 10-25 for EPC's absolute encoder model options).

## Advantages of EPC Absolute Encoders

- Remember position after a power outage, no need to re-home
- Typically have speed, scaling, preset, and fieldbus functions
- Allow you to determine the exact position of a machine and control over the storage of electronic data
- Multiple interface options: Parallel, Synchronous Serial Interface (SSI), CANopen, and EtherCAT
- Single turn and multi-turn options available, with resolution up to 16 Bit for Single Turn and 43 Bit for Multi-Turn
- Maintenance-free and environmentally friendly all-magnetic design
- Energy harvesting magnetic multi-turn technology - no gears or batteries
- Meet CE/EMC standards for immunity and emissions


## When to Use Absolute Encoders

There are certain considerations that would suggest the use of an absolute encoder rather than an incremental encoder. These considerations include, but are not limited to:

- Connectivity. When you need your encoders to communicate over a network, absolute encoders offer more communication protocol options.
- Electrical Noise. Absolute encoders are more resistant to electrical noise.
- Reliability of Power Supply. If your application is subject to power loss, an absolute encoder is a better choice because it will retain its position after a power-off scenario.

If you have questions about using an absolute encoder, call our Technical Services Department. You'll talk to real engineers who understand absolute feedback in motion control, and will help you find the right encoder solution for your application.

## Absolute Encoders

## MODEL A58HE



## FEATURES

Single/Multi-Turn Absolute Encoder (16 Bit ST / 43 Bit MT)
EtherCAT with CoE, FoE, EoE
Maintenance-Free and Environmentally Friendly Magnetic Design
Energy Harvesting Magnetic Multi-Turn Technology
No Gears or Batteries
Electronic Cam Switches
Low TCO and easy provisioning with internal web server
Color LEDs for operating condition, bus status, link activity
Compact design with bus cover
58 mm (2.28") Diameter Package

COMMON APPLICATIONS
Robotics, Telescopes, Antennas, Medical Scanners, Wind Turbines, Elevators, Lifts, Motors, Automatic Guided Vehicles, Rotary and X/Y Positioning Tables

## EPC Absolute Encoder - now with EtherCAT connectivity

The Model A58HE is an EtherCAT-ready, multi-turn absolute encoder designed for harsh factory and plant environments. It is particularly suited to applications where Ethernet-based connectivity is required, and the encoder must retain position information after poweroff events. Easily designed into a wide variety of system applications, the Model A58HE plugs directly into your network with minimal provisioning for rapid deployment, facilitating data exchange among myriad networked devices. The Model A58HE retains absolute position information even after a power loss, facilitating speedy system recovery at start-up without the need for system re-homing.

Ready for Industry 4.0 and for the Industrial Internet of Things (IIOT), data exchange between the Model A58HE and other applications has no influence on the control loop. The Model A58HE is non-reactive and can work independently from the PLC or master, transferring data through network gateways to other automation networks and sites, and up to the cloud for analysis.

MODEL A58HE ORDERING GUIDE
Blue type indicates price adder options.


MODEL A58HE 63 MM 2 PT. FLEX MOUNT (SR)


Primary dimensions are in mm , secondary dimensions SI units [inches] in brackets for reference only.

## NETWORK BUS CONNECTOR PINOUT

Bus cover with $3 \times$ M12 2 1. For EPC-supplied mating cables, wiring table is provided with cable. Trim back and insulate unused wires.

Port 1 (In)


Power


| Connector | M12×1, |
| :--- | :---: |
| (Power) | 4 -pin, |
|  | A-coded |


| $(+)$ Vcc | 1 |
| :---: | :---: |
| n.c. | 2 |
| GND | 3 |
| n.c. | 4 |

Port 2 (Out)


| Female | M12×1, |
| :--- | :---: |
| Connector |  |
| (Port2) OUT | 4-pin, |
| Tx+ | 1 |
| Rx+ | 2 |
| Tx- | 3 |
| Rx- | 4 |

## MODEL A58HE SPECIFICATIONS

## Electrical

Power Supply .......... 10 VDC up to 32 VDC
Current
Consumption.............typ. 125 mA
Power
Consumption.............typ. 3 W

## Sensor Specification

Internal Cycle Time .. $50 \mu \mathrm{~s}$
Resolution

$$
\text { Single Turn .......... up to } 65,536 \text { steps } / 360^{\circ}(16 \text { bit })
$$

Multi-Turn........... 43 bit
Accuracy
Single Turn .......... $\pm 0.0878^{\circ}$ ( $\leq 12$ bit)
Single Turn, Repeat
Accuracy............. $\pm 0.0878^{\circ}$ ( $\leq 12 \mathrm{bit}$ )
Technology
Single Turn .......... Innovative Hall-sensor technology
Multi-Turn...........Patented energy-harvesting technology, no battery and no gears
Turn on time < 1.5 s

## Interface

Interface................... Industrial Ethernet
Protocol....................EtherCAT
Device Profile ........... CiA DS-406 V4.0.2, Class 3
Data Transfer............ 100BASE-TX

| Cycle time................. up to $50 \mu$ s |  |
| :--- | :--- |
| Code ........................ | Binary, CW default, program- |
| mable |  |

## Mechanical

| Flange.................... Hollow bore (blind bore) | $1 \times 10^{-11}$ revs. at $20 \%$ rated shaft load |
| :---: | :---: |
| Flange Material ........ Aluminum | Environmental |
| Shaft Material ..........Stainless steel | Operating Temp ....... $-40^{\circ}$ to $85^{\circ} \mathrm{C}$ |
| Shaft Length ............ 17 mm | Storage Temp .......... $-40^{\circ}$ to $100^{\circ} \mathrm{C}$ |
| Insertion depth min............................... 10 mm max | Sealing. $\qquad$ IP65 tested per EN 60529 ESD $\qquad$ 8 kV tested per EN 61000-4-2 |
| Housing Cap $\qquad$ Steel case chrome-plated, magnetic shielding | EMC.................................. $2001000-6-2$; EN 61000-6-3 Vibration............... $200 \mathrm{~m} / \mathrm{s}^{2}(10 \mathrm{~Hz}$ up to 1000 Hz$)$ |
| Connection Cover .... Die cast aluminum, powder coated | ( 20.3 g [10Hz up to 1000 Hz$]$ ) tested per EN 60068-2-6 |
| Weight................... $14.4 \mathrm{oz} / 410 \mathrm{~g}$ approx | Shock..................... $5000 \mathrm{~m} / \mathrm{s}^{2}(6 \mathrm{~ms})$ |
| Shaft Rotation .......... Bi-directional | 509.8 g ( 6 ms ) |
| Shaft Load ............... 80 N (17.9 lb) | tested per EN 60068-2-27 |



Max Axial

Starting Torque ........ Approximately 1.6 Ncm (2.226 oz-in) at ambient temperature.

Bearings
Type.......................... 2 precision ball bearings
Nominal Service ....... $1 \times 10^{9}$ revs. at $100 \%$ rated
$1 \times 10^{10}$ revs. at $40 \%$ rated shaft load

## Absolute Encoders

## MODEL A58SE



FEATURES
Single/Multi-Turn Absolute Encoder (16 Bit ST / 43 Bit MT) EtherCAT with CoE, FoE, EoE
Maintenance-Free and Environmentally Friendly Magnetic Design
Energy Harvesting Magnetic Multi-Turn Technology
No Gears or Batteries
Electronic Cam Switches
Low TCO and easy provisioning with internal web server High Shaft Load
Color LEDs for operating condition, bus status, link activity Compact design with bus cover
58 mm (2.28") Diameter Package
COMMON APPLICATIONS
Robotics, Telescopes, Antennas, Medical Scanners, Wind Turbines, Elevators, Lifts, Motors, Automatic Guided Vehicles, Rotary and X/Y Positioning Tables

## EPC Absolute Encoder - now with EtherCAT connectivity

The Model A58SE is an EtherCAT-ready, multi-turn absolute encoder designed for harsh factory and plant environments. It is particularly suited to applications where Ethernet-based connectivity is required, and the encoder must retain position information after power-off events. Easily designed into a wide variety of system applications, the A58SE plugs directly into your network with minimal provisioning for rapid deployment, facilitating data exchange among myriad networked devices. The Model A58SE retains absolute position information even after a power loss, facilitating speedy system recovery at start-up without the need for system re-homing.

Ready for Industry 4.0 and for the Industrial Internet of Things (IIOT), data exchange between the Model A58SE and other applications has no influence on the control loop. The Model A58SE is non-reactive and can work independently from the PLC or master, transferring data through network gateways to other automation networks and sites, and up to the cloud for analysis.


## MODEL A58SE CLAMPING FLANGE (MH)



## MODEL A58SE SYNCHRO FLANGE (MK)



Primary dimensions are in mm , secondary dimensions SI units [inches] in brackets for reference only.
Please see the Model A58HE, page 11, for Pinout Diagram.

## MODEL A58SE SPECIFICATIONS

Electrical
Power Supply .......... 10 VDC up to 32 VDC
Current
Consumption. typ. 125 mA
Power
Consumption. $\qquad$ .typ. 3 W


Internal Cycle Time .. $50 \mu \mathrm{~s}$
lution
ccuracy
Single Turn .......... $\pm 0.0878^{\circ}$ ( $\leq 12 \mathrm{bit}$ )
ingle Turn, Repeat
chnology
Single Turn .......... Innovative Hall-sensor technology
Multi-Turn...........Patented energy-harvesting technology,
no battery and no gears

Interface

Protoco . EtherCAT

Data Transfer 100BASE-TX

Cyle up to $50 \mu \mathrm{~s}$


| Max Axial................ $120 \mathrm{~N}(26.9 \mathrm{lb})$ for $6 \mathrm{~mm}, 8$ |  |
| :---: | :---: |
| Shaft Load | mm and 10 mm shafts |
|  | 120 N (26.9 lb) for 3/8" shaft |
| Starting Torque ........Approximately 1 Ncm |  |
|  | (1.416 oz-in) at ambient temperature. |
| Max Shaft Speed...... 6000 RPM |  |
| Bearings |  |
|  |  |
| Nominal Service....... $1 \times 10^{9}$ revs. at $100 \%$ rated |  |
| Life ............ | shaft load <br> $1 \times 10^{10}$ revs. at $40 \%$ rated shaft <br> load <br> $1 \times 10^{11}$ revs. at $20 \%$ rated shaft load |
| Environmental |  |
| Operating Temp ....... $-40^{\circ}$ to $85^{\circ} \mathrm{C}$ |  |
| Storage Temp ........... $-40^{\circ}$ to $100^{\circ} \mathrm{C}$ |  |
| Sealing.....................IP65 (IP67 on 10 mm shaft)tested per EN 60529 |  |
| ESD ........................ 8 kV tested per EN 61000-4-2 |  |
| Burst...................... 2 kV tested per 61000-4-4 |  |
| EMC.......................EN 61000-6-2; EN 61000-6-3 |  |
| Vibration................. $200 \mathrm{~m} / \mathrm{s}^{2}(10 \mathrm{~Hz}$ up to 1000 Hz ) |  |
|  | ( 20.3 g [10Hz up to 1000 Hz$]$ ) |
|  | tested per EN 60068-2-6 |
| Shock. | $5000 \mathrm{~m} / \mathrm{s}^{2}$ (6 ms) |
|  | $\begin{aligned} & 509.8 \mathrm{~g}(6 \mathrm{~ms}) \\ & \text { tested per EN 60068-2-27 } \end{aligned}$ |
| Design.....................According DIN VDE 0160 |  |

## Absolute Encoders

MODEL A 36 HB


## $\varnothing 36$ mm

## FEATURES

Single Turn/Multi-Turn Absolute Encoder (16 Bit ST / 43 Bit MT) SSI or CANopen Communication
Maintenance-Free and Environmentally Friendly Magnetic Design Energy Harvesting Magnetic Multi-Turn Technology
No Gears or Batteries
Standard Size 36 mm (1.42") Hollow Bore (Blind) Encoder Flex Mount Eliminates Couplings and Is Ideal for Motors or Shafts Meets CE/EMC Standards for Immunity and Emissions

The Model A36HB Absolute Encoder offers a high performance solution for your absolute feedback needs. It provides maintenance-free feedback thanks to its innovative battery-free and gear-free multi-turn technology. This encoder is especially suited for applications where position information must be retained after loss of system power. Its rugged magnetic technology and high IP rating make the Model A36HB an excellent choice, even in tough industrial environments. Available with a $1 / 4$ " or 6 mm hollow bore (blind) and a wide selection of flexible mounting options, the Model A36HB is easily designed into a variety of applications.
COMMON APPLICATIONS
Robotics, Telescopes, Antennas, Medical Scanners, Wind Turbines, Elevators, Lifts, Motors, Automatic Guided Vehicles, Rotary and X/Y Positioning Tables

## MODEL A36HB ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


[^0]
## MODEL A36HB SPECIFICATIONS

Electrical
Input Voltage............ 10 to 32 VDC max SSI or CANopen 5 VDC SSI Only
Input Current ............ 50 mA typical for 10 to 32 VDC 80 mA typical for 5 VDC
Power Consumption... 0.5 W max
Resolution (Single) ... 01 to 16 bit
Resolution (Multi) .... 01 to 43 bit
Accuracy.................. $\pm 0.35^{\circ}$
Repeatability. $\pm 0.2^{\circ}$
CE/EMC ....................
Immunity tested per EN 61000-6-2:2006 Emissions tested per EN 61000-6-3:2011

## CANopen Interface

Protocol...................CANopen:
Communication profile CiA 301 Device profile for encoder CiA 406 V3.2 class C2
Node Number .......... 0 to 127 (default 127)
Baud Rate................. 10 Kbaud to 1 Mbaud with automatic bit rate detection
Note: The standard settings, as well as any customization in the software, can be changed via LSS (CiA 305) and the SDO protocol (e.g., PDOs, scaling, heartbeat, node-ID, baud rate, etc.).
Programmable CANopen Transmission Modes
Synchronous............. When a synchronization telegram (SYNC) is received from another bus node, PDOs are transmitted independently.
Asynchronous...........A PDO message is triggered by an internal event (e.g., change of measured value, internal timer, etc.).

## SSI Interface

Clock Input...............Via opto coupler
Clock Frequency....... 100 KHz to 500 KHz . Higher frequencies may be available. Contact Customer Service.
Data Output ............. RS485 / RS422 compatible
Output Code ............ Gray or binary
SSI Output................Angular position value
Parity Bit.................. Optional (even/odd)
Error Bit...................Optional
Turn On Time ........... < 1.5 sec
Pos. Counting Dir...... Connect DIR to GND for CW Connect DIR to VDC for CCW (when viewed from shaft end)
Set to Zero................ Yes, see Technical Bulletin TB-529: Understanding EPC's SSI Encoders
Protection $\qquad$ Galvanic Isolation

## Mechanical

Max Shaft Speed...... 12,000 RPM
Bore Depth.............. 17 mm (0.669")
User Shaft
Radial Runout. $\qquad$ $0.005^{\prime \prime}$ max
Starting Torque ........ $<0.45$ oz-in typica
Radial Shaft Load $\ldots . .17 \mathrm{lb}(80 \mathrm{~N})=$ bearing life of $1.4 \times 10^{8}$ revolutions
Axial Shaft Load ....... $11 \mathrm{lb}(50 \mathrm{~N})=$ bearing life of $1.4 \times 10^{8}$ revolutions
Housing .................... Ferrous chrome-plated magnetic screening
Weight. .5 oz typical

## Environmental

Operating Temp ........ $-40^{\circ}$ to $85^{\circ} \mathrm{C}$
Storage Temp ........... $-40^{\circ}$ to $100^{\circ} \mathrm{C}$
Humidity..................95\% RH non-condensing
Vibration................... 5 g @ 10 to 2000 Hz
Shock....................... 100 g @ 6 ms duration
Sealing....
IP67; shaft sealed to IP65

MODEL A36HB 1.812" (46 MM) SLOTTED FLEX MOUNT (SF)


## MODEL A36HB OPTIONAL FLEX MOUNTS

1.575 " (40 mm) SD

1.653" (42 mm) SW


Primary dimensions are in mm , secondary dimensions SI units [inches] in brackets for reference only.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
For CE (Conformity European) requirements, use M12 cordset with shield connected to M12 coupling nut. Trim back and insulate unused wires.

|  | SSI ENCODERS <br> Gland Cable $^{\dagger}$ <br> Wire Color | 8-pin <br> M-12 |
| :---: | :---: | :---: |
| Ground (GND) | White | 1 |
| +VDC | Brown | 2 |
| SSI CLK+ | Green | 3 |
| SSI CLK- | Yellow | 4 |
| SSI DATA+ | Gray | 5 |
| SSI DATA- | Pink | 6 |
| PRESET | Blue | 7 |
| DIR | Red | 8 |
| Shield | Side - Exit Housing <br> End - Exit N/C | Housing |

CANOPEN ENCODERS

| Function | Pin |
| :---: | :---: |
| +VDC | 2 |
| Ground (GND) | 3 |
| CAN ${ }_{\text {High }}$ | 4 |
| CAN ${ }_{\text {Low }}$ | 5 |
| CAN $\mathrm{GND}^{\text {/ Shield }}$ | 1 |

[^1]
## Absolute Encoders

## MODEL A 36 SB



CANopen


Ø36 mm
FEATURES
Single Turn/Multi-Turn Absolute Encoder (16 Bit ST / 43 Bit MT) SSI or CANopen Communication
Maintenance-Free and Environmentally Friendly Magnetic Design
Energy Harvesting Magnetic Multi-Turn Technology
No Gears or Batteries
Standard Size 36 mm Package (1.42")
Meets CE/EMC Standards for Immunity and Emissions
The Model A36SB Absolute Encoder offers a high performance solution for your absolute feedback needs. It provides maintenance-free feedback thanks to its innovative battery-free and gear-free multi-turn technology. This encoder is especially suited for applications where position information must be retained after loss of system power. Its rugged magnetic technology and high IP rating make the Model A36SB an excellent choice, even in tough industrial environments. Available with a $1 / 4^{\prime \prime}$ or 6 mm shaft and a servo mount, the Model A36SB is easily designed into a variety of applications.
COMMON APPLICATIONS
Robotics, Telescopes, Antennas, Medical Scanners, Wind Turbines, Elevators, Lifts, Motors, Automatic Guided Vehicles, Rotary and X/Y Positioning Tables

MODEL A36SB ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## NOTES:

Please refer to CANopen Interface Technical Reference Manual at encoder.com.
Please refer to Technical Bulletin TB-529: Understanding EPC's SSI Encoders at encoder.com.
Available with SSI only.
4 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
5 Available with CANopen only.

## MODEL A36SB SPECIFICATIONS

## Electrical



## CANopen Interface

Protocol.................... CANopen:
Communication profile CiA 301 Device profile for encoder CiA 406 V3.2 class C2

Node Number .......... 0 to 127 (default 127)
Baud Rate................. 10 Kbaud to 1 Mbaud with automatic bit rate detection
Note: The standard settings as well as any customization in the software can be changed via LSS (CiA 305) and the SDO protocol (e.g., PDOs, scaling, heartbeat, node-ID, baud rate, etc.)
Programmable CANopen Transmission Modes
Synchronous............. When a synchronization telegram (SYNC) is received from another bus node, PDOs are transmitted independently.
Asynchronous........... A PDO message is triggered by an internal event (e.g., change of measured value, internal timer, etc.)

## SSI Interface

Clock Input via opto coupler
Clock Frequency....... 100 KHz to 500 KHz . Higher frequencies may be available. Contact Customer Service.
Data Output ............. RS485 / RS422 compatible
Output Code ............ Gray or binary
SSI Output................Angular position value
Parity Bit. $\qquad$ Optional (even/odd)
Error Bit. $\qquad$ Optional
Turn On Time . $\qquad$ $<1.5 \mathrm{sec}$
Pos. Counting Dir...... Connect DIR to GND for CW Connect DIR to VDC for CCW (when viewed from shaft end) Yes, see Technical Bulletin TB-529; Understanding EPC's SSI Encoders
Protection Galvanic Isolation

## Mechanical

Max Shaft Speed ...... 12,000 RPM
Radial Shaft Load ..... $17 \mathrm{lb}(80 \mathrm{~N})=$ bearing life of $1.4 \times 10^{8}$ revolutions
Axial Shaft Load ....... $11 \mathrm{lb}(50 \mathrm{~N})=$ bearing life of $1.4 \times 10^{8}$ revolutions
Starting Torque ........ $<0.45$ oz-in typical
Housing ....................Ferrous chrome-plated magnetic screening
Weight...................... 5 oz typical

## Environmental

Operating Temp ....... $-40^{\circ}$ to $85^{\circ} \mathrm{C}$
Storage Temp ........... $-40^{\circ}$ to $100^{\circ} \mathrm{C}$
Humidity..................95\% RH non-condensing
Vibration................... 5 g @ 10 to 2000 Hz
Shock.. 100 g @ 6 ms duration
Sealing $\qquad$ IP67; shaft sealed to IP65

## MODEL A36SB SOLID SHAFT



Primary dimensions are in mm , secondary dimensions SI units [inches] in brackets for reference only.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
For CE (Conformity European) requirements, use M12 cordset with shield connected to M12 coupling nut. Trim back and insulate unused wires.

SSI ENCODERS

| Function | Gland Cable $^{\dagger}$ <br> Wire Color | 8-pin <br> M-12 |
| :--- | :---: | :---: |
| Ground (GND) | White | 1 |
| +VDC | Brown | 2 |
| SSI CLK + | Green | 3 |
| SSI CLK- | Yellow | 4 |
| SSI DATA+ | Gray | 5 |
| SSI DATA- | Pink | 6 |
| PRESET | Blue | 7 |
| DIR | Red | 8 |
| Shield | Side - Exit Housing <br> End - Exit $N / C$ | Housing |

${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.

CANOPEN ENCODERS

| Function | Pin |
| :--- | :---: |
| +VDC | 2 |
| Ground (GND)3 <br> CAN $_{\text {High }}$ | 4 |
| CAN $_{\text {Low }}$ | 5 |
| $\mathrm{CAN}_{\text {GND }} /$ Shield | 1 |

## Absolute Encoders

## MODEL A58HB



CANoper
058 mm

FEATURES
Single Turn/Multi-Turn Absolute Encoder (16 Bit ST / 43 Bit MT) SSI or CANopen Communication
Maintenance-Free and Environmentally Friendly All-Magnetic Design Energy Harvesting Magnetic Multi-Turn Technology No Gears or Batteries
58 mm (2.28") Diameter Hollow Bore (Blind) Encoder
Flex Mount Eliminates Couplings and Is Ideal for Motors or Shafts Meets CE/EMC Standards for Immunity and Emissions
The Model A58HB Absolute Encoder offers a high performance solution for your absolute feedback needs. It provides maintenance-free feedback thanks to its innovative battery-free and gear-free multi-turn technology. This encoder is especially suited for applications where position information must be retained after loss of system power. Its rugged magnetic technology and high IP rating make the Model A58HB an excellent choice, even in tough industrial environments. Available with bores up to $3 / 8$ " or 14 mm and two flexible mounting options, the Model A58HB is easily designed into a variety of applications.

## COMMON APPLICATIONS

Robotics, Telescopes, Antennas, Medical Scanners, Wind Turbines, Elevators, Lifts, Motors, Automatic Guided Vehicles, Rotary and X/Y Positioning Tables

```
MODEL A58HB ORDERING GUIDE
Blue type indicates price adder options
```



## NOTES:

```
1 Please refer to CANopen Interface Technical Reference Manual at encoder.com.
2 Please refer to Technical Bulletin TB-529: Understanding EPC's SSI Encoders at encoder.com.
3 Available with SSI only.
4 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
5 Available with CANopen only.
```


## MODEL A58HB SPECIFICATIONS

## Electrical

Input Voltage............ 10 to 32 VDC max
5 VDC SSI Only
Input Current ........... 50 mA typical for 10 to 32 VDC 80 mA typical for 5 VDC

Power: Consumption.. 0.5 W max
Resolution (Single) ... 01 to 16 bit
Resolution (Multi) .... 01 to 43 bit
Accuracy................... $< \pm 0.35^{\circ}$
Repeatability ............ $< \pm 0.2^{\circ}$
CE/EMC ....................Immunity tested per EN 61000-6-2:2006 Emissions tested per EN 61000-6-3:2011

## CANopen Interface

Protocol

## CANopen:

Communication profile CiA 301 Device profile for encoder CiA 406 V3.2 class C2
Node Number .......... 1 to 127 (default 127)
Baud Rate................. 10 Kbaud to 1 Mbaud with automatic bit rate detection
Note: The standard settings, as well as any customization in the software, can be changed via LSS (CiA 305) and the SDO protocol (e.g., PDOs, scaling, heartbeat, node-ID, baud rate, etc.).

Programmable CANopen Transmission Modes
Synchronous............. When a synchronization telegram (SYNC) is received from another bus node, PDOs are transmitted independently.
Asynchronous...........A PDO message is triggered by an internal event (e.g., change of measured value, internal timer, etc.).

## SSI Interface

Clock Input ................Via opto-coupler
Clock Frequency....... 100 kHz to 500 kHz . Higher frequencies may be available. Contact Customer Service.
Data Output ............. RS485 / RS422 compatible
Output Code ............ Gray or binary
SSI Output................Angular position value
Parity Bit. $\qquad$ Optional (even/odd)
Error Bit. Optional
Turn On Time ........... $<1.5 \mathrm{sec}$
Pos. Counting Dir...... Connect DIR to GND for CW Connect DIR to VDC for CCW (when viewed from shaft end)
Set to Zero................ Yes, see Technical Bulletin TB529: Understanding EPC's SSI Encoders
Protection ................ Galvanic Isolation with SSI option

## Mechanical

Max Shaft Speed...... 6000 RPM
Shaft Rotation .......... Bi-directional
Radial Run-out ......... 0.007" max
Axial Endplay............ $\pm 0.030^{\prime \prime}$ max
Radial Shaft Load ..... $17 \mathrm{lb}(80 \mathrm{~N})=$ bearing life of $1 \times 10^{9}$ revolutions
Axial Shaft Load ....... $11 \mathrm{lb}(50 \mathrm{~N})=$ bearing life of $1 \times 10^{9}$ revolutions
Starting Torque ........ 2.3 oz-in typical
Housing ...................All metal with protective finish
Bearings..................... 2 precision ball bearings
Weight...................... 7.5 oz typical

## Environmental

Operating Temp ....... $-40^{\circ}$ to $85^{\circ} \mathrm{C}$
Storage Temp ........... $-40^{\circ}$ to $100^{\circ} \mathrm{C}$
Vibration.................. 5.1 g ( 10 Hz up to 2000 Hz )
Shock.
100 g (6 ms)
Sealing
IP67, shaft sealed to IP65

MODEL A58HB 108 MM BC FLEX ARM (SQ)


MODEL A58HB 63 MM 2 PT. FLEX MOUNT (SR)


Primary dimensions are in mm , secondary dimensions SI units [inches] in brackets for reference only.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
For CE (Conformity European) requirements, use M12 cordset with shield connected to M12 coupling nut. Trim back and insulate unused wires. SSI ENCODERS

CANopen ENCODERS

| Function | 8 -Pin M12 |
| :--- | :---: |
| Ground (GND) | 1 |
| +VDC | 2 |
| SSI CLK+ | 3 |
| SSI CLK- | 4 |
| SSI DATA+ | 5 |
| SSI DATA- | 6 |
| PRESET | 7 |
| DIR | 8 |
| Shield | Housing |


| Function | 5-Pin M12 |
| :---: | :---: |
| +VDC | 2 |
| Ground (GND) | 3 |
| CAN ${ }_{\text {HIGH }}$ | 4 |
| CAN ${ }_{\text {Low }}$ | 5 |
| CAN ${ }_{\text {Gvo }} /$ Shield* | 1 |

*M12 connector is connected to encoder housing.

## Absolute Encoders

MODEL A 25 SB


CANoper SSI

## FEATURES

Single Turn/Multi-Turn Absolute Encoder (16 Bit ST / 43 Bit MT) SSI or CANopen Communication
Maintenance-Free and Environmentally Friendly Magnetic Design
Energy Harvesting Magnetic Multi-Turn Technology
No Gears or Batteries
IP67 Sealing Available
Servo and Flange Mounting
Standard Size 25 Package ( 2.5 " x 2.5")
Meets CE/EMC Standards for Immunity and Emissions
The Model A25SB Absolute Encoder offers a high performance solution for your absolute feedback needs. This encoder is especially suited for applications where position information must be retained after loss of system power. It provides maintenance-free feedback thanks to its innovative battery-free and gear-free multi-turn technology. This encoder is the perfect choice for harsh industrial applications thanks to its rugged magnetic technology, available IP67 rating, and proven double bearing design. Available with several shaft sizes and mounting styles, the Model A25SB is easily designed into OEM and aftermarket applications.

COMMON APPLICATIONS
Robotics, Telescopes, Antennas, Medical Scanners, Wind Turbines, Elevators, Lifts, Motors, Automatic Guided Vehicles, Rotary and X/Y Positioning Tables

MODEL A25SB ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## NOTES:

[^2]
## MODEL A25SB SPECIFICATIONS

Electrical
Input Voltage................ 10 to 32 VDC max SSI or CANopen
5 VDC SSI Only
Input Current ................ 50 mA typical for 10 to 32 VDC

80 mA typical for 5 VDC

MODEL A25SB 2.5" FLANGE MOUNT (MA)


MODEL A25SB 2.5" SERVO MOUNT (MC)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01$ " unless otherwise specified. Metric dimensions are given in brackets [mm].

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
For CE (Conformity European) requirements, use M12 cordset with shield connected to M12 coupling nut. Trim back and insulate unused wires.

SSI ENCODERS

| Function | Pin |
| :--- | :---: |
| Ground (GND) | 1 |
| +VDC | 2 |
| SSI CLK+ | 3 |
| SSI CLK- | 4 |
| SSI DATA+ | 5 |
| SSI DATA- | 6 |
| PRESET | 7 |
| DIR | 8 |
| Shield | Housing |

## CANOPEN ENCODERS

| Function | Pin |
| :--- | :---: |
| + VDC | 2 |
| Ground (GND)(GAN <br> High |  |
| CAN $_{\text {Low }}$ | 4 |
| $\mathrm{CAN}_{\text {GND }} /$ Shield | 5 |

## Absolute Encoders

MODEL 925


FEATURES
Standard Size 25 Package (2.5")
Resolutions up to 12-Bit (4096 Counts)
Incorporates Opto-ASIC Technology
Industrial Grade, Heavy Duty Housing Optional IP67 Seal
The Model 925 Single Turn Absolute Encoder is ideal for a wide variety of industrial applications that require an encoder with the capability of absolute positioning output. Its fully digital output and innovative use of Opto-ASIC technology make the Model 925 an excellent choice for all applications, especially ones with a high presence of noise. Available with either round servo or square flange mounting, and a variety of connector and cabling options, the Model 925 is easily designed into a variety of application requirements. The Model 925 , with its wide selection of shaft sizes supported by industrial grade, heavy duty bearings, and optional IP67 seal, is ideal for rough environments.
COMMON APPLICATIONS
Machine Tools, Robotics, Telescopes, Antennas, Rotary \& X-Y Positioning Tables, Medical Scanners

Ø2.5"
Not recommended for new applications.

MODEL 925 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


MODEL 925 RESOLUTION TABLE
Output Code Counts Per Resolution

| Gray Code | 0256 | 0512 | 1024 | 2048 | 4096 |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Natural Binary | 0250 | 0256 | 0360 | 0500 | 0512 | 0720 | 1000 |
|  | 1024 | 1440 | 2000 | 2048 | 2880 | 4000 | 4096 |
| Excess Gray | 0180 | 0250 | 0360 | 0500 | 0720 | 1000 | 1440 |
|  | 2000 | 2880 | 4000 |  |  |  |  |

## NOTES:

1 For additional connector styles, please contact Customer Service.
2 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
3 Only available with 8-bit resolution encoder. Not available with CE.
4 For non-standard cable lengths, add a forward slash (I) plus cable length expressed in feet. Example: G/6 = 6 feet of cable.
5 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com. Contact Customer Service for availability.

## MODEL 925 SPECIFICATIONS

## Electrical



## Control

Directional Control...Field selectable for increasing counts (CW or CCW)

## Mechanical

Max Shaft Speed...... 6000 RPM continuous
Radial Shaft Load ..... 35 lb max
Axial Shaft Load ....... 40 lb max
Starting Torque ........ 1.0 oz-in typical for no seal 2.0 oz-in typical with IP64 seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typcial with IP67 shaft seal

Housing Aluminum
Weight. . 22 oz typical

## Environmental

Storage Temp ............ $-20^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity................... $98 \%$ RH non-condensing
Vibration................... 10 g @ 58 to 500 Hz
Shock....................... 20 g @ 11 ms duration
Sealing.....................IP50 standard; IP64, IP66 or IP67 optional

## MODEL 925 2.5" FLANGE MOUNT (F)



MODEL 925 2.5" SERVO MOUNT (S)


All dimensions are in inches with a tolerance of $\pm 0.005$ " or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable $^{\dagger}$ <br> Wire Color | 19-pin Bayonet <br> KPT02E14-19P | 16-pin M23 |
| :---: | :---: | :---: | :---: | :---: |$\quad$ 10-pin MS*

*Only available with 8 -bit resolution encoder. Not available with CE.
**Where fitted.
${ }^{+}$Direction control Standard is CW increasing when viewed from the shaft end. Direction pin is pulled high to 5 V internally. Direction pin must be pulled low (GND, Common) to reverse count direction. Applied voltage to direction pin should not exceed 5 V .
†Standard cable is 24 AWG conductors with foil and braid shield.

## Absolute Encoders

## MODEL 960



FEATURES

## Low-Profile - 1.55"

## Thru-Bore or Hollow Bore Styles Industrial Grade, Heavy Duty Housing State-of-the-Art Opto-ASIC Circuitry

The single turn Model 960 Absolute Series Encoder provides a unique solution to a wide variety of industrial applications requiring absolute position information. By providing a low profile package of just 1.55", as well as a variety of hollow and thru-bore sizes and an easy to use flexible mounting system, the Model 960 goes where traditional absolute encoders do not fit. In addition, its innovative Opto-ASIC circuitry, coupled with its digital output, make it an excellent choice in those applications plagued by an unusually high level of electrical noise. The Model 960 can easily be mounted directly on a motor shaft, bringing the advantage of absolute positioning in an all metal housing, while eliminating the fixtures, couplers and adapters required by other absolute encoder designs.
COMMON APPLICATIONS
Machine Tools, Robotics, Telescopes, Antennas, Rotary \& X-Y Positioning Tables, Medical Scanners

Ø2.0"
Not recommended for new applications.

MODEL 960 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


[^3]
## MODEL 960 SPECIFICATIONS

## Electrical

Input Voltage............ 4.75 to 26 VDC max
Regulation ................ 100 mV peak-to-peak, max ripple at 0 to 10 kHz
Input Current ........... 100 mA max with no external load
Output Format .........Absolute - Parallel Outputs
Output Type ............. Open Collector - 20 mA max per channel Push-Pull-20mA max per channel
Code. $\qquad$ Gray Code, Excess Gray Code
Max Frequency ........ 25.6 kHz (LSB)
Rise Time.. . Less than 1 microsecond
Resolution Up to 11 bit
Accuracy $\pm 1 / 2$ LSB

## Control

Directional Control...Field selectable for increasing counts (CW or CCW). Standard configuration user selects the applicable MSB wire for direction of count. Direction control option allows user to select count direction by applying 0 VDC to an encoder input. See Wiring Table.

## Mechanical

Max Shaft Speed...... 6000 RPM continuous
Bore Size................... $0.250^{\prime \prime}, 0.3125^{\prime \prime}, 0.375^{\prime \prime}, 6 \mathrm{~mm}$, $8 \mathrm{~mm}, 10 \mathrm{~mm}$
Bore Tolerance .........- 0.0000 " / +0.0006
User Shaft Tolerances
Radial Runout .......0.007"
Axial Endplay......... $\pm 0.030^{\prime \prime}$
Starting Torque ........ 0.3 oz-in typical for thru-bore 0.14 oz-in typical for hollow bore

Electrical Conn ......... Gland with 18 " cable (braid shield, 30 AWG conductors)
Housing ...................Aluminum with non-corrosive finish
Mounting .................Slotted Flex Mount standard, Flex Arm optiona
Weight.
7 oz typical

## Environmental

Operating Temp ....... $0^{\circ}$ to $70^{\circ} \mathrm{C}$
Storage Temp ........... $-20^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity.................. $98 \% \mathrm{RH}$ non-condensing
Vibration.................... 10 g @ 58 to 500 Hz
Shock....................... 20 g @ 11 ms duration
Sealing IP50

## MODEL 960 SLOTTED FLEX MOUNT (SF)



## MODEL 960 WITH FLEX ARM (FA)

CABLE LENGTH 18" STANDARD


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.


## TRU-FLEXIBILITY

The Tru-Trac ${ }^{\text {TM }}$ Family of Linear Solution Encoders

Companies spend hours designing measuring wheel and bracket assemblies, to attach to an encoder, to measure position or velocity. That design time costs money. What's more, adjusting the pressure of the measuring wheel once it's been installed is often a major challenge - costing yet more time and money. Thanks to EPC's Tru-Trac ${ }^{\text {TM }}$ Linear Measurement Solution Encoders, you now have a ready-made solution.

Easy to use and very compact, the Tru-Trac ${ }^{\text {TM }}$ encoders are fully adjustable, integrated encoders with spring-loaded measuring wheel assemblies. Monitoring speed, velocity, or position has never been easier or more cost effective. Designed for use in almost any position and orientation, installation possibilities are endless. The threaded shaft on the pivot axis makes these units reversible, allowing measuring from either side of the assembly.

A variety of available measuring wheels, together with the flexibility of the adjustable spring loaded torsion arm, prevents slippage over many different surfaces or textures (for more on measuring wheel options, see page 35). Have an application with a unique surface or measurements? No problem. Order your Tru-Trac ${ }^{\text {TM }}$ without a wheel, and you can install your own measuring wheel. Simple torsion control provides easy wheel pressure adjustment in seconds, allowing various thicknesses of materials to be measured.

Common applications include: Web Tension Control, Paper Monitoring, Glue Dispensing, Linear Material Monitoring, Conveyor Systems, Printing, Labeling, and Document Handling.

The Tru-Trac ${ }^{\text {TM }}$ encoders are perfect for linear applications and can be mounted above or below the moving object. The spring-loaded torsion arm allows the tension on the wheel to be adjusted, so that measurement can be obtained over a variety of different surfaces and textures. Perfect for cut-to-length, packaging, conveyors, mail sorting and gantry applications.

The Tru-Trac ${ }^{\text {TM }}$ encoders can be mounted in any orientation to monitor velocity. This is perfect for many rotational applications such as web tension control drums, rotary tables, printing, spooling, etc.

The Tru-Trac ${ }^{\text {TM }}$ by Encoder Products Company is a versatile solution for tracking velocity, position, or distance over a wide variety of surfaces in almost any application.


For specification assistance call
Customer Service at 1-800-366-5412.

## TRU-TRAC ${ }^{\text {M }}$ ENCODERS ON THE JOB

## Model TR1 Tru-Trac ${ }^{\text {TM }}$ Applications



For linear applications, the TruTrac ${ }^{\text {™ }}$ can be mounted above or below the moving object, and the tension on the wheel can be adjusted for a wide range of applications, such as packaging, conveyors, mail sorting, cut-to-length, labeling, gantries, etc.


For rotational applications, the Tru-Trac ${ }^{\text {TM }}$ can be mounted in any orientation to monitor the position or velocity of many types of rotating equipment, such as web tension control drums, rotary tables, printing, spooling, etc.


## Model TR2 Tru-Trac ${ }^{\text {TM }}$ Applications

For reciprocating linear motion applications, the TR2 provides accurate reliable feedback. The adjustable spring inside the torsion arm allows the TR2 to be oriented in any direction, while still ensuring the pinion gear is properly engaged with the rack. The precision pinion gear, when paired with EPC's stainless steel or flexible rack system provides feedback with virtually no backlash.


The TR2 is ideal for gauging and backstop applications typically found on a variety of metal working equipment.


The Model TR2 is applied to provide vertical speed and position feedback for a fork lift tower.

## Linear Measurement Solutions

MODEL TR1 TRU-TRAC ${ }^{\top}{ }^{\text {M }}$


FEATURES
Encoder and Measuring Wheel Solution Integrated Into One Compact Unit Spring Loaded Torsion Arm Makes Wheel Pressure Adjustments a Snap Easily Installed in a Vertical, Horizontal or Upside Down Orientation Operates Over a Variety of Surfaces at Speeds up to 3000 Feet per Minute Integrated Module Simplifies Your System Design, Reducing Cost

With operating speeds up to 3000 feet per minute and a wide variety of configuration options, the TR1 Tru-Trac ${ }^{\text {TM }}$ is the versatile solution for tracking velocity, position, or distance over a wide variety of surfaces in almost any application. An integrated encoder and spring-loaded measuring wheel assembly available in one unit, the TR1 is both easy-to-use and compact. Plus, the TR1 housing is a durable, conductive composite material that will eliminate static build up. Its spring-loaded torsion arm offers adjustable torsion load, allowing the TR1 to be mounted in almost any orientation - even upside-down. And the threaded shaft on the pivot axis is easily reversible in the field, providing mounting access from either side. The TR1 is your solution for a compact, linear encoder.
COMMON APPLICATIONS
Web Tension Control, Paper Monitoring, Glue Dispensing, Linear Material Monitoring, Conveyor Systems, Printing, Labeling, Document Handling

MODEL TR1 TRU-TRAC ${ }^{\text {TM }}$ ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## WHEEL TYPE \& CIRCUMFERENCE

U1 Urethane 6 " cir
U2 Urethane 200 mm cir
K1 Knurled 6 " cir
K2 Knurled 200 mm cir
A1 Anodized Knurled 6.0" cir
A2 Anodized Knurled 200 mm cir
19 No Wheel - 1/4" shaft
20 No Wheel - 6 mm shaft

MODEL TR1 TRU-TRAC ${ }^{\text {TM }}$ CPR OPTIONS

| 0001 thru $0189^{*}$ | 0198 | 0200 | 0250 | 0256 | 0300 | 0315 | 0360 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0400 | 0500 | 0512 | 0580 | 0600 | 0750 | 0800 | 1000 | 1024 |
| 1200 | 1250 | 1500 | 1800 | 2000 | 2048 | 2500 | 2540 | 3000 |
| 3600 | 4000 | 4096 | 5000 | 6000 | 7200 | 8192 | 10,000 |  |
| $*$ |  |  |  |  |  |  |  |  |
| *Contact Customer Service for Availability |  |  |  |  |  |  |  |  |

New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available values. Special disk resolutions are available upon request and may be subject to a one-time NRE fee.

## A Channel A

Channel A Leads B
Q Quadrature A \& B
R Quadrature A \& B with Index
Channel B Leads A ${ }^{3}$
K Reverse Quadrature A \& B
D Reverse Quadrature A \& B with Index

CONNECTOR TYPE ${ }^{6}$
F00 18" $\mathrm{Cable}^{7}$ (Std)
F01 12" Cable
F02 24" Cable
F03 36" Cable
M00 2M Cable ${ }^{7}$
J00 18" Cable with 5 -pin M124
K00 18" Cable with 8-pin M12

## NOTES:

1 See mechanical drawing. Shaft is reversible in the field.
2 Contact Customer Service for non-standard index gating or phase relationship options.
3 Reverse Quadrature not available with Pull-Up Resistor Output Type.
4 Line Driver output not available with 5 -pin M12 connector. Additional cable lengths available. Please consult Customer Service.
5 With Input Voltage above 16 VDC , operating temperature is limited to $85^{\circ} \mathrm{C}$.
6 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
7 For non-standard English cable lengths enter ' $F$ ' plus cable length expressed in feet. Example: F06 $=6$ feet of cable. Frequency above 300 kHz standard cable lengths only.
8 For non-standard metric cable lengths enter 'M' plus cable length expressed in meters. Example: M06 $=6$ meters of cable.
9 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL TR1 TRU-TRAC ${ }^{\text {TM }}$ SPECIFICATIONS

Electrical
Input Voltage............ 4.75 to 28 VDC max for temperatures up to $85^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $85^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$
Input Current ........... 100 mA max ( 65 mA typical) with no output load
Output Format......... Incremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the shaft side. See Waveform Diagram.
Output Types............. Open Collector - 20 mA max per channel Push-Pull - 20 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index.. Once per revolution. 0001 to 0189 CPR: Ungated 0190 to 10,000 CPR: Gated to output A See Waveform Diagram.
Max. Frequency .......Standard Frequency Response is 200 kHz for CPR 1 to 2540 500 kHz for CPR 2541 to 5000 1 MHz for CPR 5001 to 10,000 Extended Frequency Response (optional) is 300 kHz for CPR 2000, 2048, 2500, and 2540
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-6-2; BS EN50081-2; BS EN61000-4-2; BS EN61000-4-3; BS EN61000-4-6; BS EN500811

Quadrature...................... $67.5^{\circ}$ electrical or better is typical,
Edge Separation $\quad 54^{\circ}$ electrical minimum at temperatures $>99^{\circ} \mathrm{C}$
Waveform Symmetry... $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical (single channel encoder)
Accuracy.................. Within $0.017^{\circ}$ mechanical or 1 arc-minute from true position (for CPR > 189)
Mechanical
Max Shaft Speed...... 6000 RPM. Higher speeds may be achievable;- contact Customer Service.
Shaft Material .........Stainless Steel
Shaft Tolerance ........ $+0.0000 /-0.0004^{\prime \prime}[+0.000 /-0.010 \mathrm{~mm}]$
Radial Shaft Load ..... 5 lb max. Rated load of 2 to 3 lb for bearing life of $1.2 \times 10^{10}$ revolutions
Axial Shaft Load ........ 5 lb max. Rated load of 2 to 3 lb for bearing life of $1.2 \times 10^{10}$ revolutions
Starting Torque ........IP50 0.05 oz-in
IP65 0.4 oz-in IP66 0.8 oz-in
Housing ................... Stainless steel fibers in a high temperature nylon composite
Wheel Width............ $0.25^{\prime \prime}$
Weight. 5 oz typical

## Environmental

Storage Temp ........... $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity...................98\% RH non-condensing
Vibration.................. 10 g @ 58 to 500 Hz
Shock....................... 80 g @ 11 ms duration
Sealing $\qquad$ IP50 standard; IP65 or IP66 available

MODEL TR1 TRU-TRAC ${ }^{\text {TM }}$


## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable $^{\dagger}$ <br> Wire Color | 5-pin M12** | 8-pin M12** |
| :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 |
| +VDC | White | 1 | 2 |
| A | Brown | 4 | 1 |
| A' $^{\text {B }}$ | Yellow | -- | 3 |
| B | Red | 2 | 4 |
| B' | Green | -- | 5 |
| Z | Orange | 5 | 6 |
| Z' | Blue | -- | 8 |
| Shield | Bare | -- | -- |

*CE Option: Cable shield (bare wire) is connected to internal case.
†Standard cable is 24 AWG conductors with foil and braid shield.
**CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

## WAVEFORM DIAGRAM

Incremental Signals


CLOCKWISE ROTATION AS VIEWED FROM THE SHAFT SIDE
NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES
ALLDEGRE REFRENCES ARE ELECLRCALDEGREES.
WAEFRM SHWN WTH OPIIONAL COMPLEMENTARY SIGNALS
A, $\bar{B}, \bar{Z}$ FOR HV OUTPUT ONLY.

## Linear Measurement Solutions

## MODEL TR2 TRU-TRAC ${ }^{\text {TM }}$ with rack and pinion gearing

## FEATURES



Encoder with Rack-and-Pinion Gear Integrated into One Compact Unit Easily Installed in a Vertical, Horizontal or Upside Down Orientation Operates at Speeds up to 400 Feet per Minute Spring Loaded Torsion Arm Eliminates Gear Backlash Integrated Module Simplifies Your System Design

The TR2 Tru-Trac™ is a versatile solution for tracking velocity, position, or distance in almost any application and features an integrated encoder with a rack-and-pinion gear assembly. Using the rack-and-pinion gear system, encoder readings can be obtained with repeatable positioning, providing excellent accuracy. Racks can be ordered in varying lengths, and with the accessory spacer block, multiple lengths of rack can be joined for easy installation. The spring loaded torsion arm provides easily adjustable torsion load, giving the TR2 all the flexibility and maneuverability of the original TR1 Tru-Trac ${ }^{\text {TM }}$. It can be installed in a horizontal, vertical, or upside down position. The threaded shaft on the TR2's pivot axis is field reversible, providing mounting access from either side. And the durable conductive composite housing material reduces static build up.

## COMMON APPLICATIONS

X-Y Tables, Gantry Systems, Packaging Machinery, Cut-to-Length, Printing, Labeling, Document Handling, Machine Shop Equipment

MODEL TR2 TRU-TRAC ${ }^{\text {TM }}$ ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


MODEL TR2 TRU-TRAC ${ }^{\text {™ }}$ CPR OPTIONS

| 0001 | thru 0189* | 0198 | 0200 | 0250 | 0256 | 0300 | 0315 | 0360 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0400 | 0500 | 0512 | 0580 | 0600 | 0750 | 0800 | 1000 | 1024 |
| 1200 | 1250 | 1500 | 1800 | 2000 | 2048 | 2500 | 2540 | 3000 |
| 3600 | 4000 | 4096 | 5000 | 6000 | 7200 | 8192 | 10,000 |  |

New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available values. Special disk resolutions are available upon request and may be subject to a one time NRE fee.

NOTES:
1 See mechanical drawing. Shaft is reversible in the field.
Contact Customer Service for non-standard index gating or phase relationship options.
3 Reverse Quadrature not available with Pull-Up Resistor Output Type.
4 Line Driver output not available with 5-pin M12 connector. Additional cable lengths available. Please consult Customer Service.
5 With Input Voltage above 16 VDC , operating temperature is limited to $85^{\circ} \mathrm{C}$
6 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com..
7 For non-standard English cable lengths enter ' $F$ ' plus cable length expressed in feet. Example: F06 $=6$ feet of cable. Frequency above 300 kHz standard cable lengths only.
8 For non-standard metric cable lengths enter ' $M$ ' plus cable length expressed in meters. Example: M06 = 6 meters of cable.
9 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL TR2 TRU-TRAC ${ }^{\text {TM }}$ SPECIFICATIONS

Electrical
Input Voltage............ 4.75 to 28 VDC max for temperatures up to $85^{\circ} \mathrm{C} 4.75$ to 24 VDC for temperatures between $85^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$
Input Current ........... $100 \mathrm{~mA} \max$ ( 65 mA typical) with no output load
Output Format.....
ncremental - Two square waves in quadrature with channel $A$ leading $B$ for clockwise shaft rotation, as viewed from the wheel side. See Waveform Diagram.
Output Types............ Open Collector- 20 mA max per channel Push-Pull - 20 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index........................ Once per revolution. 0190 to 10,000 CPR: Gated to output A. 0001 to 0189 CPR: Ungated See Waveform Diagram.
Max. Frequency .......Standard Frequency Response is 200 kHz for CPR 1 to 2540 500 kHz for CPR 2541 to 5000 1 MHz for CPR 5001 to 10,000 Extended Frequency Response (optional) is 300 kHz for CPR 2000, 2048, 2500, \& 2540
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-6-2; BS EN50081-2; BS EN61000-4-2; BS EN61000-4-3; BS EN61000-4-6, BS EN500811

Quadrature............... $67.5^{\circ}$ electrical or better is typical, Edge Separation $\quad 54^{\circ}$ electrical minimum at temperatures $>99^{\circ} \mathrm{C}$
Waveform Symmetry... $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical (single channel encoder) Accuracy.................. Within $0.017^{\circ}$ mechanical or 1 arc-minute from true position (for CPR>189)

## Mechanical

Radial Shaft Load .... 5 lb max. Rated load of 2 to 3 lb for bearing life of $1.2 \times 10^{10}$ revolutions
Axial Shaft Load ....... 5 lb max. Rated load of 2 to 3 lb for bearing life of $1.2 \times 10^{10}$ revolutions
Starting Torque .........IP50 0.05 oz-in IP65 0.4 oz-in IP66 0.8 oz-in
Housing ................... Stainless steel fibers in a high temperature nylon composite
Weight 5 oz typical

## Environmental

Storage Temp ........... $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity...................98\% RH non-condensing
Vibration.................. 10 g @ 58 to 500 Hz
Shock....................... 80 g @ 11 ms duration
Sealing. IP50 standard; IP65 or IP66 available
Mechanical - Stainless Steel Rack
Max Linear Speed .... 400 Feet Per Minute. Speeds over 200 FPM require lubricant, such as $\mathrm{MoS}_{2}$ paste, to reduce gearing wear. Higher speeds may be achievable, contact Customer Service.
Rack Material .......... 303 Stainless Steel
Gearing Tolerance....AGMA 10, 20 degree pressure angle teeth
$\qquad$ $\pm 0.0005$ inch/inch max accumulated error
Repeatability. $\qquad$ $\pm 0.0001$ inch

## Mechanical - Flexible Rack

Max Linear Speed .... 200 Feet Per Minute
Rack Material ..........Acetal
Gearing Geometry ... $20^{\circ}$ pressure angle teeth
Accuracy.................. $\pm 0.002$ inch/inch max accumulated error Repeatability.

MODEL TR2 TRU-TRAC™


WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable $\dagger$ <br> Wire Color | 5-pin <br> M12** | 8-pin <br> M12** |
| :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 |
| +VDC | White | 1 | 2 |
| A | Brown | 4 | 1 |
| A' $_{\text {B }}$ | Yellow | -- | 3 |
| B' | Red | 2 | 4 |
| Z | Green | -- | 5 |
| Z' | Orange | 5 | 6 |
| Shield | Blue | -- | 8 |

*CE Option: Cable shield (bare wire) is connected to internal case.
†Standard cable is 24 AWG conductors with foil and braid shield.
**CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

WAVEFORM DIAGRAM
Incremental Signals


CLOCKWISE ROTATION AS VIEWED FROM THE SHAAFT SIDE
Note: All degree references are electrical degrees.
ALLDEGREE REFERENCESARE ELECTRICALDEGRES.
WAEFFRM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS
A, B. Z̄ FOR HV OUTPUT ONLY. +0.005 " or $+0.01 "$ unless otherwise specified. $\bar{M}$ Metric dimensions are given in brackets [ mm ].

## RESOLUTIONS - English Units

| Inches per <br> Pulse | Pulses per <br> Inch | Disc Cycles per <br> Revolution |
| :---: | :---: | :--- |
| 0.01 | 100 | 400 |
| 0.005 | 200 | 800 |
| 0.004 | 250 | 1000 |
| 0.002 | 500 | 2000 |
| 0.001 | 1000 | $2000^{*}$ |
| 0.0005 | 2000 | $2000^{* *}$ |
| 0.0004 | 2500 | $2500^{* *}$ |
| 0.0002 | 5000 | $2500^{* *+}$ |
| 0.0001 | 10,000 | $2500^{* *++}$ |

*Requires $2 x$ external quadrature counting.
${ }^{* *}$ Requires $4 x$ external quadrature counting.
${ }^{+}$Requires $2 x$ Interpolation.
++Requires 4x Interpolation.
RESOLUTIONS - Metric Units

| mm <br> per Pulse | Pulses <br> per mm | Disc Cycles per <br> Revolution |
| :---: | :---: | :---: |
| 0.04 | 25 | 2540 |
| 0.02 | 50 | $2540^{*}$ |
| 0.01 | 100 | $2540^{* *}$ |

*Requires $2 x$ external quadrature counting.
**Requires $4 x$ external quadrature counting.
PINION GEAR FOR FLEXIBLE RACK

0.125 FACE WIDTH PINION FOR FLEXIBLE RACK


PINION GEAR FOR STAINLESS STEEL RACK



## Linear Measurement Solutions

## MODEL TR3 HEAVY DUTY TRU-TRACTM



FEATURES


#### Abstract

Integrated Heavy Duty Encoder and Measuring Wheel In One Spring Loaded Torsion Arm for Quick Wheel Pressure Adjustments Easily Installed in a Vertical, Horizontal or Upside-Down Orientation Operates Over a Variety of Surfaces at Speeds up to 3000 Feet per Minute Integrated Module Simplifies System Design, Reducing Cost


The TR3 Heavy Duty Tru-Trac™ is an integrated, heavy duty encoder and spring loaded measuring wheel assembly all in one unit. Available in both single or optional dual-wheel format, the TR3 Heavy Duty Tru-Trac ${ }^{\text {TM }}$ is a versatile solution for tracking velocity, position or distance over a wide variety of surfaces in many industrial applications. Its spring loaded torsion arm provides a simple-to-adjust torsion load, allowing the TR3 Heavy Duty Tru-Trac ${ }^{\text {TM }}$ to be mounted in any orientation, even upside-down. The TR3 Heavy Duty Tru-Trac™ housing is an all metal work horse, specifically designed to take on your toughest application environments at operating speeds up to 3000 feet per minute. Just one look and it's easy to see the TR3 Heavy Duty Tru-Trac ${ }^{\text {TM }}$ is the ideal solution for countless applications.

COMMON APPLICATIONS
Lumber, Corrugated, Converting, Metal Roll Forming, Paper Monitoring, Glue Dispensing, Linear Material Monitoring, Conveyor Systems, Printing, Labeling, Mining, Construction

MODEL TR3 HEAVY DUTY TRU-TRAC ${ }^{\text {TM }}$ ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## WHEEL TYPE \& CIRCUMFERENCE

U3 Urethane 12" cir
U5 Urethane 300 mm cir
K3 Knurled 12" cir
K5 Knurled 300 mm ci
25 No Wheel 3/8" (0.375") Shaft
A3 Hard Anodized Knurled 12" cir
A5 Hard Anodized Knurled 1/3 M cir

NUMBER OF CHANNELS ${ }^{1}$
A Channel A
Channel A Leads B
Q Quadrature A \& B
R Quadrature A \& B with Index
Channel B Leads A ${ }^{2}$
K Reverse Quadrature A \& B
D Reverse Quadrature A \& B with Index

MODEL TR3 TRU-TRAC ${ }^{\text {TM }}$ CPR OPTIONS

| 0001 thru 0189* | 0198 | 0200 | 0250 | 0256 | 0300 | 0315 | 0360 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0400 | 0500 | 0512 | 0580 | 0600 | 0750 | 0800 | 1000 | 1024 |
| 1200 | 1250 | 1500 | 1800 | 2000 | 2048 | 2500 | 2540 | 3000 |
| 3600 | 4000 | 4096 | 5000 | 6000 | 7200 | 8192 | 10,000 |  |

*Contact Customer Service For Availability
New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available values. Special disk resolutions are available upon request and may be subject to a one-time NRE fee.

Optional Features

| Leave Blank for Standard Options |  |
| ---: | ---: | ---: |
| $-20^{\circ}$ to $85^{\circ} \mathrm{C} \mathrm{Std} \quad$ IP50 Std | None Std |

CONNECTOR ORIENTATION (See Drawing)
Standard Rear Exit
L1 $60^{\circ}$ From Standard
L2 $120^{\circ}$ From Standard L3 $180^{\circ}$ From Standard L4 $240^{\circ}$ From Standard L5 $300^{\circ}$ From Standard

OPERATING TEMPERATURE $-20^{\circ}$ to $85^{\circ} \mathrm{C}(\mathrm{Std})$
T1 $-40^{\circ}$ to $85^{\circ} \mathrm{C}^{9}$ T2 $-20^{\circ}$ to $100^{\circ} \mathrm{C}$

CERTIFICATION None (Std) CE CE Marked 10

CONNECTOR TYPE ${ }^{5}$
F00 18" Cable ${ }^{6}$ (Std)
F01 12" Cable
F02 24" Cable
F03 36" Cable
m002M Cable ${ }^{7}$
SMW 6 -pin MS ${ }^{8}$
SMY 7 -pin MS ${ }^{8}$
SMX 10-pin MS8
SMJ 5 -pin M123,8
SMK 8 -pin M12 ${ }^{8}$

MAXIMUM
FREQUENCY
Standard
F3 Extended
See Specifications

NOTES:
1 Contact Customer Service for non-standard index gating or phase relationship options.
2 Reverse Quadrature not available with Pull-Up Resistor Output Type.
3 Line Driver not available with 5-pin M12 connector
4 With Input Voltage above 16 VDC , operating temperature is limited to $85^{\circ} \mathrm{C}$
5 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
6 For non-standard English cable lengths enter 'F' plus cable length expressed in feet. Example: F06 = 6 feet of cable. Frequency above 300 kHz standard cable lengths only.
7 For non-standard metric cable lengths enter ' M ' plus cable length expressed in meters. Example: M06 = 6 meters of cable.
8 Body Mount connector options only available with connector orientation L1 thru L5
9 Rated to $-40^{\circ} \mathrm{C}$ during encoder operation. Storage and startup below $-25^{\circ} \mathrm{C}$ not recommended.
10 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com

## MODEL TR3 TRU-TRAC ${ }^{\text {TM }}$ SPECIFICATIONS

## Electrical

Input Voltage............ 4.75 to 28 VDC max for temperatures up to $85^{\circ} \mathrm{C}$ 4.75 to 24 VDC for temperatures between $85^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$
Input Current $\qquad$ 100 mA max ( 65 mA typical) with no output load Output Format .......... ncremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the shaft side. (For units with dual wheels, orient the encoder so that the label is readable). See Waveform Diagram.
Output Types............ Open Collector - 20 mA max per channe Push-Pull- 20 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index Once per revolution. 0190 to 10,000 CPR: Gated to output A 0001 to 0189 CPR: Ungated See Waveform Diagram.
Max. Frequency .......Standard Frequency Response is 200 kHz for CPR 1 to 2540 500 kHz for CPR 2541 to 5000 1 MHz for CPR 5001 to 10,000 Extended Frequency Response (optional) is 300 kHz for CPR 2000, 2048, 2500, and 2540
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-6-2; BS EN50081-2; BS EN61000-4-2; BS EN61000-4-3; BS EN61000-4-6, BS EN500811

Quadrature............... $67.5^{\circ}$ electrical or better is typical,
Edge Separation $\quad 54^{\circ}$ electrical minimum at temperatures $>99^{\circ} \mathrm{C}$
Waveform Symmetry . $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical (single channel encoder)
Accuracy................... Within $0.017^{\circ}$ mechanical or 1 arc-minute from true position (for CPR>189).

Mechanical
Max Linear Speed .... 3000 FPM not to exceed a maximum shaft speed of 6000 RPM.
Shaft Material ......... Stainless Steel
Radial Shaft Load ..... Up to 10 lb max. Controlled by spring torsion feature
Starting Torque ........ 1.0 oz-in typical with IP50 seal 2.5 oz-in typical with IP66 seal and single wheel 4.0 oz-in typical with IP66 seal and dual wheel 7.0 oz-in typical with IP67 seal and single wheel 14.0 oz-in typical with IP67 seal and dual wheel

Housing .. $\qquad$ Powder coated aluminum
Wheel Width. 3/4" standard
Weight 2.5 lb typical with single wheel 3.0 lb typical with dual wheel

## Environmental

Storage Temp ... $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity. $\qquad$ 98\% RH non-condensing
Vibration. $.10 \mathrm{~g} @ 58$ to 500 Hz
Shock. $.80 \mathrm{~g} @ 11 \mathrm{~ms}$ duration
Sealing IP50 standard; IP66 or IP67 optiona

## MODEL TR3 HEAVY DUTY TRU-TRAC ${ }^{\text {TM }}$



## MODEL TR3 MOUNTING BRACKET



Optional Accessory Mounting Bracket (stock \#176389-01) for TR3 Heavy Duty Tru-Trac ${ }^{\text {TM }}$ can be ordered separately.

## Linear Measurement Solutions

## MODEL TR3 HEAVY DUTY TRU-TRAC ${ }^{\text {TM }}$

## MODEL TR3 DOUBLE WHEEL PIVOT



Optional Accessory Double Pivot Kit (stock \#176391-01) for TR3 Heavy Duty Tru-Trac ${ }^{\text {TM }}$ can be ordered separately.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | 5-pin M12** | 8-pin M12** | 10-pin MS | $\begin{aligned} & \text { 7-pin MS } \\ & H V, O D \end{aligned}$ | 7-pin MS <br> PU, PP, OC | 6-pin MS <br> PU, PP, OC |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A, F |
| +VDC | White | 1 | 2 | D | D | D | B |
| A | Brown | 4 | 1 | A | A | A | D |
| $A^{\prime}$ | Yellow | -- | 3 | H | C | -- | -- |
| B | Red | 2 | 4 | B | B | B | E |
| B' | Green | -- | 5 | 1 | E | -- | -- |
| Z | Orange | 5 | 6 | C | -- | C | C |
| Z' | Blue | -- | 8 | J | -- | -- | -- |
| Case | -- | -- | -- | G | G | G | -- |
| Shield | Bare* | -- | -- | -- | -- | -- | -- |

[^4]MODEL TR3 CONNECTOR ORIENTATION


WAVEFORM DIAGRAM
Incremental Signals


CLOCKWISE ROTATION AS VIEWED FROM THE SHAFT SIDE
(FOR UNITS WITH DUAL WHEELS, ORIENT THE ENCODER SO THAT THE LABEL IS READABLE).

NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z}$ FOR HV OUTPUT ONLY.

## MEASURING WHEELS

## Increasing the Versatility of Encoders

While using an encoder with a measuring wheel has many advantages, it can also be challenging to assemble and put into use. EPC has decades of experience helping customers solve their linear measurement needs with our Tru-Trac ${ }^{\text {TM }}$ series, a family of integrated units that bring together a rotary encoder, precision measuring wheel, and spring-loaded torsion arm into a single, easy-to-use package. See pages 126-128 for measuring wheels and other measuring wheel options.


A selection of measuring wheels available from EPC, including two different urethane, hard anodized knurled aluminum, and rubber insert

## Size/Speed

The wheel's circumference should give the best accuracy possible within the mounting constraints. EPC offers many different measuring wheel sizes, including, but not limited to: $6^{\prime \prime}$, 12", $1 / 3$ meter, 200 mm . Also, make sure the encoder can handle both the mechanical and electrical speed of your application. For Instance, EPC Models TR1 and TR3 can handle applications with linear speeds up to 3000 feet per minute and electrical frequencies up to 1 MHz .

## Selecting the Proper Measuring Wheel Surface

When selecting a measuring wheel surface, consider these general guidelines:

- Wheel material will expand and contract with temperature variations.
- Wheels wear down with usage.
- A harder wheel surface generally provides greater durability, but less traction.
- Dual wheels result in twice the traction, reducing the potential for wheel slippage (dual wheels only available with Model TR3).

Encoder Products Company offers numerous measuring wheels in different sizes, all made of high grade aluminum alloy. There are four different contact surfaces available.

## Rubber Insert

Rubber provides better traction in most applications, but also may wear faster than other materials, depending on the application. The nature of replaceable O-rings allows easy completion of regularly scheduled maintenance. Rubber insert wheels are good for materials such as (but not limited to): paper, film, foil, hard plastic, and other smooth materials.

## Polyurethane

This smooth, versatile material comes in different durometer ratings (that is, degrees of hardness). Polyurethane is good for materials such as (but not limited to): metal pipe, sandpaper, matting, cardboard/packaging, belting, insulated wire, metal, etc.

## Knurled Aluminum

Knurled aluminum offers good traction, but should not be used with delicate materials. It is a good choice for materials such as (but not limited to): metal pipe, sandpaper, matting, cardboard/packaging, belting, insulated wire, metal, coarse fabric, cloth tape, rubber, rough wood, carpet, foam, insulation, or other rugged materials that won't damage easily from constant contact with the wheel.

## Hard Anodized Knurled Aluminum

Anodizing hardens the aluminum and prevents corrosion, so these wheels are good for harsh environments where there may be washdown or exposure to corrosive elements. These wheels are also not meant for delicate materials, and are excellent for materials such as (but not limited to): coarse fabric, wood (i.e., lumber cut-to-length), or other durable materials.

For long service life, choose a measuring wheel encoder that will withstand the environment in which it will be exposed. All measuring wheels, like EPC's Accu-Coder ${ }^{\text {TM }}$ brand encoders, are manufactured to EPC's exacting standards, and feature EPC's 3-year standard product warranty, ensuring years of trouble free use.

## Linear Measurement Solutions

## MODEL LCE



## FEATURES

## Low Cost Linear Solution

## Resolutions from 2-500 Cycles per Inch <br> IP65 Sealing Available <br> Cable Measurement 0-50 inches

The Linear Cable Encoder (LCE) provides a low cost alternative for obtaining accurate linear measurements. As opposed to typical rotary shaft style encoders, the LCE has a retractable stainless steel cable, allowing for numerous measuring configurations. You can place the LCE away from harsh environmental conditions, while still providing precise measurements, giving the LCE an outstanding advantage over shaft-style encoders. Installation is easy with a variety of cable exit directions, and perfect parallel alignment is no longer necessary. The heart of the LCE is the popular Cube Accu-Coder ${ }^{\text {TM }}$, the original cube style encoder. The LCE provides a reliable digital pulse train in either single channel or quadrature format, with resolutions down to 0.002 " per cycle. The small overall size, a variety of resolutions, and many different connector types, makes the versatility of the LCE unbeatable.
COMMON APPLICATIONS
Robotics, Extrusion Presses, Valve Positioning, Textile Machinery, Control Gate Positioning

MODEL LCE ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


Model LCE features.a retractable stainless steel cable at a standard length of 50 ". Longer lengths may be available, please contact Customer Services.

NOTES:
1 Line Driver not available with 5-pin M12 connector.
2 For mating connectors, cables, and cordsets see Accessories at encoder. com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
3 For non-standard cable lengths, add a forward slash (/) plus cable length expressed in feet. Example: $G / 6=6$ feet of cable.

## MODEL LCE SPECIFICATIONS



## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | $\begin{aligned} & \text { 5-pin } \\ & \text { M12 } \end{aligned}$ | $\begin{aligned} & \text { 8-pin } \\ & \text { M12 } \end{aligned}$ | $\begin{gathered} \text { 10-pin } \\ \text { MS } \end{gathered}$ | 7-pin MS <br> HV | 7-pin MS <br> O, S, PP | $\begin{aligned} & \text { 6-pin MS } \\ & \text { HV, No } \\ & \text { Index } \end{aligned}$ | 6-pin MS <br> O, S, PP | Term. <br> Block HV, No Index | Term Block <br> O, S, PP |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A | A, F | 1 | 1,6 |
| +VDC | Red | 1 | 2 | D | D | D | B | B | 2 | 2 |
| A | White | 4 | 1 | A | A | A | C | D | 3 | 4 |
| $\mathrm{A}^{\prime}$ | Brown | -- | 3 | H | C | -- | D | -- | 4 | -- |
| B | Blue | 2 | 4 | B | B | B | E | E | 5 | 5 |
| $B^{\prime}$ | Violet | -- | 5 | 1 | E | -- | F | -- | 6 | -- |
| Z | Orange | 5 | 6 | C | -- | C | -- | C | -- | 3 |
| Z' | Yellow | -- | 8 | J | -- | -- | -- | -- | -- | -- |
| Case | Green | -- | -- | G | G | G | -- | -- | -- | -- |
| Shield | Bare | -- | -- | -- | -- | -- | -- | -- | -- | -- |

## *E-Cube only.

tStandard cable is 24 AWG conductors with foil and braid shield.

MODEL LCE STANDARD HOUSING (LCEO1)


MODEL LCE IP65 INDUSTRIAL HOUSING (LCEO2)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## CABLE EXIT OPTIONS



Optional Mounting Plate
Attaches to Standard or Industrial LCE in three different orientations. Order Accessory Item \#176064-01.


## WAVEFORM DIAGRAMS



## SPECIFYING OUTPUT TYPES FOR INCREMENTAL ENCODERS

Choosing the correct number of channels and the correct output type for an encoder can be the determining factor in whether or not a feedback system functions properly. There are four common output types to select from, and most of EPC's encoder models can be ordered with any of these four types. There are also some speciality output types, available on select models.

## Determining What Output Type Your Application Needs

The receiving device determines the correct configuration of the encoder's outputs. One type of output is not necessarily better than another; it depends on the individual application and the controller being used with the encoder. For instance, if the controller calls for "compatible NPN" output circuitry, a simple open-collector output type is the right choice. The circuit will be current sinking, and the load on the controller side will pull up the encoder output to the desired voltage. In another example, if the controller is set up to receive differential signals, for better noise immunity (especially at higher voltages), use an encoder with an HV differential line driver output. Reference your controller's manual for specific information on its requirements, and of course, EPC Technical Services is here to help if you still have questions.

## Common Output Types

1. "OC" NPN Open-Collector is a current sinking output and is useful for doing what is called level shifting. This is when the encoder is powered with on e voltage level, and the output is pulled up externally to a different voltage level. For example, the encoder can be powered with 5 volts DC and the output can be pulled up to a 24 volt DC level.
2. "PU" Pull-Up is the same as the open-collector, but, as the name implies, it also contains an internal pull-up resistor to the positive supply voltage supplied to the encoder. (Not to be confused with a "sourcing" type output.) The amount of current that can be sourced with the output transistor in the off state is limited by the supply voltage and the value of the internal pull-up resistor. Common values for the internal pull-up resistor used in encoder is between 1,500 and $2,200 \Omega$. This type of output is used when the counter, or PLC does not have built-in provisions to pull up the input circuitry.


NPN Electrical Hook-Up


Open Collector
OC Output Circuit
3. "PP" Push-Pull is sometimes referred to as a "totem-pole" type of output circuit. For our discussion here, we will treat them equally. This is a combination of sinking and sourcing outputs. When the output is in the logic high state, current is sourced to the load. When the output is in the logic low state, current is sinked from the load. It suffers from lack of noise immunity, however, because when the output is high (sourcing) whatever noise, ripple, etc., that is on the DC supply lines to the encoder is directly dumped into the input circuitry of the counter, PLC, or whatever the load. When the output is sinking (low state), the noise immunity is the same as if the open-collector was used.

4. "HV" Differential Line Driver provides differential outputs, or complementary signals for noise immunity. It meets RS-422 standards when operated at 5 volts DC . This type of output should be selected if the load device is set up to receive differential signals. The output lines are electrically balanced and if the proper balance between them is not maintained, ringing and spurious oscillations can occur on the lines. At higher frequencies it may cause false counting in the load device. Noise immunity is obtained by the nature of what is called "common mode" rejection. (For more information, see white paper WP-2005: Noise Suppression of Differential Signals.) Remember that for each output channel the encoder has, one additional wire in the cable must be used for the complement signal. Also, for applications where there will be long lengths of interconnecting cable, which can degrade the signal, HV is the best option to ensure a clear signal.


PP Electrical Hook-up


## Specialty Output Types

The following output types are available on select EPC encoder models:

"OD" Open Collector/Differential: an open collector output with complimentary channels similar to a line driver.
"LO" Line Driver on ABZ and Open Collector on UVW: Complimentary line drivers outputs for the clock channels A, B, and Z. Open collector outputs for the commutation channels $\mathrm{U}, \mathrm{V}, \mathrm{W}$.
"H5" Line Driver at +5 VDC: Regardless of the input voltage, the outputs will be limited to +5 VDC complimentary line driver. Input voltage is limited to $8-28$ VDC for Models $702,725,758,802$, and 755.
"P5" Push-Pull at +5 VDC: Regardless of the input voltage, the outputs will be limited to +5 VDC Push-Pull.

## Other Common Industry Terminology

Output types are also referred to in the industry as "HTL", "TTL", "PNP", and many others. Sometimes the output IC (7272, 4469, $8830,7406,3904,26$ LS31, etc.) is all that is used to define the output type.

If the output type you need is not discussed here or is otherwise unclear, or if you have any additional questions, please contact EPC Technical Service at 800-366-5412 or email sales@encoder.com.

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL $15 \mathrm{~T} / \mathrm{H}$



FEATURES
High Performance Economical Encoder
Low Profile - 1.0" ( 25.4 mm ) Height and 1.5" ( 38 mm ) Diameter Thru-Bore or Hollow Bore (Blind) with sizes up to 0.375" ( 10 mm ) Simple, Innovative Flex Mounting System (Global Mounting Standards) Up to 12 Pole Commutation Optional for Brushless Motor Control
The Model 15T or 15H Accu-Coder™ offers a high performance feedback solution in a low profile package. Unlike modular or kit encoders, the Model 15 utilizes an integral bearing set and an innovative flexible mounting system, which are much more tolerant to axial misalignment or radial shaft runout. The slotted flex mounts provide 20 to 30 degrees of rotational adjustment for commutation or index pulse timing. Installation is quick and easy; for brushless servo motor applications, three $120^{\circ}$ electrical phase tracks can provide up to 12 pole commutation feedback. The optional $100^{\circ} \mathrm{C}$ and $120^{\circ} \mathrm{C}$ temperature options allow servo motors to operate at higher power outputs and duty cycles. With its stable and reliable operation, the Model 15 is an excellent replacement modular encoder when you need a high-performance solution.

## COMMON APPLICATIONS

Servo Motor Control, Robotics, Specialty Assembly Machines, Digital Plotters, High Power Motors

MODEL 15T/H ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 15T/H SPECIFICATIONS



MODEL 15T/H 1.811" (46 MM ) SLOTTED FLEX MOUNT (SF)


MODEL 15T/H 1.811" (46 MM) TWO HOLE FLEX MOUNT (SA)


MODEL 15T/H SMALL DIAMETER SLOTTED FLEX MOUNTS
1.142 " $(29 \mathrm{~mm}) \mathrm{SB}^{*}$


ROTATIONAL ADJUSTMENT
1.2795 " $(32.5 \mathrm{~mm})$ SC* $^{*}$

$1.575^{\prime \prime}(40 \mathrm{~mm})$ SD* $^{*}$


ROTATIONAL ADJUSTMENT
*Order Appropriate No Charge Mounting and Installation Kit for SB, SC, or SD Option. Each kit contains 10 screws for mounting 5 encoders.

176150-01 Installation Kit, 4-40 Buttonhead Screws with 0.062 " Shortened Hex Wrench
176149-01 Installation Kit, M2.5 Buttonhead Screws with 1.5 mm Shortened Hex Wrench

Encoder length and diameter are the same as SF and SA mounts detailed above. All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$


SB Slotted Flex Mount

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL 15 T/H

WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Flying Leads Cable ${ }^{\dagger}$ Wire Color | 5-pin <br> M12** | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | 15-pin <br> Header |
| :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | 1 |
| +VDC | White | 1 | 2 | 2 |
| A | Brown | 4 | 1 | 4 |
| $\mathrm{A}^{\prime}$ | Yellow | -- | 3 | 3 |
| B | Red | 2 | 4 | 6 |
| B' | Green | -- | 5 | 5 |
| Z | Orange | 5 | 6 | 7 |
| Z' | Blue | -- | 8 | 8 |
| U | Violet | -- | -- | 10 |
| U' | Gray | -- | -- | 9 |
| V | Pink | -- | -- | 14 |
| V' | Tan | -- | -- | 13 |
| W | Red/Green | -- | -- | 12 |
| W' | Red/Yellow | -- | -- | 11 |
| Shield | Bare* | -- | -- | -- |


*CE Option: Cable shield (bare wire) is connected to internal case.
${ }^{\dagger}$ Standard cable for non-commutated models is 24 AWG For commutated units, conductors are 28 AWG.
**CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

## WAVEFORM DIAGRAMS



## EPC HAS THE SOLUTION

Replacing an Encoder Has
Never Been Easier

## Cross References

EPC also has a complete line of motor friendly encoders that easily fit motor sizes from small to large.
The Model 15 can be crossed to many encoders. This is not a comprehensive list. Please contact Customer Service for additional offerings and to ensure complete and accurate cross-referencing. For help selecting the correct motor kit for your motor, please contact our encoder experts today.

Visit encoder.com for a product datasheet and to view our full line of replacement encoders. Or contact EPC with your cross-reference request. You'll get a prompt response from an encoder expert that will help you serve your customers better, while reducing your overhead.

## MODEL 15S

The Model 15 S offers a wide selection of mounting face options. A variety of bosses and bolt hole patterns provide cross-reference adaptability like no other encoder.


## MODEL 15T

The Model 15T (thru-bore) and 15H (hollow bore, or "blind") are the superior choice for your servo or stepper motor applications. Endurance under high-temperature conditions, high resolution performance, commutation, and flexible mounting options make the 15T/H an unbeatable encoder.


SA-1.811" Bolt Circle Mounting DRC 73 DRC T23 DRC 731 Sumtak LBKLLDA


SB - 1.142" ( 29 mm ) Bolt Circle Mounting Dynapar F14


SC - 1.2795" (32.5mm Bolt Circle Mounting Dynapar M14 Renco RCM15


SD - 1.575" (40 mm Bolt Circle Mounting Sumtak IRH3 Sumtak IRT3


SF - 1.811" Bolt Circle Mounting
DRC H15 Renco RCM15 Dynapar M15 Sumtak LBK/LDA Dynapar M21 Turck 8.3720 Dynapar F14

## Incremental Thru-Bore \& Motor Mount Encoders

MODEL 755 A


Ø1.5"

## FEATURES

## Miniature Size (1.5" Diameter)

Up to 30,000 Cycles Per Revolution
Flex Mounting \& Large Hollow Bore Option (up to 0.750") High Temperature Option
The Model 755A Size 15 Accu-Coder ${ }^{T M}$ is ideal for applications requiring a small, high-precision, high-performance encoder. Approximately 1.5" in diameter and 1.5 " long, it will fit where many encoders cannot. All metal construction and shielded ball bearings provide years of trouble-free use. A variety of blind hollow bore sizes are available with large bores allowing for shafts up to $0.750^{\prime \prime}$ or 14 mm . Attaching directly to a motor is quick and simple with the innovative flex mount, first developed by EPC. This industry-standard mount eliminates couplings and increases reliability, while reducing overall length and cost. Where critical alignment is required, a Slotted Flex (SF) is available. A perfect replacement encoder where high reliability is required.
COMMON APPLICATIONS
Robotics, Assembly Machines, Motor-Mounted Feedback, Phototypesetters, Printers \& Digital Plotters, Elevator Controls, Medical Diagnostic Equipment

MODEL 755A ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


MODEL 755A CPR OPTIONS

| 0001* | 0002* | 0004* | 0005* | 0006* | 0007* | 0008* | 0010* | 0011* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0012* | 0014* | 0020 | 0021* | 0024* | 0025* | 0028* | 0030* | 0032* |
| 0033* | 0034* | 0035* | 0038* | 0040* | 0042* | 0045* | 0050* | 0060 |
| 0064* | 0100 | 0120 | 0125 | 0128* | 0144* | 0150* | 0160* | 0192* |
| 0200 | 0240* | 0250 | 0254* | 0256* | 0300 | 0333* | 0360 | 0400 |
| 0500 | 0512 | 0600 | 0625* | 0635 | 0665* | 0720 | 0768* | 0800 |
| 0889 | 1000 | 1024 | 1200 | 1201*a | 1203*a | 1204*a | $1250{ }^{\text {a }}$ | $1270^{\text {a }}$ |
| 1440 | 1500 | 1800 | 2000 | 2048 | $2400^{\text {a }}$ | 2500 | $2540^{\text {a }}$ | $2880^{\text {a }}$ |
| $3000{ }^{\text {a }}$ | $3600^{\text {a }}$ | $4000^{\text {a }}$ | 4096 ${ }^{\text {a }}$ | $5000^{\text {a }}$ | $6000^{\text {a }}$ | $7200^{\text {a }}$ | $7500{ }^{\text {a }}$ | $9000^{\text {a }}$ |
| 10,000 ${ }^{\text {a }}$ | 10,240 ${ }^{\text {a }}$ | 12,000 ${ }^{\text {a }}$ | 12,500 ${ }^{\text {a }}$ | $14,400^{\text {a }}$ | 15,000 ${ }^{\text {a }}$ | 18,000 ${ }^{\text {a }}$ | 20,000 ${ }^{\text {a }}$ |  |
| 20,480 ${ }^{\text {a }}$ | 25,000 ${ }^{\text {a }}$ | 30,000 ${ }^{\text {a }}$ |  |  |  |  |  |  |

*Contact Customer Service for High Temperature Option.
aHigh Temperature Option (H) limited to $85^{\circ} \mathrm{C}$ maximum for these CPR options.
New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available CPR values. Special disk resolutions are available upon request. A one-time NRE fee may apply.

NOTES:
1 Contact Customer Service for additional options.
Low temperature option not available with resolutions of 3000 CPR or higher. $0^{\circ}$ to $85^{\circ} \mathrm{C}$ for certain resolutions, see CPR Options. Contact Customer Service for index gating options. 24 VDC max for high temperature option. Line Driver outputs not available with 5 -pin M12 connector. Standard temperature, 60 to 3000 CPR only. Not available with 2540 CPR. H 5 and P 5 outputs are not available with CE option.
9 Standard cable lengths only. For details, please refer to Technical Bulletin TB116: Noise and Signal Distortion Considerations encoder.com.
10 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
11 Additional cable lengths available. Please consult Customer Service. For non-standard cable lengths, add a forward slash (/) plus cable length expressed in feet. Example: $S / 6=6$ feet of cable.
12 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL 755A SPECIFICATIONS



## MODEL 755A FLEX MOUNT (S)



OPTIONAL SLOTTED FLEX MOUNT (SF)


## MODEL 755A LARGE BORE FLEX MOUNT (S)



All dimensions are in inches with a tolerance of +0.005 " or +0.01 " unless otherwise specified. Metric dimensions are given in brackets [mm].

## WAVEFORM DIAGRAMS

Line Driver and Push-Pull


CLOCKWISE ROTATION AS VIEWED FROM THE MOUNTING FACE NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z}$ FOR HV OUTPUT ONLY.

Open Collector and Pull-Up


CLOCKWISE ROTATION AS VIEWED FROM THE MOUNTING FACE NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. INDEX IS POSITIVE GOING

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Flying <br> Leads Cable ${ }^{\dagger}$ Wire Color | Terminal Block | 8-pin Molex | $\begin{aligned} & \text { 5-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 7 | 2 | 3 | 7 |
| +VDC | White | 8 | 1 | 1 | 2 |
| A | Brown | 1 | 8 | 4 | 1 |
| $A^{\prime}$ | Yellow | 2 | 7 | -- | 3 |
| B | Red | 3 | 4 | 2 | 4 |
| B' | Green | 4 | 3 | -- | 5 |
| Z | Orange | 6 | 6 | 5 | 6 |
| Z' | Blue | 5 | 5 | -- | 8 |
| Shield | Bare* | -- | -- | -- | -- |

*CE Option: Cable shield (bare wire) is connected to internal case
${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.
${ }^{* *}$ CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL 260



FEATURES

## Low Profile 1.19"

Up to 12 Pole Commutation
Available in Thru-Bore and Hollow Bore (Blind) Simple, Innovative Flexible Mounting System Incorporates Opto-ASIC Technology CE Marking Available

With a bore up to 0.625 " and a low profile, the Model 260 Accu-Coder ${ }^{\text {TM }}$ is the perfect solution for many machine and motor applications. Available in both hollow bore and a complete thru-bore, the Model 260 uses EPC's innovative anti-backlash mounting system, allowing simple, reliable, and precise encoder attachment. Unlike traditional kit or modular encoder designs, its integral bearing set provides stable and consistent operation without concerns for axial or radial shaft runout. For brushless servo motor applications, the Model 260 can be specified with three $120^{\circ}$ electrical phase tracks to provide up to 12 pole commutation feedback. The optional extended temperature capability allows servo motors to operate at higher power outputs and duty cycles. And of course, the Model 260 uses EPC's pioneering Opto-ASIC design, so you'll always get a clean, reliable signal.

## COMMON APPLICATIONS

Brushless Servo Motor Commutation, Robotics, Motor-Mounted Feedback, Assembly Machines, Digital Plotters, High Power Motors

MODEL 260 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## NOTES:

1 Not available in all configurations. Contact Customer Service for availability.
2 Contact Customer Service for additional options not shown.
MODEL 260 CPR OPTIONS

| 0001 thru 0189* |  | 0200 | 0250 | 0254 | 0256 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0300 | 0360 | 0400* | 0500 | 0512 | 0600 |
| 0720 | 0800 | 0840 | 1000 | 1024 | 1200 |
| 1250 | 1270 | 1500 | 1800 | 2000 | 2048 |
| 2500 | 2540 | 3000 | 3600 | 4000 | 4096 |
| 5000 | 6000 | 7200 | 8192 | 10,000 |  |
| *Contact Customer Service for availability. |  |  |  |  |  |

Contact Customer Service for other disk resolutions. Not all disk resolutions available with every commutation option.

## MODEL 260 SPECIFICATIONS

## Electrica

Input Voltage............ 4.75 to 28 VDC for temperatures up to $70^{\circ} \mathrm{C}$
5 to 16 VDC for $0^{\circ}$ to $100^{\circ} \mathrm{C}$ operating temperature
5 VDC for $0^{\circ}$ to $120^{\circ} \mathrm{C}$ operating temperature
Input Current ........... $130 \mathrm{~mA} \max (<100 \mathrm{~mA}$ typical) with
no output load
Output Format......... Incremental - Two square waves in quadrature with channel $A$ leading $B$ for clockwise shaft rotation, as viewed from the mounting face. See Waveform Diagrams.
Output Types............ Open Collector - 20 mA max per channel
Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index........................ Once per revolution gated to channel A. See Waveform Diagrams.

Max. Frequency .......Standard Frequency Response is 200 kHz for CPR 1 to 2540 500 kHz for CPR 2541 to 5000 1 MHz for CPR 5001 to 10,000 Extended Frequency Response (optional) is 300 kHz for CPR 2000, 2048, 2500, and 2540
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-6-2; BS EN50081-2; BS EN61000-4-2; BS EN61000-4-3; BS EN61000-4-6, BS EN55011
$\qquad$ $67.5^{\circ}$ electrical or better is typical
Edge Separation....... $54^{\circ}$ electrical minimum at temperatures $>99^{\circ} \mathrm{C}$
Accuracy.................. Within $0.01^{\circ}$ mechanical from one cycle to any other cycle, or 0.6 arc minutes.
Commutation............Up to 12 pole. Contact Customer Service for availability.
Comm. Accuracy ...... $1^{\circ}$ mechanical.
Mechanical
Max Shaft Speed...... 7500 RPM. Higher shaft speeds may be achievable, contact Customer Service. Note: For extreme temperature operation, de-rate temperature by $5^{\circ} \mathrm{C}$ for every 1000 RPM above 3000 RPM.
Bore Tolerance .........-0.0000" / +0.0006"
User Shaft Tolerances
Radial Runout ....... 0.007" max
Axial Endplay. $\pm 0.030$ " max
Starting Torque ........IP50 Thru-Bore: 0.50 oz -in IP50 Hollow Bore: 0.30 oz-in P64 Thru-Bore: 2.50 oz-in IP64 Hollow Bore: 2.0 oz-in Note: Add 3.0 oz-in for $-40^{\circ} \mathrm{C}$ operation
Moment of Inertia ... $3.9 \times 10^{-4} \mathrm{Oz}-\mathrm{in}-\mathrm{sec}^{2}$
Housing .....................Non-corrosive material
Weight..................... 3.5 oz typical
Environmental
Storage Temp.......... $-40^{\circ}$ to $100^{\circ} \mathrm{C}$
Humidity................... $98 \% \mathrm{RH}$ non-condensing
Vibration................. 10 g @ 58 to 500 Hz
Shock................. $50 \mathrm{~g} @ 11$ ms duration
Sealing..................IP50; IP64 available

## MODEL 260 WITH FRONT SHAFT CLAMP (T)

WITH 1.811" (46 MM) BC SLOTTED FLEX (SF)


## MODEL 260 REAR CLAMP (R)

WITH 1.811" (46 MM) BC SLOTTED FLEX (SF)

three point flex mount (Xf, nf)


[^5]
## Incremental Thru-Bore \& Motor Mount Encoders

MODEL 260
1.575" (40 MM) BC FLEX MOUNT (SD)

1.06" TO 1.81" FLEX ARM (FA)

2.36" (60 MM) BC FLEX MOUNT (SL)

1.50" TO 3.13" FLEX ARM (FB)


## MODEL 260 CONNECTOR OPTIONS

BODY MOUNT 10-PIN BAYONET (SMH)


BODY MOUNT M12 (SMJ, SMK)


All dimensions are in inches with a tolerance of $\pm 0.005$ " or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## WAVEFORM DIAGRAMS



NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES.WAVE FORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}$, Z FOR HV AND OD OUTPUTS ONLY

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Flying Leads Cable ${ }^{\dagger}$ <br> Wire Colors | $\begin{aligned} & \text { 5-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | 10-pin Bayonet ${ }^{+}$ |
| :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F |
| +VDC | White | 1 | 2 | D |
| A | Brown | 4 | 1 | A |
| $A^{\prime}$ | Yellow | -- | 3 | H |
| B | Red | 2 | 4 | B |
| B' | Green | -- | 5 | J |
| Z | Orange | 5 | 6 | C |
| Z' | Blue | -- | 8 | K |
| U | Violet | -- | -- | -- |
| U' | Gray | -- | -- | -- |
| V | Pink | -- | -- | -- |
| $V^{\prime}$ | Tan | -- | -- | -- |
| W | Red/Green | -- | -- | -- |
| W' | Red/Yellow | -- | -- | -- |
| Shield | Bare* | -- | -- | -- |

${ }^{\dagger}$ Standard cable for non-commutated models is 24 AWG For commutated units, conductors are 28 AWG. *CE Option: Cable shield (bare wire) is connected to internal case.
**CE Option: Use cable cordset with shield connected to M12 connector coupling nut.
${ }^{+}$CE Option: Pin G is connected to internal case.

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL $225 \mathrm{~A} / \mathrm{Q}$



## FEATURES

Single Channel \& Quadrature Models
Easy to Mount Economical Thru-Bore Design
Metal Construction
Bore Sizes to $0.875^{\prime \prime}$ or 22 mm
Controlling motor speed is essential for many production assembly machines or robotic equipment. For tachometer feedback, or motor speed control applications, the Model 225 Accu-Coder ${ }^{\text {TM }}$ is the ideal encoder choice. The Model 225 Accu-Coder™ is a thru-bore encoder available in both single channel (225A) and quadrature (225Q) models that provides a cost-effective solution for simple measurement. Features including an all metal housing, a variety of connector options, and easy installation due to the thru-bore design, make the Model 225 AccuCoder ${ }^{\text {TM }}$ ideal for many motion control and manufacturing applications.

COMMON APPLICATIONS
Brushless Servo Motor Commutation, Robotics, Motor-Mounted Feedback, Assembly Machines, Digital Plotters, High Power Motors

MODEL 225A/Q ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


MODEL 225A/Q CPR OPTIONS
225A
1-600 CPR, all resolutions

| 225Q |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 001 | 002 | 003 | 004 | 005 | 006 | 010 | 011 |
| 015 | 016 | 020 | 022 | 025 | 030 | 032 | 040 |
| 048 | 050 | 060 | 062 | 080 | 083 | 090 | 099 |
| 100 |  |  |  |  |  |  |  |
| Contact Customer Service for other disk resolutions. |  |  |  |  |  |  |  |

NOTES:
1 Shaft speed limited to 400 RPM.
2 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
3 For Non-Standard Cable Lengths add a forward slash (/) plus cable length expressed in feet. Example: $\mathrm{S} / 12=12$ feet of cable.

## MODEL 225A SPECIFICATIONS

 SINGLE CHANNEL
## Electrical

Input Voltage $\qquad$ 4.75 to 24 VDC

Input Current $\qquad$ 32 mA max with Pull-Up option Input Ripple $\qquad$ 100 mV peak-to-peak at 0 to 100 kHz
Output Format Square wave $50 \%$ duty cycle
Output Types. Open Collector - 100 mA max
Pull-Up - Open Collector with 1.5 K ohm internal resistor, 20 mA max per channel
Max Frequency ........ 0 to 6 kHz
Rise Time..
Less than 1 microsecond
Cycles per Rev. 1 to 600

## Mechanical

Max. Shaft Speed..... 4000 RPM
Bore Tolerance ......... Bore H7 fit for g6 shaft Class LC5 per ANSI B-4.I Standard
Running Torque........ 10 oz-in typical
Housing ................... Black non-corrosive finish
Bearings. $\qquad$ Precision ABEC ball bearings
Weight $\qquad$ 8 oz typical

## Environmental

Storage Temp ...........-25 to $85^{\circ} \mathrm{C}$
Humidity..................95\% RH non-condensing
Vibration.................... 3 g @ 5 to 1000 Hz
Shock. $\qquad$ 20 g @ 10 ms duration

## MODEL 225Q SPECIFICATIONS QUADRATURE

## Electrical

Input Voltage............ 4.75 to 24 VDC
Input Current 64 mA max with Pull-Up option
Input Ripple $\qquad$ 100 mV peak-to-peak at 0 to 100 kHz
Output Format.........Square wave $50 \%$ duty cycle in quadrature
$\qquad$ Open Collector -100 mA max per channel Pull-Up - Open Collector with 1.5 K ohm resistor, 20 mA max per channel
Max Frequency ........ 0 to 6 kHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Rise Time................... Less than 1 microsecond
Cycles Per Rev 1 to 100

Mechanical
Max. Shaft Speed... 4000 RPM
Bore Tolerance ......... Bore H7 fit for g6 shaft Class LC5 per ANSI B-4.I Standard
Running Torque........ 10 oz-in typical
Housing .................... Black non-corrosive finish
Bearings...................Precision ABEC ball bearings
Weight Precision ABEC ball bearings

## Environmental

Storage Temp........... $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity................... $95 \%$ RH non-condensing
Vibration.................. 3 g @ 5 to 1000 Hz
Shock..
20 g @ 10 ms duration

## MODEL 225



## MODEL 225 CONNECTOR OPTIONS

9D 9-pin D-Subminiature
T Terminal Block
J 5-pin M12 (12 mm K 8-pin M12 (12 mm)


MODEL 225 MOUNTING OPTION (F) FLEX ARM KIT
To order Model 225 Flexible Mounting Arm Kit as an accessory, order part \#140106-01. Kit may be mounted in either an up or down orientation.


NOTE: FOR ANY CONNECTOR OPTION, THE BOLT CIRCLE RANGE IS
FROM $\varnothing_{1.72 " ~ T O ~}^{\text {甲 }}$. 60 " DUE TO THE INCREASED CAP HIEGHT


All dimensions are in inches with a tolerance of $\pm 0.005$ " or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

|  | Flying <br> Leads $^{2}$ <br> Cable |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Function | 5-pin | 8-pin |  |  |  |
| Wire Color | M12 | M12 | Term <br> Block | 9-pin <br> D-Sub |  |
| Com | Black | 3 | 7 | 1 | 9 |
| +VDC | Red | 1 | 2 | 2 | 1 |
| A | White | 4 | 1 | 3 | 2 |
| B | Green | 2 | 4 | 4 | 4 |
| Shield | Bare | -- | -- | -- | -- |

## WAVEFORM DIAGRAM

 MODELS 225A/Q

NOTE: MODEL 225A INCLUDES OUTPUT A ONLY

[^6]
## Incremental Thru-Bore \& Motor Mount Encoders

MODEL 25 T/H


## FEATURES

2.5" Opto-ASIC Encoder with a Low Profile (2.0")

Standard Bore Sizes Ranging from 0.625" to $1.125^{\prime \prime}$
Metric Bore Sizes Ranging from 6 mm to 28 mm
Single Replacement Solution for 2.0" to $3.5^{\prime \prime}$ Encoders
Resolutions to 10,000 CPR; Frequencies to 1 MHz
Versatile Flexible Mounting Options

## RoHS Compliant

Representing the next generation of high performance encoders, the Model 25T AccuCoder ${ }^{T M}$ features the largest thru-bore available in a $2.5^{\prime \prime}$ encoder, able to mount directly on shafts as large as $1.125^{\prime \prime}(28 \mathrm{~mm})$. With resolutions up to 10,000 CPR and frequencies up to 1 MHz , this industrial strength encoder is perfect for fast revving motors. The 25 T features the next generation of EPC's proprietary Opto-ASIC sensor, which provides superior accuracy and precision counts. The injection molded housing, made from EPC's custom blend of nylon composites, is grooved with "cooling fins" and can tolerate the extreme heat of the motion-control industry. With sealing available up to IP66 and many new rugged flexible mounting options, the Model 25T can perform in demanding industrial environments.

## COMMON APPLICATIONS

Motor-Mounted Feedback and Vector Control, Specialty Machines, Robotics, Web Process Control, Paper and Printing, High Power Motors

MODEL 25T/H ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 25T/H SPECIFICATIONS

Electrical
Input Voltage............ 4.75 to 28 VDC max for temperatures up to $85^{\circ} \mathrm{C}$
4.75 to 24 VDC max for temperatures between $85^{\circ}$ and $105^{\circ} \mathrm{C}$
Input Current ... 100 mA max with no output load Output Format.. ncremental - Two square waves in quadrature with channel $A$ leading $B$ for clockwise shaft rotation, as viewed from the mounting face.
See Waveform Diagram, below.
Output Types............ Open Collector - 20 mA max per channel Pull Up - Open Collector with 2.2 K ohm internal resistor, 20 mA max per channe Push-Pull-20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index. Once per revolution. 1 to 360 CPR: Ungated 361 to 10,000 CPR: Gated to output A See Waveform Diagram, below.
Max Frequency ........ 250 kHz for 1 to 2500 CPR 500 kHz for 2501 to 5000 CPR 1 MHz for 5001 to 10,000 CPR Electrical Protection Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
CE Testing.................Emissions tested per EN61000-6-3:2001 as applicable. Immunity tested per EN6100-6-2: 2005 as applicable.
Min. Edge Sep .......... $45^{\circ}$ electrical min, $63^{\circ}$ electrical or better typical Rise Time.................. Less than 1 microsecond
Accuracy.................. Within $0.1^{\circ}$ mechanical from one cycle to any other cycle, or 6 arc minutes.

## Mechanical

Max Shaft Speed...... 6000 RPM, 8000 RPM intermittent 4000 RPM for IP66 seal option
Bore Tolerance .........-0.0000"/+0.0008"
User Shaft Tolerances
Radial Runout .......0.005" max

Axial Endplay......... $\pm 0.050$ " max
Starting Torque ........ IP50 sealing: 1.0 oz-in typical IP66 sealing: 4.0 oz-in typical Note: Add 1.0 oz-in typical for $-20^{\circ} \mathrm{C}$ operation
Moment of Inertia ... $7.6 \times 10^{-4}$ oz-in-sec ${ }^{2}$
Housing .................... Proprietary nylon composite
Weight...................... 8 oz typical

## Environmental

Storage Temp............-20 to $85^{\circ} \mathrm{C}$
Humidity....................98\% RH non-condensing
Vibration.................. 20 g @ 5 to 2000 Hz
Shock... .80 g @ 11 ms duration
Sealing. . IP50, IP66 with shaft seals at both ends

## WAVEFORM DIAGRAM



NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z}$ FOR HV AND H5 OUTPUTS ONLY.

## MODEL 25T/H 3-POINT FLEX MOUNT (SE)



MODEL 25T/H CONNECTOR OPTIONS


MODEL 25T/H MOUNTING OPTIONS


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | 5-pin M12** | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 10-pin } \\ & \text { MS } \end{aligned}$ | $\begin{gathered} \text { 7-pin MS } \\ \mathrm{HV}, \mathrm{H} 5 \end{gathered}$ | $\begin{gathered} \text { 7-pin MS } \\ \begin{array}{c} \text { PU, PP, } \\ \text { OC, P5 } \end{array} \end{gathered}$ | $\begin{aligned} & \text { 6-pin MS } \\ & \begin{array}{c} \text { PU, PP, } \\ \text { oc, P5 } \end{array} \end{aligned}$ | $\begin{aligned} & \text { 9-pin } \\ & \text { D-sub } \end{aligned}$ | 10-pin Bayonet HV, H5, OD, PU, PP, OC, P5 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A, F | 9 | F |
| +VDC | White | 1 | 2 | D | D | D | B | 1 | D |
| A | Brown | 4 | 1 | A | A | A | D | 2 | A |
| $A^{\prime}$ | Yellow | -- | 3 | H | C | -- | -- | 3 | H |
| B | Red | 2 | 4 | B | B | B | E | 4 | B |
| $B^{\prime}$ | Green | -- | 5 | 1 | E | -- | -- | 5 | J |
| Z | Orange | 5 | 6 | C | -- | C | C | 6 | C |
| Z' | Blue | -- | 8 | J | -- | -- | -- | 7 | K |
| Case | -- | -- | -- | G | G | G | -- | 8 | G |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- | -- |
| *CE Option: Cable shield (bare wire) is connected to internal case. tStandard cable is 24 AWG conductors with foil and braid shield. <br> ${ }^{* *}$ CE Option: Use cable cord set with shield connected to M12 connector coupling nut. |  |  |  |  |  |  |  |  |  |

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL 58TP - PROGRAMMABLE



Ø58 mm
FEATURES
Programmable with USB Module or Factory Configured when Ordered
Programmable Resolution from 1 to 65,536 CPR
Programmable Output Type and Wave Form
58 mm Thru-Bore or Hollow Bore (Blind)
Standard and Metric Thru-Bore Sizes up to $5 / 8^{\prime \prime}$ and 15 mm
Several Flexible Mounting Options
Sealing Options up to IP67
The Model 58TP Programmable 58 mm Accu-CoderPro ${ }^{\text {TM }}$ thru-bore encoder is specifically designed for the challenges of an industrial environment. Its advanced set of electronics allow the encoder to be programmed to meet your exact application needs. Using EPC's optional programming module, users may select the output type, 32 different waveforms, and any resolution from 1 to 65,536 CPR - that's 262,144 counts using $4 x$ quadrature counting. These programming features allow a single encoder to be configured for multiple applications, enabling one encoder to replace many different part numbers - and that provides cost savings on inventory and down-time replacement. The 58TP can also be configured and shipped with specs preprogrammed, with no on-site programming needed.

## COMMON APPLICATIONS

Motor Control, Conveyors, Elevator Controls, Machine Control, Food Processing, Process Control, Robotics, Material Handling, Textile Machines and all types of Motion Control Feedback

MODEL 58TP ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


3-point Flex Mount SH 2.72" to 3.42" B.C. (Block \& Pin) Tether Arm Kit SG 3.50" to 5.90" B.C. (4.5" C-face) Tether Arm Kit SJ 3.50 " to 8.10 " B.C. (8.5" C-face) Tether Arm Kit

[^7]
## MODEL 58TP SPECIFICATIONS



## MODEL 58TP / 58HP 3-POINT FLEX MOUNT (SE)



MODEL 58TP / 58HP CONNECTOR OPTIONS


MODEL 58TP / 58HP MOUNTING OPTIONS


All dimensions are in inches with a tolerance of +0.005 " or $+0.01^{\prime \prime}$ unless otherwise specified. Metric dimensions are given in brackets [mm].

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | $\begin{aligned} & \text { 5-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | 10-pin MS | $\begin{gathered} \text { 7-pin MS } \\ \mathrm{HV}, \mathrm{H} 5 \end{gathered}$ | 7-pin MS PU,PP,OC,P5 | $\begin{gathered} \text { 9-pin } \\ \text { D-sub } \end{gathered}$ | 12-pin M23 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | 9 | 10 |
| +VDC | Red | 1 | 2 | D | D | D | 1 | 12 |
| A | White | 4 | 1 | A | A | A | 2 | 5 |
| $\mathrm{A}^{\prime}$ | Brown | -- | 3 | H | C | -- | 3 | 6 |
| B | Blue | 2 | 4 | B | B | B | 4 | 8 |
| $B^{\prime}$ | Violet | -- | 5 | 1 | E | -- | 5 | 1 |
| Z | Orange | 5 | 6 | c | -- | c | 6 | 3 |
| Z' | Yellow | -- | 8 | J | -- | -- | 7 | 4 |
| Case | Green | -- | -- | G | G | G | 8 | 9 |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- |
| +VDC Sense | -- | -- | -- | -- | -- | -- | -- | 2 |
| Com Sense | -- | -- | -- | -- | -- | -- | -- | 11 |

*CE Option: Cable shield (bare wire) is connected to internal case.
${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.
**CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL 58TP - PROGRAMMABLE

EPC STANDARD WAVEFORM (B5)
Additional waveforms available. See below for other options.


NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES.
COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z}$ APPLY TO LINE DRIVER (HV \& H5) OUTPUTS ONLY.


An EPC Thru-Bore Encoder in a common application, mounted on a motor with an SJ Flex Mount

## WAVEFORMS

Choose any of these waveforms using the Field Programming Software, USB programming module, and interface cable (see page 57).


Odd numbers - A leads B Even numbers - B leads A


A and B - High Going Index W and X - Low Going Index


## FIELD PROGRAMMING SOFTWARE

With the easy to use, point-and-click interface, programming is quick and straight-forward. The number of possible configurations makes this Size 58 programmable thru-bore or hollow bore encoder incredibly versatile. Anywhere a Size 58 thru-bore or hollow bore encoder goes, the Model 58TP can get the job done.

Available on USB drive or by download.
System requirements:

- Windows 7 or higher operating systems
- USB 2.0 port required for USB Programming Module (see below)
$\checkmark$ (PR - any resolution from 1 to 65,536
That's 262,144 counts using $4 x$ quadrature counting
$\checkmark$ Waveform - choose from 32 options
See page 56 for waveform choices


## $\checkmark$ Output type - 6 different output types



USB PROGRAMMING KIT
Kit includes Field Programming Software, USB Programming Module, and 2-meter Interface Cable with specified connector. See Accessories for individual Interface Cables.
All output types are 5 V to 30 V in/out except H 5 Line Driver and P5 Push-Pull output types, which are 5-30VDC in and 5VDC out.

| CONNECTOR TYPE | ITEM \# |
| :--- | :--- |
| 7-pin MS | PR1-001-07 |
| 10-pin MS | PR1-001-10 |
| 5-pin M12 | PR1-001-J |
| 8-pin M12 | PR1-001-K |
| 9-pin D-Sub | PR1-001-09 |
| Gland Cable | PR1-001-G |
| 12-pin M23 | PR1-001-R |

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL 58 TF


$\emptyset 58$ mm

## FEATURES

58 mm Thru-Bore or Hollow Bore (Blind)
Standard and Metric Thru-Bore Sizes up to 5/8" and 15 mm
Resolution from 1 to 65,536 CPR
Several Flexible Mounting Options
Sealing Options up to IP67
Multiple Connector Options

The Model 58TF Accu-CoderPro ${ }^{\text {TM }}$ is a 58 mm thru-bore encoder that is specifically designed for the challenges of an industrial environment. Its advanced set of electronics allow the encoder to be configured to meet your exact application needs. Choose from 6 output types, 32 different waveforms, and select any resolution from 1 to 65,536 CPR (that's 262,144 counts in full quadrature). The Model 58TF is also highly mechanically configurable, with bore options up to $5 / 8$ " or 15 mm , several flexible mounting options, multiple connector options, and sealing up to IP67. This versatile thru-bore encoder can go in almost any application.

## COMMON APPLICATIONS

Motor Control, Conveyors, Elevator Controls, Machine Control, Food Processing, Process Control, Robotics, Material Handling, Textile Machines and all types of Motion Control Feedback

## MODEL 58TF ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 58TF SPECIFICATIONS

Electrical
Input Voltage............ 4.75 to 30 VDC max. See Output Types for limitations
Input Current............ 100 mA max with no output load ( 65 mA typical)
Output Format.......... Incremental, Programmable. See Waveforms on page 56 for options.
Output Types............Line Driver* (HV) - 20 mA max per channel, max freq $1.0 \mathrm{MHz}, 5 \mathrm{VDC}$ max at $100^{\circ} \mathrm{C}$ or 24 VDC max at $85^{\circ} \mathrm{C}$.
Line Driver* (H5) - 5-30 VDC in/5 VDC out, 20 mA max per channel, max freq 2.7 MHz , 5 VDC max at $100^{\circ} \mathrm{C}$.
Push-Pull (PP) - 20 mA max per channel, max frequency $1.0 \mathrm{MHz}, 5 \mathrm{VDC}$ max at $100^{\circ} \mathrm{C}$ or 24 VDC max at $85^{\circ} \mathrm{C}$.
Push-Pull (P5) - 5-30 VDC in/5 VDC out, 20 mA max per channel, max frequency 2.7 MHz, 5 VDC max at $100^{\circ} \mathrm{C}$

Open Collector (OC) - 100 mA max per channel, 200 KHz max freq recommended Pull-Up (PU) - 2.2K ohm internal resistors, 100 mA max per channel, 150 KHz max freq recommended, max temp $85^{\circ} \mathrm{C}$ at $>24$ VDC *Meets RS 422 at 5 VDC supply
Index Once per revolution, programmable. EPC standard is $180^{\circ}$ gated to output A (waveform B5). See Waveform Diagrams for additional options.
Max Frequency ......... 2.7 MHz subject to RPM restrictions for high resolution (CPR):
5000 RPM max for CPR 16385 to 32768 and 2500 RPM max for CPR 32769 to 65536 NOTE: Use 5 VDC Line Driver (H5 or HV output type) to obtain high frequencies.
Electrical Protection .. Overvoltage, reverse voltage, and output short circuit protected. NOTE: Sustained over or reverse voltage may result in permanent damage.
CE/EMC $\qquad$ Immunity tested per EN 61000-6-2:2005 Emission tested per EN 61000-6-4:2007 + A1: 2011
Rise Time.
Accuracy. $\qquad$ Less than 1 microsecond Better than $0.015^{\circ}$ or 54 arc-sec from true position

## Mechanical

Max Shaft Speed...... 6000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Shaft Material .......... 303 Stainless Stee
Shaft Rotation .......... Bi-directional
Bore Tolerance .........-0.0000"/+0.001"
User Shaft Tolerances
Radial Runout......0.005" max
Axial Endplay....... $\pm 0.030$ max
Starting Torque ........ IP50 sealing: 3.0 oz-in typical
IP64 sealing: 4.0 oz-in typical IP66 or IP67 sealing: 7.0 oz-in typical
Moment of Inertia ... $5.5 \times 10^{-4}$ oz-in-sec ${ }^{2}$

Housing .................... Black non, corrosive finish
Weight. 10 oz.

## Environmental

Operating Temp ....... $-20^{\circ}$ to $85^{\circ} \mathrm{C}$ for standard models $-40^{\circ}$ to $100^{\circ} \mathrm{C}$ for extended temp option
NOTE: For IP66 or IP67 sealing derate max temperature of $100^{\circ} \mathrm{C}$ by $4^{\circ} \mathrm{C}$ for every 1000 RPM above 2000 RPM.
Humidity.. $\qquad$ $95 \%$ RH non-condensing
Vibration. $\qquad$ 10 to 2000 Hz A 20g (International Standard IEC 60068-2-6)
Shock....................... 80g @ 6 ms Duration (International Standard IEC 60068-2-27)
Sealing......................IP50 standard; IP64, IP66 or IP67 optional

## MODEL 58TF / 58HF 3-POINT FLEX MOUNT (SE)



MODEL 58TF / 58HF CONNECTOR OPTIONS


MODEL 58TF / 58HF MOUNTING OPTIONS


All dimensions are in inches with a tolerance of +0.005 " or +0.01 " unless otherwise specified.
Metric dimensions are given in brackets [mm].

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | $\begin{aligned} & \text { 5-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | 10-pin MS | $\begin{gathered} \text { 7-pin MS } \\ \text { HV,H5 } \end{gathered}$ | 7-pin MS PU,PP,OC,P5 | $\begin{aligned} & \text { 9-pin } \\ & \text { D-sub } \end{aligned}$ | 12-pin M23 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | 9 | 10 |
| +VDC | Red | 1 | 2 | D | D | D | 1 | 12 |
| A | White | 4 | 1 | A | A | A | 2 | 5 |
| $A^{\prime}$ | Brown | -- | 3 | H | C | -- | 3 | 6 |
| B | Blue | 2 | 4 | B | B | B | 4 | 8 |
| $B^{\prime}$ | Violet | -- | 5 | 1 | E | -- | 5 | 1 |
| Z | Orange | 5 | 6 | c | -- | C | 6 | 3 |
| Z' | Yellow | -- | 8 | J | -- | -- | 7 | 4 |
| Case | Green | -- | -- | G | G | G | 8 | 9 |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- |
| +VDC Sense | -- | -- | -- | -- | -- | -- | -- | 2 |
| Com Sense | -- | -- | -- | -- | -- | -- | -- | 11 |

*CE Option: Cable shield (bare wire) is connected to internal case.
${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.
**E Option: Use cable cordset with shield connected to M12 connector coupling nut.

## Incremental Thru-Bore \& Motor Mount Encoders

MODEL 775


Ø4.3"

## FEATURES

Thru-Bore Design for Easy Mounting Bore Options to 1.375"<br>Incorporates Opto-ASIC Technology<br>Resolutions to 4096 CPR<br>$100^{\circ}$ C Operating Temperature Available CE Marking Available

The sleek design of the Model 775 Thru-Bore Series Accu-Coder ${ }^{\text {TM }}$ makes form and function a successful reality. The slim profile and Thru-Bore design, makes installation easy by simply slipping the bore over motor shafts up to $1.375^{\prime \prime}$ in diameter. The advanced Opto-ASIC based electronics provide the superior noise immunity necessary in many industrial applications.
With a variety of bore sizes, resolutions, and connector types, application possibilities are endless.

COMMON APPLICATIONS
Motor Feedback, Velocity \& Position Control, Food Processing, Robotics, Material Handling

MODEL 775 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


A Completely encloses motor shaft, and eliminates access to motor shaft. For physical protection only.
B Thru-Bore housing version. Allows access to motor shaft.

## Channel A Leads B

Q Quadrature A \& B
R Quadrature A \& B with Index
Channel B Leads A
K Reverse Quadrature A \& $B$
D Reverse Quadrature A \& B with Index
CYCLES PER

1-4096
ee CPR Options below for
available resolutions.

NUMBER OF CHANNELS

See http://www.encoder.com/
literature/index-phasing.pdf for additional options, and waveforms.

BORE SIZE
A 5/8", 0.625 " collet style H 14 mm collet style B $3 / 4^{\prime \prime}, 0.750$ " collet style I 19 mm collet style
C $7 / 8^{\prime \prime}, 0.875^{\prime \prime}$ collet style K 24 mm collet style
D 1", 1.000" collet style M 25 mm clamp style
O 1-1/8", 1.125" clamp style L 28 mm clamp style
T 1-1/4", 1.250" clamp style Q 30 mm clamp style
V 1-3/8", 1.375 " clamp style $\mathbf{R} 32 \mathrm{~mm}$ clamp style

MODEL 775 CPR OPTIONS

| 0060 | 0100 | 0120 | 0240 | 0250 | 0256 | 0500 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0512 | 1000 | 1024 | 2048 | 2500 | 4096 |  |

Contact Customer Service for other disk resolutions; not all disk resolutions available with all output types

## NOTES:

1 Contact Customer Service for index gating options.
5 to 24 VDC max for high temperature option.
3 Line Driver Outputs not available with 5 -pin M12 or 6-pin MS connector. Available with 7-pin MS connector only without Index Z.
4 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
5 For non-standard cable lengths, add a forward slash (/) plus cable length expressed in feet. Example: P/6 $=6$ feet of cable.
6 Connector options other than 9D and Prequire extended housing. See drawing, next page
7 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL 775 SPECIFICATIONS

Electrica
Input Voltage............ 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$
Input Current . 100 mA max with no output load Input Ripple 100 mV peak-to-peak at 0 to 100 kHz Output Format. Incremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the mounting face.
See Waveform Diagrams
Output Types.. Open Collector - 100 mA max per channe Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel
Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index.. $\qquad$ Once per revolution. 0001 to 0474 CPR: Ungated 0475 to 4096 CPR: Gated to output A See Waveform Diagrams.
Max Frequency . 200 kHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2

Quadrature.............. $67.5^{\circ}$ electrical or better is typical,
Edge Separation $54^{\circ}$ electrical minimum a temperatures $>99^{\circ} \mathrm{C}$

Rise Time Less than 1 microsecond

Mechanical
Max Shaft Speed...... 6000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
User Shaft Tolerances
Radial Runout ....... 0.005"
Axial Endplay......... $\pm 0.030$ " with appropriate flex mount
Moment of Inertia ... $3.3 \times 10^{-3}$ oz-in-sec ${ }^{2}$ typical
Housing $\qquad$ All metal construction Weight 1.0 lb with gland nut or D-sub connector option 1.5 lb with MS connector option Note: All weights typical

## Environmental

Storage Temp ...........- $25^{\circ}$ to $100^{\circ} \mathrm{C}$
Humidity... 98\% RH non-condensing
Vibration. $\qquad$ 10 g @ 58 to 500 Hz

Shock. 50 g @ 11 ms duration
Sealing $\qquad$ .IP50

MODEL 775 COLLET CLAMP (A, B, C, D, H, I, K)


MODEL 775 CLAMP STYLE (O, T, V, M, L, Q)


MODEL 775 EXTENDED HOUSING (W, X, Y, J, K)


MODEL 775 SHOWN WITH ANTI-ROTATION FLEX MOUNT


All dimensions are in inches with a tolerance of $\pm 0.005$ " or $\pm 0.01$ " unless otherwise specified.
For wiring table and waveforms, see page 64.

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL 776



Ø4.3"
FEATURES
Slim Profile - Only 1.36" In Depth
Thru-Bore Design For Easy Mounting
Incorporates Opto-ASIC Technology
Resolutions to 4096
Bore Options to 1.875"
CE Marking Available
The Thru-Bore Series Accu-Coder ${ }^{\text {TM }}$ Model 776 encoder is designed to fit directly on either a motor or other shaft where position, direction, or velocity information is needed. The advanced Opto-ASIC based electronics provide the superior noise immunity necessary in many industrial applications. The Model 776 conveniently features a clamp type mount for fast and easy mounting over a large range of shaft sizes. An optional anti-rotation flex mount maintains housing stability.

COMMON APPLICATIONS
Motor Feedback, Velocity \& Position Control, Robotics, Conveyors, Material Handling

MODEL 776 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 776 SPECIFICATIONS

Electrical
Input Voltage... 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$
Input Current . 100 mA max with no output load
Input Ripple. $\qquad$ .100 mV peak-to-peak at 0 to 100 kHz Output Format......... ncremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the mounting face. See Waveform Diagrams.
Output Types. Open Collector - 100 mA max per channe Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel
Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index . Once per revolution. 0475 to 4096 CPR: Gated to output A 0001 to 0474 CPR: Ungated See Waveform Diagrams.
Max Frequency 200 kHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2

Quadrature...............67.5 ${ }^{\circ}$ electrical or better is typical,
Edge Separation $54^{\circ}$ electrical minimum at temperatures $>99^{\circ} \mathrm{C}$

Rise Time. Less than 1 microsecond

## Mechanical

Max Shaft Speed...... 3500 RPM. Higher shaft speeds may be achievable, contact Customer Service.
User Shaft Tolerances
Radial Runout .......0.005"
Axial Endplay......... $\pm 0.030$ " with appropriate flex mount
Moment of Inertia $\ldots .3 .3 \times 10^{-3}$ oz-in-sec ${ }^{2}$ typical
Housing ..................... All metal construction
Weight. 1.0 lb with gland nut or D-sub connector option 1.5 lb with MS connector option Note: All weights typical

## Environmental

Storage Temp . $25^{\circ}$ to $100^{\circ} \mathrm{C}$ Humidity $\qquad$ 98\% RH non-condensing

Vibration $\qquad$ 10 g @ 58 to 500 Hz

Shock.. $\qquad$ $50 \mathrm{~g} @ 11 \mathrm{~ms}$ duration
Sealing. IP50

MODEL 776 WITH GLAND NUT CABLE (P)


MODEL 776 WITH 9-PIN D-SUB CONNECTOR (9D)

 10-PIN MS $\begin{array}{ll}5 \text { - OR 8-PIN M12 } & 0.90 \\ & 0.50\end{array}$


MODEL 776 SHOWN WITH ANTI-ROTATION FLEX MOUNT


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.
For wiring table and waveforms, see page 64.

## Incremental Thru-Bore \& Motor Mount Encoders

## MODELS 775 \& 776

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | $\begin{aligned} & \text { 5-pin M12++ } \\ & \text { PU, PP, OC } \end{aligned}$ | 8-pin M12 ${ }^{++}$ | 10-pin MS | $\underset{H V}{7-\text { pin }^{\text {MS }}}$ | $\begin{aligned} & \text { 7-pin MS } \\ & \text { PU, PP, OO } \end{aligned}$ | $\begin{aligned} & \text { 6-pin MS } \\ & \text { PU, PP, OC } \end{aligned}$ | 9-pin D-sub |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A, F | 9 |
| +VDC | Red | 1 | 2 | D | D | D | B | 1 |
| A | White | 4 | 1 | A | A | A | D | 2 |
| $A^{\prime}$ | Brown | -- | 3 | H | C | -- | -- | 3 |
| B | Blue | 2 | 4 | B | B | B | E | 4 |
| B' | Violet | -- | 5 | I | E | -- | -- | 5 |
| Z | Orange | 5 | 6 | C | -- | C | C | 6 |
| Z' | Yellow | -- | 8 | J | -- | -- | -- | 7 |
| Case | -- | -- | -- | G** | G** | G** | -- | $8^{+}$ |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- |

*CE Option: Cable shield (bare wire) is connected to internal Case.
**CE Option: Pin G is connected to Case. Non-CE Option: Pin G has No Connection.
${ }^{+}$CE Option: Pin G is connected to Case. Non CE Option: Pin 8 has No Connection.
${ }^{++}$CE Option: Use cable cordset with shield connected to M12 connector coupling nut.
${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.

## WAVEFORM DIAGRAMS

Line Driver and Push-Pull


NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES.
WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS
$\bar{A}, \bar{B}, \bar{Z}$ FOR HV OUTPUT ONLY.

Open Collector and Pull-Up


## BORE OPTIONS

When to Specify a Hollow Bore (Blind) Encoder vs. a Thru-Bore Encoder

When specifying a rotary encoder, should you opt for a hollow bore (also called a "blind encoder") or a thru-bore housing? Often either design can work equally well. However, in some situations there are important reasons to choose one over the other.

Generally, thru-bore (or through-bore) housings have a bore opening that passes completely through the encoder body. The encoder is more or less a donut. With a hollow bore (or blind bore) housing the bore does not pass completely through the encoder, with the shaft end residing inside the housing. The depth of the bore varies from model to model, with some units only having a cap or cover on one side of the housing.

NOTE: EPC offers many incremental encoders in both thru-bore and hollow bore (blind) configurations. Due to their electronics, magnetic absolute encoders are only offered as hollow bore (blind). See Absolute Section, pages 10-25, for Absolute Encoder options.

A thru-bore housing offers more flexibility for shaft attachment. Provided a means of securing the anti-rotation tether is readily available, a thru-bore encoder can be affixed to any point on the shaft in question.

Here are three factors that favor use of a hollow bore (blind) encoder:

1. Environmental Seal. If your encoder will be exposed to dirt, dust

ABOVE: Model 15H, a 1.5 inch hollow bore, or blind, incremental encoder. Also available in thru-bore. See below. BELOW: A Model 15 T mounted on the end of a motor. See page 40 for product specifications.
 and moisture, consider a hollow bore encoder. A thru-bore encoder has two exposed shaft seals that offer potential paths of contaminant ingress. With a hollow bore solution, one seal is protected from


ABOVE: Model 25T, a 2.5 inch thru-bore incremental encoder. Also available in hollow bore (blind). See below. BELOW: A Model 25H hollow bore mounted on a conveyor belt system. See page 52 for product specifications.
 contaminants and potential leakage. If the encoder is exposed to washdown or direct water spray, we recommend a hollow bore housing if possible.
2. Starting Torque. Since a sealed thru-bore encoder has two shaft seals, the friction created by the additional shaft-seal interface is usually greater than that of a hollow bore housing, which can translate into greater starting torque for thru-bore versus hollow bore encoders.
3. Safety. With a hollow bore encoder, hazards presented by an exposed rotating shaft are minimized.

For most applications the items above may be relatively minor points to consider when specifying a rotary encoder. However, failure to properly address them could contribute to less than optimum encoder longevity and performance, especially when an application pushes encoder performance requirements toward the limits.

If you have questions about which housing is right for your application, our Technical Services Department is available to help you find the right solution. Call today.

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL 770



FEATURES<br>Slim Profile - Only 1.00" Deep<br>Fits NEMA Size 56C Thru 184C Motor Faces (4.5" AK) Incorporates Opto-ASIC Technology Resolutions to 4096 CPR

The Model 770 C-Face encoder is a rugged, high resolution encoder designed to mount directly on NEMA C-Face motors. Both sides of the encoder are C-Face mounts, allowing additional C-Face devices to be mounted to this encoder. Unlike many C-Face kit type encoders, the Model 770 contains precision bearings and an internal flex mount, virtually eliminating encoder failures and inaccuracies induced by motor shaft runout or axial endplay. The advanced Opto-ASIC design provides the advanced noise immunity necessary for many industrial applications. This encoder is ideal for applications using induction motors and flux vector control. The Model 770 provides speed and position information for drive feedback in a slim profile - only 1.00 " thick. The Thru-Bore design allows fast and simple mounting of the encoder directly to the accessory shaft or to the drive shaft of the motor, using the standard motor face (NEMA sizes 56C - 184C). The tough, allmetal housing resists the vibration and hazards of an industrial environment.

COMMON APPLICATIONS
Motor Feedback, Velocity \& Position Control, Conveyors, Variable Speed Drives, Mixing \& Blending Motors, Assembly \& Specialty Machines

MODEL 770 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


| MODEL 770 CPR OPTIONS |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0060 | 0100 | 0120 | 0240 | 0250 | 0256 | 0500 |
| 0512 | 1000 | 1024 | 2048 | 2500 | 4096 |  |

Contact Customer Service for other disk resolutions; not all disk resolutions available with all output types.

## NOTES:

1 Thru-bore version may be IP65 sealed if mounted between two C-Face devices with optional gasket kit. Select 'Yes' under C-Face Gasket Kit Option.
2 Contact Customer Service for index gating options.
35 to 24 VDC max for high temperature option.
4 Line Driver Outputs not available with 5-pin M12 connector. Available with 7-pin MS connector only without Index Z.
5 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
6 For non-standard cable lengths, add a forward slash (I) plus cable length expressed in feet. Example: P/6 = 6 feet of cable.
7 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com..

## MODEL 770 SPECIFICATIONS

Electrical up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$
Input Current ........... 100 mA max with no output load Input Ripple.............. 100 mV peak-to-peak at 0 to 100 kHz Output Format......... Incremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the mounting face. See Waveform Diagrams.
Output Types ...............Open Collector - 100 mA max per channel
Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel
Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index........................ Once per revolution.
0001 to 0474 CPR: Ungated 0475 to 4096 CPR: Gated to output A See Waveform Diagrams.
Max Frequency ........ 200 kHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2

Quadrature............... $67.5^{\circ}$ electrical or better is typical,
Edge Separation $\quad 54^{\circ}$ electrical minimum at temperatures $>99^{\circ} \mathrm{C}$

Rise Time.................. Less than 1 microsecond

## Mechanical

Max Shaft Speed...... 6000 RPM. Higher shaft speeds may be achievable; contact Customer Service.
Bore Tolerance ......... +0.0015"/-0.000"
User Shaft Tolerances
Radial Runout ....... $0.005^{\prime \prime}$
Axial Endplay......... $\pm 0.050 "$
Moment of Inertia ... $3.3 \times 10^{-3} \mathrm{oz}$-in-sec ${ }^{2}$ typical
Housing ....................All metal construction
Weight $\qquad$ 2.60 lb with gland nut 3.00 lb with all other connector options Note: All weights typical

## Environmental

Storage Temp ...........- $25^{\circ}$ to $100^{\circ} \mathrm{C}$
Humidity.................. $98 \%$ RH non-condensing
Vibration.................. 10 g @ 58 to 500 Hz
Shock..
50 g @ 11 ms duration
Sealing $\qquad$ IP65 for Option A housing style with gasket kit; IP50 for Option B housing style

MODEL 770 WITH GLAND NUT (P)


MODEL 770 WITH CONDUIT BOX (B, X, Y, J, K)


OPTIONAL HOUSING STYLE (A) PROTECTIVE COVER


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01$ " unless otherwise specified.

## WAVEFORM DIAGRAMS

Line Driver and Push-Pull
 NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES, WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z}$ FOR HV OUTPUT ONLY.

Open Collector and Pull-Up


## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | 5-pin <br> M12++ <br> $\mathrm{Pu}, \mathrm{PP}$, <br> OC | $\begin{aligned} & \text { 8-pin } \\ & \text { M12 }^{++} \end{aligned}$ | $\begin{aligned} & \text { 10-pin } \\ & \text { MS } \end{aligned}$ | $\begin{gathered} \text { 7-pin } \\ \text { MS } \\ \text { HV } \end{gathered}$ | $\begin{aligned} & \text { 7-pin } \\ & \text { MS } \\ & \text { PU, Pp, } \\ & \text { OC } \end{aligned}$ | Term Block | 10-pin Indust. Clamp |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | 2 | 1 |
| +VDC | Red | 1 | 2 | D | D | D | 1 | 6 |
| A | White | 4 | 1 | A | A | A | 3 | 3 |
| $A^{\prime}$ | Brown | -- | 3 | H | C | -- | 4 | 8 |
| B | Blue | 2 | 4 | B | B | B | 5 | 2 |
| $B^{\prime}$ | Violet | -- | 5 | 1 | E | -- | 6 | 7 |
| Z | Orange | 5 | 6 | C | - | C | 7 | 4 |
| Z' | Yellow | -- | 8 | J | -- | -- | 8 | 9 |
| Case | -- | -- | -- | G** | G** | G** | -- | -- |
| Shield | Bare* | -- | -- | -- | -- | -- | $9^{+}$ | $10^{+}$ |
| *CE Option: Cable shield (bare wire) is connected to internal Case. <br> ${ }^{* *}$ CE Option: Pin G is connected to Case. Non-CE Option: Pin G has No Connection. <br> ${ }^{+}$CE Option: Pins 9 and 10 are connected to Case. Non CE Option: Pins 9 and 10 have No Connection. <br> ${ }^{++}$CE Option: Use cable cordset with shield connected to M12 connector coupling nut. <br> +Standard cable is 24 AWG conductors with foil and braid shield. |  |  |  |  |  |  |  |  |

†Standard cable is 24 AWG conductors with foil and braid shield

## Incremental Thru-Bore \& Motor Mount Encoders

## MODEL 771



FEATURES

Large Bore Size to $1.875^{\prime \prime}$ or 43 mm<br>Fits NEMA Size 182TC Thru 256TC Motor Faces (8.5" AK)<br>Incorporates Opto-ASIC Technology<br>Resolutions to 4096 CPR

The Model 771 C-Face encoder is a rugged, high resolution encoder designed to mount directly on NEMA C-Face motors. Both sides of the encoder are C-Face mounts, allowing additional C-Face devices to be easily mounted. Many competitive C-Face units are kit type encoders, but the Model 771 contains precision bearings and an internal flex mount that virtually eliminates encoder failures and inaccuracies induced by motor shaft runout or axial endplay. The advanced Opto-ASIC design provides superior noise immunity necessary for many industrial applications. This encoder is ideal for applications using induction motors and flux vector control. A ThruBore design allows fast and simple mounting of the encoder directly to the accessory shaft or drive shaft of a motor using a NEMA standard motor face (sizes 182TC - 256TC). The tough, all metal housing resists the vibration and hazards of an industrial environment.

COMMON APPLICATIONS
Ø9.0"
Motor Feedback, Velocity \& Position Control, Servo Control Systems, Assembly \& Specialty Machines, Elevator Controls

## MODEL 771 ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


HOUSING STYLE
A Cover completely encloses motor shaft and eliminates access to motor shaft; IP65 rated.
B Thru-Bore housing version with IP50 dust seal ${ }^{1}$

MODEL 771 CPR OPTIONS

| 0060 | 0100 | 0120 | 0240 | 0250 | 0256 | 0500 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0512 | 1000 | 1024 | 2048 | 2500 | 4096 |  |

Contact Customer Service for other disk resolutions; not all disk resolutions available with all output types

## BORE SIZE

1-4096
See CPR Options below for
available resolutions.
Price adder for CPR >1024
T 5/8", $0.625^{\prime \prime}$ V 7/8", 0.875" W 1", 1.000" A 1-1/8", 1.125" K 1-1/4", 1.250" B 1-3/8", 1.375" C 1-1/2", 1.500" D 1-5/8", 1.625" F 1-3/4", 1.750" E 1-7/8", 1.875"
H 28 mm
Q 30 mm R 32 mm
L 35 mm
I 38 mm
J 40 mm
M 42 mm N 43 mm

## NUMBER OF CHANNELS ${ }^{2}$

Channel A Leads B
Q Quadrature A \& B
R Quadrature A \& B with Index
Channel B Leads A
K Reverse Quadrature A \& B
D Reverse Quadrature A \& B with Index

See http://www.encoder.com/ literaturelindex-phasing.pdf for additional options, and waveforms.

## CONNECTOR TYPE ${ }^{5}$

P Gland Nut with $244^{\prime \prime}$ cable ${ }^{6}$
B Terminal Strip in Conduit Box
X 10-pin MS on Conduit Box
Y 7-pin MS on Conduit Box 4
J 5 -pin M12 ( 12 mm ) on Conduit Box ${ }^{4}$
K 8-pin M12 (12 mm) on Conduit Box
L 10-pin Industrial Clamp

## NOTES:

1 Thru-Bore version may be IP65 sealed if mounted between two C-Face devices with optional gasket kit. Select 'Yes' under C-Face Gasket Kit Option.
2 Contact Customer Service for index gating options.
35 to 24 VDC max for high temperature option.
4 Line Driver Outputs not available with 5-pin M12 connector. Available with 7-pin MS connector only without Index Z.
5 For mating connectors, cables, and cordsets see Accessories at encoder.com.
For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
6 For non-standard cable lengths, add a forward slash (I) plus cable length expressed in feet. Example: P/6 = 6 feet of cable.

## MODEL 771 SPECIFICATIONS

## Electrical

Input Voltage............ 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$
Input Current .100 mA max with no output load
Input Ripple... 100 mV peak-to-peak at 0 to 100 kHz Output Format. . Incremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the mounting face. See Waveform Diagrams.
Output Types.................Open Collector - 100 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel
Push-Pull - 20 mA max per channe Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index. Once per revolution. 0001 to 0474 CPR: Ungated 0475 to 4096 CPR: Gated to output A See Waveform Diagrams.
Max Frequency ........ 200 kHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2

Quadrature.. Edge Separation $67.5^{\circ}$ electrical or better is typical, $54^{\circ}$ electrical minimum at temperatures $>99^{\circ} \mathrm{C}$

Rise Time. . Less than 1 microsecond

## Mechanical

Max Shaft Speed...... 3500 RPM. Higher shaft speeds may be achievable, contact Customer Service. 6000 RPM for 1.125", 1.250", 1.375", $28 \mathrm{~mm}, 30 \mathrm{~mm}, 32 \mathrm{~mm}$ bore diameter
User Shaft Tolerances
Radial Runout .......0.005"
Axial Endplay......... $\pm 0.1^{\prime \prime}$
Moment of Inertia ... $3.3 \times 10^{-3}$ oz-in-sec ${ }^{2}$ typical
Housing ....................All metal construction
Weight....................... 7.0 lb typical

## Environmental

Storage Temp ............ $-25^{\circ}$ to $100^{\circ} \mathrm{C}$
Humidity................... $98 \% \mathrm{RH}$ non-condensing
Vibration... $10 \mathrm{~g} @ 58$ to 500 Hz
Shock. $\qquad$ 50 g @ 11 ms duration
Sealing. $\qquad$ IP65 for Option A housing style with gasket kit; IP50 for Option B housing style

## MODEL 771 WITH GLAND NUT CABLE (P)



MODEL 771 WITH CONDUIT BOX (B, X, Y, J, K)


OPTIONAL HOUSING STYLE

## (A) PROTECTIVE COVER

(


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

WAVEFORM DIAGRAMS
Line Driver and Push-Pull


CLOCKWISE ROTATION AS VIEWED FROM THE MOUNTING FACE
NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES.
WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS
$\bar{A}, \bar{B}, \bar{Z}$ FOR HV OUTPUT ONLY.
Open Collector and Pull-Up


WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | 5-pin M12 ${ }^{++}$ PU, PP, oc | $\begin{aligned} & \text { 8-pin } \\ & \text { M12 } \end{aligned}$ | $\begin{aligned} & \text { 10-pin } \\ & \text { MS } \end{aligned}$ | $\begin{gathered} \text { 7-pin } \\ \text { MS } \\ \text { HV } \end{gathered}$ | 7-pin MS $\mathrm{PU}, \mathrm{PP}$, oc | Term Block | 10-pin Indust. Clamp |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | 2 | 1 |
| +VDC | Red | 1 | 2 | D | D | D | 1 | 6 |
| A | White | 4 | 1 | A | A | A | 3 | 3 |
| $A^{\prime}$ | Brown | -- | 3 | H | C | -- | 4 | 8 |
| B | Blue | 2 | 4 | B | B | B | 5 | 2 |
| $B^{\prime}$ | Violet | -- | 5 | 1 | E | -- | 6 | 7 |
| z | Orange | 5 | 6 | c | -- | c | 7 | 4 |
| Z' | Yellow | -- | 8 | J | -- | -- | 8 | 9 |
| Case | -- | -- | -- | G** | G** | G** | $9^{+}$ | $10^{+}$ |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- |
| *CE Option: Cable shield (bare wire) is connected to internal Case. <br> **CE Option: Pin G is connected to Case. Non-CE Option: Pin G has No Connection. <br> ${ }^{+}$CE Option: Pins 9 and 10 are connected to Case. Non CE Option: Pins 9 and 10 have No Connection. <br> ${ }^{++}$CE Option: Use cable cordset with shield connected to M12 connector coupling nut. <br> ${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield. |  |  |  |  |  |  |  |  |

## Incremental Shaft Encoders

MODEL 711


## FEATURES

## The Original Industry-Standard Cube <br> Versatile Housing Styles <br> Unidirectional Output <br> Resolutions Available to $\mathbf{1 0 , 0 0 0}$ CPR

The Model 711 Accu-Coder ${ }^{\text {TM }}$ is the original, industry standard cube encoder. Designed for compatibility with most programmable controllers, electronic counters, motion controllers, and motor drives, it is ideally suited for applications that require a simple, symmetrical, unidirectional square wave output in a single channel format. Critical performance specifications for the most popular resolutions and advanced Opto-ASIC circuitry - a single chip design that eliminates many board level components - increase the reliability of an already dependable and durable encoder. With new options continually being added, the Model 711 excels in a wide variety of industrial applications.

COMMON APPLICATIONS
Feedback for Counters, PLCs \& Motors, Measuring for Packaging, Filling \& Material Handling Machines, Wire Winding, Film Extrusion

MODEL 711 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## NOTES:

## MODEL 711 CPR OPTIONS

| 0001 thru 0189* 0193 0198 0200 0205 0210 0240 <br> 0250 0256 0276 0298 0300 0305 0308 0315 | 0333 |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0336 | 0350 | 0360 | 0400 | 0480 | 0500 | 0512 | 0580 | 0597 |
| 0600 | 0700 | 0720 | 0800 | 0840 | 0960 | 1000 | 1024 | 1200 |
| 1250 | 1270 | 1500 | $1800^{*}$ | 2000 | 2048 | 2500 | 3000 | $3600^{*}$ |
| 4096 | 5000 | 6000 | $7200^{*}$ | 8192 | 10,000 |  |  |  |
| *Contact Customer Service for availability. |  |  |  |  |  |  |  |  |
| Contact Customer Service for other disk resolutions. Not all disk resolutions <br> available with all output types. |  |  |  |  |  |  |  |  |

[^8]
## MODEL 711 SPECIFICATIONS

Common to all cube housing styles.

Electrical
Input Voltage........... 4.75 to 28 VDC max for temperatures up to $85^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $85^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$.
Input Current.. 80 mA maximum with no output load Input Ripple.. 100 mV peak-to-peak at 0 to 100 kHz Incremental - Square wave with single channel
Output Types

Open Collector - 250 mA max per channel Pull-Up - Open Collector with 1.5 K ohm internal resistor, 250 mA max per channel
Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)

Housing .................... Black non-corrosive finished 6063-T6
aluminum Bearings....................Precision ABEC ball bearings

## STANDARD CUBE HOUSING (S, S1) SPECIFICATIONS

Mechanical
Shaft Type $\qquad$ .Single or double-ended (specify choice) Radial Loading.. 15 lb maximum ( 0.250 " diameter shaft) 40 lb maximum ( $0.375^{\mathrm{\prime} \mathrm{\prime}}$ diameter shaft)
Axial Loading. 10 lb maximum ( 0.250 " diameter shaft) 30 lb maximum ( $0.375^{\prime \prime}$ diameter shaft)
Starting Torque
. 0.13 oz-in typical for 0.250 " shaft 0.38 oz-in typical for 0.375 " shaft

Moment of Inertia ... $6.5 \times 10^{-6}$ oz-in-sec ${ }^{2}$
Weight. $\qquad$ 10 oz for standard housing

## WIRING TABLE

| For EPC-sup | mating cabl | fer to | ng | provide | with ca |  |  |  | Term. |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Function | Gland <br> Cable ${ }^{\dagger}$ Wire Color | $\begin{aligned} & \text { 5-pin } \\ & \text { M12 } \end{aligned}$ | 8-pin <br> M12 | $\begin{gathered} \text { 10-pin } \\ \text { MS } \end{gathered}$ | 7 pin MS <br> HV | $\begin{gathered} \text { 7-pin } \\ \text { MS } \\ \text { O,S } \\ \text { PP } \end{gathered}$ | 6-pin MS HV, No Index | 6-pin <br> MS <br> 0,S <br> PP | Block <br> HV, <br> No <br> Index | Term. Block 0,S HV,PP |
| Com | Black | 3 | 7 | F | F | F | A | A,F | 1 | 1,6 |
| +VDC | Red | 1 | 2 | D | D | D | B | B | 2 | 2 |
| A | White | 4 | 1 | A | A | A | C | D | 3 | 4 |
| $A^{\prime}$ | Brown | -- | 3 | H | C | -- | D | -- | 4 | -- |
| Case | -- | -- | -- | G | G | G | -- | -- | -- | -- |
| Shield | Bare | -- | -- | -- | -- | -- | -- | -- | -- | -- |

${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.

## WAVEFORM DIAGRAM

OUTPUTA $\square$

## CUBE PIVOT MOUNTING BRACKETS

176430-01 Single Pivot
176431-01 Double Pivot
176430-02 Spring Loaded Single Pivot
176431-02 Spring Loaded Double Pivot
Encoder sold separately

-6-32 UNC-2B 0.250 DEEP
$4 \times 90^{\circ} \quad 22.000$ B.C.
SAME MOUNTING HOLE PATTERN
IS ALSO PROVIDED ON THE
OPPOSITE END AND BASE

Cube Housing with $3 / 8^{\prime \prime}$ Shaft (6)

$4 \times 90^{\circ}$ ф2.000 B.C.
SAME MOUNTING HOLE PATTERN
IS ALSO PROVIDED ON THE
OPPOSITE END AND BASE


Dual Wheel

## Incremental Shaft Encoders

## MODEL 715



## FEATURES

## The Original Industry-Standard Cube

Versatile Housing Styles
Bi-Directional, Constant Pulse Width
Resolutions Available up to 10,000 CPR
The Model 715 Accu-Coder ${ }^{\text {TM }}$ is ideally suited for applications requiring bi-directional feedback with a constant pulse width. The Model 715 is available in two versions. The Model 715-1 provides output pulses for clockwise shaft rotation on one channel and pulses for counterclockwise rotation on another. The Model 715-2 provides output pulses for counting on one channel while the other channel indicates direction of rotation. Critical performance specifications for the most popular resolutions and advanced Opto-ASIC circuitry - a single chip design that eliminates many board level components - increases the reliability of an already dependable and durable encoder. With new options continually being added, the Model 715 excels in a wide variety of industrial applications.

## COMMON APPLICATIONS

Measuring for Cut-to-Length, Labeling \& Filling, Position Control, Motion Following, or Slaving Applications

## MODEL 715 ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


MODEL 715 PPR OPTIONS

| 0001 | thru 0189* | 0193 | 0198 | 0200 | 0205 | 0210 | 0240 | 0250 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0256 | 0276 | 0298 | 0300 | 0305 | 0308 | 0333 | 0336 | 0350 | 0360 |
| 0400 | 0480 | 0500 | 0512 | 0597 | 0600 | 0700 | 0720 | 0800 | 0840 |
| 0960 | 1000 | 1024 | 1200 | 1250 | 1270 | 1800 | 2000 | 2048 | 2500 |

2 x and 4 x , of all of the above resolutions are available
*Contact Customer Service for availability.
Contact Customer Service for other disk resolutions. Not all disk resolutions available with all output types

## NOTES:

1 Available with 0.250 " shaft only.
2 Only available with 6-pin MS or Screw Terminal Connector Types.
3 Only available with $5 / 16^{\prime \prime}, 0.3125^{\prime \prime}$ shaft.
4 Contact Customer Service for custom shaft lengths and diameters.
Standard housing only.
Standard or 5PY housing only.
7 HD10 housing only.
8 Not available for HD or EX housings.
9 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
10 For non-standard cable lengths, add a forward slash (/) plus cable length expressed in feet. Example: $\mathrm{G} / 6=6$ feet of cable.
11 Screw terminals available for HD and EX housings. Solder terminals available for S and S 1 housings.

## MODEL 715 SPECIFICATIONS

Common to All Cube Housing Styles

| Electrical | Rise Time................ Less than 1 microsecond |
| :---: | :---: |
| Input Voltage. $\qquad$ 4.75 to 28 VDC max for temperatures up to $85^{\circ} \mathrm{C}$ 4.75 to 24 VDC for temperatures between $85^{\circ}$ to $100^{\circ} \mathrm{C}$ | Accuracy. $\qquad$ Within $0.05^{\circ}$ mechanical from one cycle to any other cycle, or 3 arc minutes |
| Input Current .......... 80 mA maximum with no output load | Max Speed ............... 6000 RPM. Higher shaft speeds |
| Input Ripple............. 100 mV peak-to-peak at 0 to 100 kHz | achievable, contact Customer Service. |
| Output Format..........Incremental - Square wave with timed | Shaft Material .......... 303 Stainless Steel |
| Output Types $\qquad$ Open Collector - 250 mA max per channel | Housing .................... Black non-corrosive finished 6063-T6 |
| Pull-Up - Open collector with 1.5 K ohm internal resistor, 250 mA max per channel | Bearings ...................Precision ABEC ball bearings <br> Environmental <br> Operating Temp ....... 0 to $85^{\circ} \mathrm{C}$ |
| Max Frequency ........ 0 to 125 kHz | Storage Temp ........... $25^{\circ}$ to $85^{\circ} \mathrm{C}$ |
| Electrical Protection .. Reverse voltage and output | Humidity.................98\% RH non-condensing |
| stained | Vibration.................. 10 g @ 58 to 500 Hz |
| reverse voltage may result in permanent damage. | Shock..................... 50 g @ 11 ms duration |

## STANDARD CUBE HOUSING (S, S1) SPECIFICATIONS

## Mechanical

Shaft Type $\qquad$ Single or double-ended (specify choice) Radial Loading 15 lb maximum ( 0.250 " diameter shaft) 40 lb maximum ( $0.3755^{\prime \prime}$ diameter shaft) Axial Loading. 10 lb maximum ( 0.250 " diameter shaft) 30 lb maximum ( $0.375^{\mathrm{l}}$ diameter shaft)
Starting Torque ......... 0.13 oz-in typical for 0.250 " shaft 0.38 oz-in typical for 0.375 " shaft

Moment of Inertia ... $6.5 \times 10^{-6}$ oz-in-sec ${ }^{2}$ Weight

## STANDARD CUBE HOUSING (S, S1)

Cube Housing with $1 / 4^{\prime \prime}$ Shaft (4)


SAME MOUNTING HOLE PATTERN
IS ALSO PROVIDED ON THE
OPPOSITE END AND BASE

Cube Housing with $3 / 8^{\prime \prime}$ Shaft (6)
 Trim back and insulate unused wires.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable

| Function | Gland Cable $^{\dagger}$ <br> Wire Color | 5-pin M12 | 8-pin M12 | 6-pin MS | Term. <br> Block |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | A,F | 1,6 |
| +VDC | Red | 1 | 2 | B | 2 |
| A | White | 4 | 1 | D | 4 |
| B | Blue | 2 | 4 | E | 5 |
| Shield | Bare | -- | -- | -- | -- |

${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.

WAVEFORM DIAGRAMS
Model 715-1


Model 715-1 Bi-Directional Encoder
The 715-1 provides two output channels. A constant pulse width is generated on one channel with clockwise shaft rotation, and on the other channel with counterclockwise shaft rotation. Specify PPR in any even numbered value between 2 and 10,000 . Specify any pulse width from 10 microseconds to 100 milliseconds and pulse polarity. Some options require Heavy Duty housing. The Line Driver output option is not available.

## CUBE PIVOT MOUNTING BRACKETS

176430-01 Single Pivot
176431-01 Double Pivot
176430-02 Spring Loaded Single Pivot 176431-02 Spring Loaded Double Pivot Encoder sold separately.


Dual Wheel


Single Wheel (shown with Torsion Spring)

Model 715-2


## Model 715-2 Bi-Directional Encoder

The 715-2 provides two output channels. One channel has a constant pulse width output regardless of shaft rotation direction. The other channel indicates direction with logic level " 1 " for clockwise shaft rotation, and level " 0 " for counter-clockwise shaft rotation. Options are the same as for the Model 715-1.


## FEATURES

## The Original Industry-Standard Cube

Five Versatile Housing Styles

## Quadrature Output

## New Resolutions Available to 10,000 CPR

The Model 716 Accu-Coder ${ }^{\text {TM }}$ is ideally suited for applications requiring a quadrature output. Designed for compatibility with most programmable controllers, electronic counters, motion controllers, and motor drives, it is ideally suited for industrial applications where it is important that the direction of rotation be known. Critical performance specifications for the most popular resolutions and advanced Opto-ASIC circuitry - a single chip design that eliminates many board level components - increase the reliability of an already dependable and durable encoder. With new options continually being added, the Model 716 excels in a wide variety of industrial applications.

## COMMON APPLICATIONS

Feedback for Counters, PLCs \& Motors, Cut-to-Length, Labeling, Measuring for Packaging, Filling \& Material Handling Machines, Wire Winding, Film Extrusion

## MODEL 716 ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 716 CPR OPTIONS

| 0001 | thru 0189* | 0193 | 0198 | 0200 | 0205 | 0210 | 0240 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0250 | 0256 | 0276 | 0298 | 0300 | 0305 | 0308 | 0315 | 0333 |
| 0336 | 0350 | 0360 | 0400 | 0480 | 0500 | 0512 | 0580 | 0597 |
| 0600 | 0700 | 0720 | 0800 | 0840 | 0960 | 1000 | 1024 | 1200 |
| 1250 | 1270 | 1500 | $1800^{*}$ | 2000 | 2048 | 2500 | 3000 | $3600^{*}$ |
| 4096 | 5000 | 6000 | $7200^{*}$ | 8192 | 10,000 |  |  |  |

409650006000 7200* 8192 10,000
*Contact Customer Service for availability.
Contact Customer Service for other disk resolutions. Not all disk resolutions available with all output types.

## NOTES:

1 Complete only if Index Pulse option is selected.
2 Available with 0.250 " shaft only.
Only available with 6-pin MS or Screw Terminal Connector Types.
Only available with $5 / 16^{\prime \prime}$ ( $0.3125^{\prime \prime}$ ) shaft.
5 Contact Customer Service for custom shaft lengths and diameters.
6 Standard housing only.
7 Standard or 5PY housing only.
8 HD10 housing only.
9 Not available for HD or EX housings.
10 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
11 For non-standard cable lengths, add a forward slash ( $/$ ) plus cable length expressed in feet. Example: $\mathrm{G} / 6=6$ feet of cable. For CPR > 2500. Standard cable length only.
12 Screw terminals available for HD and EX housings. Solder terminals available for S and S 1 housings.

## MODEL 716 SPECIFICATIONS

Common to All Cube Housing Styles

Electrical
Input Voltage............ 4.75 to 28 VDC max for temperature up to $85^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $85^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$.
Input Current Input Ripple. $\qquad$ 80 mA maximum with no output load Output Format.. 100 mV peak-to-peak at 0 to 100 kHz . Incremental - Square wave with single channel
Output Types.................Open Collector - 250 mA max per channel Pull-Up - Open collector with 1.5 K ohm internal resistor, 250 mA max per channel
Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)

| Max Frequency......... 1 to 2500 CPR 125 kHz , 2501 to 5000 |  |
| :---: | :---: |
|  | CPR 250 kHz , 5001 to 10,000 CPR |
|  | 500 kHz |
| Electrical Protection. | Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage. |
| Index.................. | Once per revolution, $180^{\circ}$ electrical gated to Channel A. See Waveform Diagrams. |
| Quadrature......... | $67.5^{\circ}$ electrical or better is typical, $54^{\circ}$ |
| Edge Separation | electrical minimum at temperatures $>99^{\circ} \mathrm{C}$ |
| Rise Time...... | Less than 1 microsecond |
| Accuracy ................. | Within $0.05^{\circ}$ mechanical from one cycle to any other cycle, or 3 arc minutes |

Mechanical
Max Speed ............... 6000 RPM. Higher shaft speeds
achievable, contact Customer Service.
Shaft Material ........... 303 Stainless Steel
Housing ................ Black non-corrosive finished 6063-T6
aluminum
Bearings................... Precision ABEC ball bearings

Environmental
Operating Temp ....... $0^{\circ}$ to $85^{\circ} \mathrm{C}$
Storage Temp ........... $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity...................98\% RH non-condensing
Vibration.................. 10 g @ 58 to 500 Hz
Shock..
$50 \mathrm{~g} @ 11 \mathrm{~ms}$ duration

## STANDARD CUBE HOUSING (S, S1) SPECIFICATIONS

| Mechanical |
| :---: |
| Shaft Type ...............Single or double-ended (specify choice) |
| Radial Loading......... 15 lb maximum ( 0.250 " diameter shaft) |
| 40 lb maximum ( 0.375 " diameter shaft) |
| Axial Loading............ 10 lb maximum ( 0.250 " diameter shaft) |
| 30 lb maximum ( 0.375 " diameter shaft) |
| Starting Torque ........ 0.13 oz-in typical for 0.250" shaft |
| 0.38 oz-in typical for 0.375 " shaft |
| Moment of Inertia ...6.5 x $10^{-6} \mathrm{oz}$-in-sec ${ }^{2}$ |
| Weight................... 10 oz for standard housing |

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Cable ${ }^{\top}$ <br> Wire Color | 5-pin M12 | 8-pin <br> M12 | $\begin{gathered} \text { 10-pin } \\ \text { MS } \\ \text { HV } \end{gathered}$ | $\begin{aligned} & \text { 7-pin } \\ & \text { MS } \\ & \text { HV } \end{aligned}$ | $\begin{aligned} & \text { 7-pin } \\ & \text { MS } \\ & \text { 0,S,PP } \end{aligned}$ | 6-pin MS <br> HV,No Index | $\begin{gathered} \text { 6-pin MS } \\ 0, S, P \mathrm{P} \end{gathered}$ | Term. Block HV,No Index | Term. Block 0,S,PP |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A | A, F | 1 | 1,6 |
| +VDC | Red | 1 | 2 | D | D | D | B | B | 2 | 2 |
| A | White | 4 | 1 | A | A | A | C | D | 3 | 4 |
| $\mathrm{A}^{\prime}$ | Brown | -- | 3 | H | C | -- | D | -- | 4 | -- |
| B | Blue | 2 | 4 | B | B | B | E | E | 5 | 5 |
| B' | Violet | -- | 5 | 1 | E | -- | F | -- | 6 | -- |
| Z | Orange | 5 | 6 | C | -- | C | -- | C | -- | 3 |
| Z' | Yellow | -- | 8 | J | -- | -- | -- | -- | -- | -- |
| Case | Green | -- | -- | G | G | G | -- | -- | -- | -- |
| Shield | Bare | -- | -- | -- | -- | -- | -- | -- | -- | -- |

${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.

## STANDARD CUBE HOUSING (S, S1)

Cube Housing with $1 / 4^{\prime \prime}$ Shaft (4)


6-32 UNC-2B 0.250 DEEP $4 \times 90^{\circ} \phi 2.000$ B.C.
SAME MOUNTING HOLE PATTERN IS ALSO PROVIDED ON THE OPPOSITE END AND BASE

Cube Housing with $3 / 8^{\prime \prime}$ Shaft (6)



CUBE PIVOT MOUNTING BRACKETS


Dual Wheel


Single Wheel (shown with Torsion Spring)

176430-01 Single Pivot 176431-01 Double Pivot 176430-02 Spring Loaded Single Pivot 176431-02 Spring Loaded Double Pivot Encoder sold separately.

## WAVEFORM DIAGRAMS

Line Driver and Push-Pull


CLOCKWISE ROTATION AS VIEWED FROM THE MOUNTING FACE
note: All Degree refrences are electrical degrees.
E: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES.
WAVEFRRM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS WAVEFORM SHOWN WITH OPTIO
A. Bi,
İ FOR HV OUTPUT ONLY.

Open Collector and Pull-Up


CLOCKWISE ROTATIONAS VIEWED FROM THE MOUNTNING FACE

## Incremental Shaft Encoders

## CUBE HOUSINGS

## INDUSTRIAL CUBE HOUSING (IND12)

This more robust unit meets requirements between Standard and Heavy Duty housings while retaining the Cube design. The Industrial 12 (IND12) model features an IP66 shaft seal. The tough, sealed aluminum housing has a wall thickness of 0.187 " and offers greater protection from wash down, sprays, dust, moisture, shock, vibration, and other hazards found in industrial environments.

## INDUSTRIAL CUBE HOUSING (IND12) SPECIFICATIONS

Refer to all Standard Cube Housing specifications except as follows:

## Mechanical

Shaft Size. $\qquad$ 0.375 " diameter

Shaft Type Single- or Double-Ended Shaft Available Radial Loading. 40 lb Maximum
Axial Loading 30 lb Maximum
Starting Torque ........ 3 oz-in Starting Torque w/IP66 Shaft Seal


## HEAVY DUTY CUBE HOUSING (HD12)

The Heavy Duty housing uses a separate $0.375^{\prime \prime}$ diameter external shaft and bearing assembly to rotate the shaft of an internally mounted Cube Housing. This provides mechanical isolation from external loads and stress. A flexible coupling between the external shaft and the encoder protects the internal unit from axial and radial loading. The 0.250 " aluminum walls protect the encoder from external shock, vibration, and the outside environment.

## Heavy Duty Housing Options

HD 1 Heavy Duty 3" x 6" housing
HD 3 Heavy Duty w/conduit connector (threaded for 0.500" NPT Conduit) and terminal strip HD 5 Heavy Duty w/10 mm outer bearing
HD 12* Heavy Duty w/IP66 rated outer shaft seal
HD 14* Heavy Duty w/IP66 rated outer shaft seal, conduit connector
(threaded for 0.500" NPT Conduit), and terminal strip
*These units have an outer boss diameter of 1.000 "

## HEAVY DUTY CUBE HOUSING (HD12) SPECIFICATIONS

Refer to all cube specifications except as follows: Mechanical
Max Speed ............... 6000 RPM
Shaft Size. $\qquad$ 0.375"

Rotation....................Either direction
Radial Loading.. Axial Loading .40 lb maximum ( 50 lb for HD 5)

Bearings.... .30 lb maximum ( 35 lb for HD 5)

Starting Torque Precision ABEC ball bearings
........ 1 oz-in; 3 oz-in w/IP66 seal
Mounting ... Tapped holes face and base
Weight.. .3 .25 lb

## ULTRA HEAVY DUTY CUBE HOUSING (HD10)

The HD 10 Ultra Heavy Duty encoder is designed for use in applications with severe shaft loading conditions. The HD 10 offers two shaft sizes: 0.500 " and 0.625 ". Shaft material is 303 stainless steel. Bearings are conservatively rated at 95 lb radial and 60 lb axial shaft loading. IP66 shaft seal is standard on all units. The HD 10 Ultra Heavy Duty housing uses a larger external shaft and R10 bearing assembly to rotate the shaft of an internally mounted Cube Housing. This provides mechanical isolation from external loads and stress. A flexible coupling between the external shaft and the encoder protects the internal unit from axial and radial loading. The 0.250 " aluminum walls protect the encoder from external shock, vibration, and the outside environment.


## ULTRA HEAVY DUTY CUBE HOUSING (HD 10) SPECIFICATIONS

## Mechanical

Max Speed ............... 6000 RPM
Shaft Size.................0.500" or 0.625"
Rotation... $\qquad$ Either direction
Radial Loading.......... 95 lb operating
Axial Loading 60 lb operating
Bearings.. .ABEC precision ball bearings Bearing Life 15,000 hours at rated load Starting Torque ........ 3 oz-in IP66 rated
Mounting ................. Tapped holes face and base
Weight.. 3.85 lb

## ULTRA HEAVY DUTY CUBE HOUSING (HD10)-CONT'D



All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified

## EXPLOSION-PROOF HOUSING (EX)

An explosion-proof housing is available for installing the Cube Series Accu-Coder ${ }^{\text {TM }}$ in hazardous locations. The Cube Series encoder is mounted within the explosion-proof housing and is coupled to the $0.375^{\prime \prime}$ shaft assembly by a flexible shaft coupling. This decreases radial and axial loading on the internal encoder shaft and bearings to ensure long life. Electrical connection to the Accu-Coder ${ }^{\text {TM }}$ is by an internal barrier terminal strip. A threaded hole for 0.500 " NPT conduit is provided.


## EXPLOSION-PROOF HOUSING (EX) SPECIFICATIONS

The explosion-proof housing is designed to meet the following:
NEC Class 1, Groups C and D
NEC Class 2, Groups E, F, and G
UL Standard 1203
Class 1, Division 1, Groups C and D
Class 2, Division 1, Groups E, F, and G
CSA Standard C 22.2 No. 30-M 1986
NEMA 7 and NEMA 9
Refer to all cube specifications except as follows:
Mechanical
Max Speed ............... 4000 RPM
Radial Loading.......... 30 lb operating
Axial Loading............ 10 lb operating
Weight..................... 6 lb
Finish ........................Unpainted Aluminum

## CUBE SERIES OPTIONAL 5PY ADAPTER (175443)

The all aluminum optional 5PY adapter allows any standard housing Cube Series encoder to replace DC tachometer technology. The 5PY adapter is interchangeable with any 5PY tach generator.


## Incremental Shaft Encoders

MODEL 15 S


Ø1.5"

## FEATURES

## High Performance Economical Encoder

## Low Profile - Less Than 1.0" ( 25.4 mm ) Height and 1.5" (38 mm) Diameter Extended Temperature Operating Ranges Available Up to 12 Pole Commutation Optional (for Brushless Motor Control)

The Model 15S Accu-Coder ${ }^{\text {TM }}$ offers a high performance feedback solution in a low profile package, making the Model 15 S ideal for commercial and light-duty industrial applications. This industry standard Size 15 (1.5" diameter) encoder features a precision bearing set, sealing available to IP64, a durable stainless steel shaft, and a selection of servo, flange, and face mount options. The Model 15 S may also be specified with features such as extended operating temperatures from $-40^{\circ} \mathrm{C}$ to $120^{\circ} \mathrm{C}$, and up to 12 pole commutation for brushless motor control. The Model 15S features EPC's Opto-ASIC circuitry for a clean, reliable signal. Its durable yet economical design makes it an ideal encoder for high precision OEM applications.
COMMON APPLICATIONS
Servo Motor Control, Robotics, Medical Diagnostic Equipment, Specialty Assembly Machines, Digital Plotters, Printers, Typesetting Equipment

MODEL 15S ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 15S CPR OPTIONS

| 0001 thru 0189* | 0198 | 0200 | 0250 | 0256 | 0300 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0315 | 0360 | 0400 | 0500 | 0512 | 0580 | 0600 |
| 0750 | 0800 | 1000 | 1024 | 1200 | 1250 | 1500 |
| 1800 | 2000 | 2048 | 2500 | 2540 | 3000 | 3600 |
| 4000 | 4096 | 5000 | 6000 | 7200 | 8192 | 10,000 |

New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available values. Special disk resolutions are available upon request and may be subject to a one-time NRE fee.

## NOTES:

1 Contact Customer Service for additional options not shown.
2 Not available in all configurations, and not available with V1 Input Voltage. Contact Customer Service for availability.
3 Contact Customer Service for non-standard index gating or phase relationship options, or see Quadrature Phasing and Index Gating Options at encoder.com.
4 Reverse Quadrature not available with PU output type.
5 With Input Voltage above 16 VDC, operating temperature is limited to $85^{\circ} \mathrm{C}$.
6 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
7 For non-standard English cable lengths enter ' $F$ ' plus cable length expressed in feet. Example: F06 = 6 feet of cable. For non-standard metric cable lengths enter ' $M$ ' plus cable length expressed in meters. Example: M06 = 6 meters of cable. Frequency above 300 kHz standard cable lengths only.
8 Not available with commutation. 5-pin not available with Line Driver (HV, OD, LO) outputs. Additional cable lengths available. Please contact Customer Service.
9 Pin Header available with 5 VDC Input Voltage, HV Line Driver and standard quadrature phasing only. Not available with CE Certification. IP50 sealing option only.
10 Only available with 5 VDC Input Voltage.
11 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL 15S SPECIFICATIONS

## Electrical



## Mechanical

Max Shaft Speed ...... 8000 RPM. Higher speeds may be achievable, contact Customer Service.
Shaft Material .........Stainless Steel
Radial Shaft Load .... 5 lb max. Rated load of 2 to 3 lb for bearing life of $1.2 \times 10^{10}$ revolutions
Axial Shaft Load ....... 5 lb max. Rated load of 2 to 3 lb for bearing life of $1.2 \times 10^{10}$ revolutions
Starting Torque ........IP50- 0.05 oz-in IP64- 0.4 oz-in
Moment of Inertia ... $6.7 \times 10^{-5} \mathrm{oz}-\mathrm{in}-\mathrm{sec}^{2}\left(4.8 \mathrm{gm}-\mathrm{cm}^{2}\right)$
Weight. 3 oz typical

## Environmental

Storage Temp ............ $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity...................98\% RH non-condensing
Vibration................... 10 g @ 58 to 500 Hz
Shock....................... 80 g @ 11 ms duration
Sealing. IP50 standard; IP64 available

## MODEL 15S STANDARD SERVO MOUNT M1



MODEL 15S SERVO MOUNT M2 \& M9*
*M9 mount includes a 0.750 " boss


MODEL 15S SERVO MOUNT M5


MODEL 15S SERVO MOUNT M6


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01$ " unless otherwise specified. Metric dimensions are given in brackets [ mm ].

## Incremental Shaft Encoders

## MODEL 15 S

## MODEL 15S SERVO MOUNT M7

CABLE LENGTH
18" [457] STANDARD


## MODEL 15S SERVO MOUNT M4



## MODEL 15S SQUARE FLANGE M3



## MODEL 15S SERVO MOUNT M8



All dimensions are in inches with a tolerance of $\pm 0.005$ " or $\pm 0.01$ " unless otherwise specified. Metric dimensions are given in brackets [mm].

## WAVEFORM DIAGRAMS



15-PIN HEADER


WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland <br> Cable ${ }^{\dagger}$ <br> Wire Color | 5-pin M12** | 8-pin M12** | 15-pin Header |
| :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | 1 |
| +VDC | White | 1 | 2 | 2 |
| A | Brown | 4 | 1 | 4 |
| $A^{\prime}$ | Yellow | -- | 3 | 3 |
| B | Red | 2 | 4 | 6 |
| $B^{\prime}$ | Green | -- | 5 | 5 |
| Z | Orange | 5 | 6 | 7 |
| Z' | Blue | -- | 8 | 8 |
| U | Violet | -- | -- | 10 |
| U' | Gray | -- | -- | 9 |
| V | Pink | -- | -- | 14 |
| V' | Tan | -- | -- | 13 |
| W | Red/Green | -- | -- | 12 |
| W' | Red/Yellow | -- | -- | 11 |
| Shield | Bare* | -- | -- | -- |

${ }^{*}$ CE Option: Cable shield (bare wire) is connected to internal case.
${ }^{\dagger}$ Standard cable for non-commutated models is 24 AWG; for commutated units, conductors are 28 AWG.
**CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

## Incremental Shaft Encoders

MODEL 755 A


## FEATURES

## Miniature Size (1.5" Diameter)

## Up to 30,000 CPR

Servo or Flange Mounting
1 MHz Frequency Response Available
Extended Temperature Operating Range Available
The Model 755A Size 15 Accu-Coder ${ }^{\text {TM }}$ is ideal for applications requiring a small, high precision, high performance encoder. Approximately 1.5 " in diameter and $1.5^{\prime \prime}$ long, it will fit where many encoders cannot. Designed with all-metal construction and shielded ball bearings, it will provide years of trouble-free use. The standard servo mount (S) version is available with a variety of shaft sizes and lengths. Three additional servo style mounts (S1, S2, S3) are also available. The optional flange mounting (MF) is ideal for applications requiring a bolt-on, high precision encoder. With its high reliability and quick delivery, the Model 755A encoder is the perfect replacement encoder in this size category.

COMMON APPLICATIONS
Robotics, Assembly Machines, Motor-Mounted Feedback, Phototypesetters, Printers \& Digital Plotters, Elevator Controls, Medical Diagnostic Equipment

MODEL 755A ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


MODEL 755A CPR OPTIONS

| 0001* | 0002* | 0004* | 0005* | 0006* | 0007* | 0008* | 0010* | 0011* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0012* | 0014* | 0020 | 0021* | 0024* | 0025* | 0028* | 0030* | 0032* |
| 0033* | 0034* | 0035* | 0038* | 0040* | 0042* | 0045* | 0050* | 0060 |
| 0064* | 0100 | 0120 | 0125 | 0128* | 0144* | 0150* | 0160* | 0192* |
| 0200 | 0240* | 0250 | 0254* | 0256* | 0300 | 0333* | 0336* | 0360 |
| 0400 | 0500 | 0512 | 0600 | 0625* | 0635 | 0665* | 0720 | 0768* |
| 0800 | 0889 | 1000 | 1024 | 1200 | 1201*a | 1203*a | 1204*a | $1250^{\text {a }}$ |
| $1270^{\text {a }}$ | 1440 | 1500 | 1800 | 2000 | 2048 | $2400{ }^{\text {a }}$ | 2500 | $2540^{\text {a }}$ |
| $2880{ }^{\text {a }}$ | $3000^{\text {a }}$ | $3600^{\text {a }}$ | $4000^{\text {a }}$ | $4096{ }^{\text {a }}$ | $5000^{\text {a }}$ | $6000{ }^{\text {a }}$ | $7200^{\text {a }}$ | $7500{ }^{\text {a }}$ |
| $9000^{\text {a }}$ | 10,000 ${ }^{\text {a }}$ | 10,240 ${ }^{\text {a }}$ | 12,000 ${ }^{\text {a }}$ | 12,500 ${ }^{\text {a }}$ | 14,400 ${ }^{\text {a }}$ | 15,000 ${ }^{\text {a }}$ | 18,000 ${ }^{\text {a }}$ | 20,000 ${ }^{\text {a }}$ |
| 20,480 ${ }^{\text {a }}$ | 25,000 ${ }^{\text {a }}$ | 30,000 ${ }^{\text {a }}$ |  |  |  |  |  |  |
| *Contact Customer Service for High Temperature Option (H). <br> aHigh Temperature Option (H) limited to $85^{\circ} \mathrm{C}$ maximum for these CPR options. |  |  |  |  |  |  |  |  |
| New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available CPR values. Special disk resolutions are available upon request. A one-time NRE fee may apply. |  |  |  |  |  |  |  |  |

NOTES:
1 Contact Customer Service for additional options.
2 Low temperature option not available with resolutions of 3000 CPR or higher.
$30^{\circ}$ to $85^{\circ} \mathrm{C}$ for certain resolutions, see CPR Options.
4 Contact Customer Service for index gating options.
524 VDC max for high temperature option.
6 5-pin not available with Line Driver (HV, H5) outputs.
7 Standard temperature, 60 to 3000 CPR only. Not available with 2540 CPR.
8 H5 and P5 outputs are not available with CE option.
9 Standard cable lengths only. For details, please refer to Technical Bulletin
TB116: Noise and Signal Distortion Considerations at encoder.com.
10 For mating connectors, cables, and cordsets see Accessories at encoder. com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
11 For non-standard cable lengths, add a forward slash (I) plus cable length expressed in feet. Example: $S / 6=6$ feet of cable.
12 Additional cable lengths available. Please consult Customer Service.
13 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL 755A SPECIFICATIONS

## Electrical

Input Voltage............ 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$
Input Current ........... 100 mA max with no output load Input Ripple.............. 100 mV peak-to-peak at 0 to 100 kHz
Output Format ......... Incremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the encoder mounting face. See Waveform Diagrams.
Output Types............ Open Collector - 100 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index. Occurs once per revolution. The index for units $>3000 \mathrm{CPR}$ is $90^{\circ}$ gated to Outputs A and B. See Waveform Diagrams.
Max Frequency ........ 100 kHz std; Up to 1 MHz optional. (See Ordering Guide for availability)
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2
Symmetry................. 1 to 6000 CPR: $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical at 100 kHz output 6001 to 20,480 CPR: $180^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Quad Phasing........... 1 to 6000 CPR: $90^{\circ}\left( \pm 22.5^{\circ}\right)$ electrical at 100 kHz output 6001 to 20,480 CPR: $90^{\circ}\left( \pm 36^{\circ}\right)$
Min Edge Sep ............ 1 to 6000 CPR: $67.5^{\circ}$ electrical at 100 kHz output 6001 to 20,480 CPR: $54^{\circ}$ electrical >20,480 CPR: $50^{\circ}$ electrical
Rise Time $\qquad$ . Less than 1 microsecond
Accuracy..................Instrument and Quadrature Error: For 200 to 1999 CPR, $0.017^{\circ}$ mechanical (1.0 arc minutes) from one cycle to any other cycle. For 2000 to $3000 \mathrm{CPR}, 0.01^{\circ}$ mechanical ( 0.6 arc minutes) from one cycle to any other cycle. Interpolation error (units > 3000 CPR only) within $0.005^{\circ}$ mechanical. (Total Optical Encoder Error = Instrument + Quadrature + Interpolation)

## Mechanical

Max Speed ............... 7500 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Shaft Rotation .......... Bi-directional
Radial Shaft Load ..... 5 lb
Axial Shaft Load ....... 3 lb
Starting Torque ........0.14 oz-in typical 4.0 oz-in typical for $-40^{\circ} \mathrm{C}$ operation

Moment of Inertia ... $2.8 \times 10^{-4} \mathrm{oz}$-in-sec ${ }^{2}$
Housing ................... Black non-corrosive finish
Bearings.................... Precision ABEC ball bearings
Weight. 3.10 oz servo mount, typical

## Environmental

Storage Temp ........... $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity................... $98 \%$ RH non-condensin
Vibration.................. 10 g @ 58 to 500 Hz
Shock.
$50 \mathrm{~g} @ 11$ ms duration

MODEL 755A STANDARD SERVO MOUNT (S)
-M3 0.30 [7.6] DEEP
$3 \times 120^{\circ} \emptyset 1.100$ B.C.



## MODEL 755A SERVO MOUNTS (S1 \& S2)



S2 Pictured below has a 0.750" Boss. S1 has a 0.547 " Boss. See www.encoder.com to download drawings


## MODEL 755A SERVO MOUNT (S3)



MODEL 755A 1.575" SQUARE FLANGE (MF)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$. unless otherwise specified metric dimensions are given in brackets [mm].

WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Gland <br> Cable ${ }^{\dagger}$ <br> Wire Color | Term. <br> Block | 8-pin <br> Molex | 5-pin M12** | 8-pin <br> M12** |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 7 | 2 | 3 | 7 |
| +VDC | White | 8 | 1 | 1 | 2 |
| A | Brown | 1 | 8 | 4 | 1 |
| $A^{\prime}$ | Yellow | 2 | 7 | -- | 3 |
| B | Red | 3 | 4 | 2 | 4 |
| $B^{\prime}$ | Green | 4 | 3 | -- | 5 |
| Z | Orange | 6 | 6 | 5 | 6 |
| Z' | Blue | 5 | 5 | -- | 8 |
| Shield | Bare* | -- | -- | -- | -- |

*CE Option: Cable shield (bare wire) is connected to internal case
${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.
${ }^{* *}$ CE Option: Use cable cordset with shield connected to M12 connector coupling nut.


WAVEFORM DIAGRAMS Open Collector and Pull-Up


## Incremental Shaft Encoders

## MODEL 702


ø2.0"

## FEATURES

## Standard Size 20 Package (2x2) <br> Flange and Servo Mounting <br> Up to 30,000 CPR <br> 80 lb Maximum Axial and Radial Shaft Loading IP67 Sealing Available

The Model 702 Size 20 Accu-Coder ${ }^{\text {TM }}$ is a heavy duty, extremely rugged, reliable, yet compact industry standard 2" diameter encoder, designed for harsh factory and plant floor environments. The double shielded ball bearings are rated at 80 lb maximum axial and radial shaft loading to ensure a long operating life. Made to withstand the harsh effects of the real world, both the flange and servo models are rated IP67 with the optional heavy duty shaft seal. With a variety of mounting options in both the flange and servo models, the Model 702 is ideal for both new applications and replacements. If you need an encoder that won't let you down, the Model 702 is it.
COMMON APPLICATIONS
Motion Control Feedback, Conveyors, Elevator Controls, Machine Control, Food Processing, Process Control, Robotics, Material Handling, Textile Machines

MODEL 702 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


| M | 22 | CPR | PTIO |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0001* | 0002* | 0004* | 0005* | 0006* | 0007* | 0008* | 0010* 0011* |
| 0012* | 0014* | 0020 | 0021* | 0024* | 0025* | 0028* | 0030* 0032* |
| 0033* | 0034* | 0035* | 0038* | 0040* | 0042* | 0045* | 0050* 0060 |
| 0064* | 0100 | 0120 | 0125 | 0128* | 0144* | 0150* | 0160* 0192* |
| 0200 | 0240* | 0250 | 0254* | 0256* | 0300 | 0333* | 03360360 |
| 0400 | 0500 | 0512 | 0600 | 0625* | 0635 | 0665* | 0720 0768* |
| 0800 | 0889 | 1000 | 1024 | 1200 | 1201*a | 1203*a | 1204*a 1250 ${ }^{\text {a }}$ |
| $1270{ }^{\text {a }}$ | 1440 | 1500 | 1800 | 2000 | 2048 | $2400{ }^{\text {a }}$ | $25002540^{\text {a }}$ |
| $2880^{\text {a }}$ | $3000^{\text {a }}$ | $3600^{\text {a }}$ | $4000^{\text {a }}$ | 4096 ${ }^{\text {a }}$ | $5000^{\text {a }}$ | $6000^{\text {a }}$ | $7200^{\text {a }} 7500^{\text {a }}$ |
| $9000^{\text {a }}$ | 10,000a | 10,240 ${ }^{\text {a }}$ | 12,000 ${ }^{\text {a }}$ | 12,500 ${ }^{\text {a }}$ | 14,400 ${ }^{\text {a }}$ | 15,000 ${ }^{\text {a }}$ | 18,000 ${ }^{\text {a }}$ |
| 20,000 ${ }^{\text {a }}$ | 20,480 ${ }^{\text {a }}$ | 25,000 ${ }^{\text {a }}$ | 30,000 ${ }^{\text {a }}$ |  |  |  |  |

*Contact Customer Service for High Temperature Option.
aHigh Temperature Option (H) limited to $85^{\circ} \mathrm{C}$ maximum for these CPR options.
New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available CPR values. Special disk resolutions are available upon request. A one-time NRE fee may apply.

NOTES:
Contact Customer Service for additional options.
Shaft with Size 25 Mounting Adapter, J or K mounting only. Low temperature option not available with resolutions of 3000 CPR or higher. $0^{\circ}$ to $85^{\circ} \mathrm{C}$ for certain resolutions, see CPR Options. Contact Customer Service for non-standard index gating options.
24 VDC max for high temperature option.
7 Line Driver not available with 5 -pin M12 or 6-pin MS connector. Available with 7-pin MS connector only without Index Z.
8 Standard temperature, 60 to 3000 CPR only. Not available with 2540 CPR.
9 H5 and P5 outputs are not available with CE option, or any End Mount MS Connector.
10 Standard cable lengths only. For details, please refer to Technical Bulletin TB116: Noise and Signal Distortion Considerations at encoder.com.
11 For mating connectors, cables, and cordsets see Accesssories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
12 For non-standard cable lengths, add a forward slash (I) plus cable length expressed in feet. Example: $\mathrm{G} / 6=6$ feet of cable.
13 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL 702 SPECIFICATIONS

## Electrical

Input Voltage........... 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$ 4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$
Input Current
Input Ripple .. 100 mA max with no output load Output Format. 100 mV peak-to-peak at 0 to 100 kHz Incremental - Two square waves in quadrature with channel $A$ leading $B$ for clockwise shaft rotation, as viewed from the encoder mounting face. See Waveform Diagrams.
Output Types ............ Open Collector - 100 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
$\qquad$ Occurs once per revolution. The index for units $>3000$ CPR is $90^{\circ}$ gated to Outputs A and B. See Waveform Diagrams.
Max Frequency... Up to 1 MHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity ........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2
Symmetry ................. 1 to 6000 CPR: $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical at 100 kHz output 6001 to 20,480 CPR: $180^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Quad Phasing............ 1 to 6000 CPR: $90^{\circ}\left( \pm 22.5^{\circ}\right)$ electrical at 100 kHz output 6001 to 20,480 CPR: $90^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Min Edge Sep.............. 1 to 6000 CPR: $67.5^{\circ}$ electrical at 100 kHz output 6001 to 20,480 CPR: $54^{\circ}$ electrical $>20,480$ CPR: $50^{\circ}$ electrical
Rise Time $\qquad$ Less than 1 microsecond
Accuracy. $\qquad$ Instrument and Quadrature Error: For 200 to 1999 CPR, $0.017^{\circ}$ mechanical ( 1.0 arc minutes) from one cycle to any other cycle. For 2000 to $3000 \mathrm{CPR}, 0.01^{\circ}$ mechanical ( 0.6 arc minutes) from one cycle to any other cycle. Interpolation error (units > 3000 CPR only) within $0.005^{\circ}$ mechanical. (Total Optical Encoder Error = Instrument + Quadrature + Interpolation)

## Mechanical

Max Shaft Speed ...... 8000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Shaft Rotation.. Bi-directional
Radial Shaft Load......
80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Axial Shaft Load........ 80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Starting Torque ......... 1.0 oz-in typical with IP64 seal or no seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typical with IP67 shaft seal

Moment of Inertia.... $5.2 \times 10^{-4}$ oz-in-sec ${ }^{2}$
Housing..................... Black non-corrosive finish
Bearings................... Precision ABEC ball bearings
Weight....................... 11 oz typical

## Environmental

Storage Temp ........... $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity... .. $98 \%$ RH non-condensing
Vibration. $.20 \mathrm{~g} @ 58$ to 500 Hz
Shock 75 g @ 11 ms duration
Sealing. $\qquad$ IP50 standard; IP64, IP66 or IP67 optional

MODEL 702 2.0" SERVO MOUNT (S)


MODEL 702 2.0" SERVO MOUNT (C)


MODEL 702 2.0" SERVO MOUNT (P)


OPTIONAL PILOTS FOR FLANGE AND SERVO MOUNTS
( $G, T, D, R$ )

(L, U, E, Q)


All dimensions are in inches with a tolerance of $\pm 0.005$ " or $\pm 0.01$ " unless otherwise specified.

## Incremental Shaft Encoders

## MODEL 702

MODEL 702 2.0" FLANGE MOUNT (F)


MODEL 702 WITH 2.5" FLANGE MOUNT (K)


MODEL 702 WITH 2.5" SERVO MOUNT (J)


All dimensions are in inches with a tolerance of $\pm 0.005$ " or $\pm 0.01$ " unless otherwise specified.
WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | $\begin{aligned} & \text { 5-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 10-Pin } \\ & \text { MS } \end{aligned}$ | 7-pin MS HV,H5 | $\begin{aligned} & \text { 7-pin } \\ & \text { MS } \\ & \text { PU,PP, } \\ & \text { OC,P5 } \end{aligned}$ | $\begin{gathered} \text { 6-pin } \\ \text { MS } \\ \text { PU,PP } \\ \text { OC,P5 } \end{gathered}$ | $\begin{aligned} & \text { 9-pin } \\ & \text { D-sub } \end{aligned}$ | 10-pin Bayonet | *CE Option: Cable shield (bare wire) is connected to internal case. <br> ${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield. <br> **CE option: Use cable cordset with shield connected to M12 connector coupling nut. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A,F | 9 | F |  |
| +VDC | Red | 1 | 2 | D | D | D | B | 1 | D |  |
| A | White | 4 | 1 | A | A | A | D | 2 | A |  |
| $A^{\prime}$ | Brown | -- | 3 | H | C | -- | -- | 3 | H |  |
| B | Blue | 2 | 4 | B | B | B | E | 4 | B |  |
| B' | Violet | -- | 5 | 1 | E | -- | -- | 5 | J |  |
| Z | Orange | 5 | 6 | C | -- | C | C | 6 | C |  |
| Z' | Yellow | -- | 8 | J | -- | -- | -- | 7 | K |  |
| Case | Green | -- | -- | G | G | G | -- | 8 | G |  |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- | -- |  |



## Quick Specs

- Rugged Industrial Encoder
- 2" x 2" Housing
- CPR to 30,000
- Flex Mount for Easy Installation
- Several Output Types
- RPM to 8000
- Sealing to IP66
- High Temperature Option


## Mounting Options

The 702 Motor Mount comes with a coupling and is available with a Bossed Hub to attach directly to fast revving motors.

The 702 Shaft has many different servo mounts and mounting flanges available and is able to handle heavy loads.

## Related Products



The Model 802S Accu-Coder ${ }^{T M}$ is an industry standard Size 20 (2.0" diameter) encoder housed in a heavy duty 316 stainless steel package. It's specifically designed for harsh factory and plant floor environments. A variety of flange and servo mounting styles make it easy to use in a broad range of applications. See page 100 for more information.


The Model 25SF Size 25 Accu-CoderPro ${ }^{\text {™ }}$ shaft encoder is specifically designed for the challenges of an industrial environment. With its tough, industrial package, it still has the performance to reach resolutions up to 65,536 cycles per revolution, offers 32 waveform options, and has different output types available. See page 92 for more information.


The Model 858S European Size 58
Accu-Coder ${ }^{\text {TM }}$ is a heavy duty, extremely rugged, reliable encoder in a 316 stainless steel package. Its compact design is well suited for harsh factory and plant floor environments calling for a metric solution. See page 102 for more information.


The Model 25SP Accu-CoderPro ${ }^{\text {™ }}$ is an industry standard Size 25 (2.5" diameter) and is programmable with the easy to use, point and click software. You can program:

- CPR - resolutions to 65,536
- Waveform - 32 options
- Output Type - 6 different output types available

See page 88 for more information.

## Incremental Shaft Encoders

MODEL $25 S P$ - PROGRAMMABLE


FEATURES<br>Industry Standard Size 25 Package ( $2.5^{\prime \prime} \times 2.5$ " / 63.5 mm )<br>Fully Programmable with Optional USB Module or Factory Configured<br>Optical Technology for High Accuracy<br>Resolutions from 1 to 65,536 CPR (262,144 quadrature counts)<br>Servo and Flange Mounting<br>IP67 Sealing Available

The Model 25SP Programmable Size 25 Accu-CoderPro ${ }^{\text {TM }}$ shaft encoder is specifically designed for the challenges of an industrial environment. But don't let the tough exterior fool you - contained within the rugged, industrial housing is an advanced set of electronics that allow the encoder to be programmed to your exact application needs. Using EPC's optional programming module, users may select the output type, 32 different waveforms, and any resolution from 1 to 65,536 CPR - that's 262,144 counts using $4 x$ quadrature counting. These programming features allow a single encoder to be configured for multiple applications, enabling one encoder to replace many different part numbers - and that provides cost savings on inventory and down-time replacement. The 25SP can also be configured and shipped with specs pre-programmed, with no on-site programming needed. The Model 25SP Accu-CoderPro ${ }^{\text {TM }}$ comes standard with dual bearings rated 80lbs axial or radial, and may be specified with up to IP67 sealing.

## COMMON APPLICATIONS

Motion Control Feedback, Conveyors, Elevator Controls, Machine Control, Food Processing, Process Control, Robotics, Material Handling, Textile Machines

## MODEL 25SP ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 25SP SPECIFICATIONS

## Electrical

Input Voltage............ 4.75 to 30 VDC max. See Output Types for limitations
Input Current............ 100 mA max with no output load ( 65 mA typical)
Output Format.......... Incremental, Programmable. See Waveforms on page 90 for options.
Output Types............ Line Driver* (HV) - 20 mA max per channel, max freq $1.0 \mathrm{MHz}, 5 \mathrm{VDC}$ max at $100^{\circ} \mathrm{C}$ or 24 VDC max at $85^{\circ} \mathrm{C}$.
Line Driver* (H5) - 5-30 VDC in/5 VDC out, 20 mA max per channel, max freq 2.7 MHz ,
5 VDC max at $100^{\circ} \mathrm{C}$.
Push-Pull (PP) - 20 mA max per channel, max frequency $1.0 \mathrm{MHz}, 5 \mathrm{VDC}$ max at $100^{\circ} \mathrm{C}$ or 24 VDC max at $85^{\circ} \mathrm{C}$.
Push-Pull (P5) - 5-30 VDC in/5 VDC out, 20 mA max per channel, max frequency $2.7 \mathrm{MHz}, 5 \mathrm{VDC}$ max at $100^{\circ} \mathrm{C}$.
Open Collector (OC) - 100 mA max per channel, 200 KHz max freq recommended Pull-Up (PU) -2.2 K ohm internal resistors, 100 mA max per channel, 150 KHz max freq recommended, max temp $85^{\circ} \mathrm{C}$ at $>24 \mathrm{VDC}$ *Meets RS 422 at 5 VDC supply
Index Once per revolution, programmable. EPC standard is $180^{\circ}$ gated to output A (waveform B5). See Waveform Diagrams for additional options.
Index Teach............... Index location adjustable via programming interface.
Max Frequency ......... 2.7 MHz subject to RPM restrictions for high resolution (CPR):
5000 RPM max for CPR 16385 to 32768 and 2500 RPM max for CPR 32769 to 65536
NOTE: Use 5 VDC Line Driver (H5 or HV output type) to obtain high frequencies.
Electrical Protection .. Overvoltage, reverse voltage, and output short circuit protected. NOTE: Sustained over or reverse voltage may result in permanent damage.
Min Edge Sep ........... 1 to 16384 CPR: $36^{\circ}$ electrical min, $63^{\circ}$ or better typical
16385 to 65536 CPR: $20^{\circ}$ electrical $\min , 36^{\circ}$ or better typical
Rise Time .................. ess than 1 microsecond
Accuracy. Better than $0.013^{\circ}$ or 47 arc-sec from true position
Diagnostic ................. LED located on encoder housing and error report available via programming Interface.

## Mechanical

Max Shaft Speed...... 8000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Shaft Material .......... 303 Stainless Steel
Shaft Rotation .......... Bi-directional
Radial Shaft Load. .... 80 lb max. Rated load of 20 to 40 lb for rated life of $1.5 \times 10^{9}$ revs
Axial Shaft Load ....... 80 lb max. Rated load of 20 to 40 lb for rated life of $1.5 \times 10^{9}$ revs
Starting Torque ........ 1.0 oz-in typical with IP64 seal or no seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typical with IP67 shaft seal

Moment of Inertia ... $5.6 \times 10^{-4} \mathrm{oz}$-in-sec ${ }^{2}$
Housing .................... Black non-corrosive finish
Bearings.................... Precision ABEC ball bearings
Weight...................... 20 oz typical

## Environmental

Operating Temp ....... $-20^{\circ}$ to $85^{\circ} \mathrm{C}$ for standard models $-40^{\circ}$ to $100^{\circ} \mathrm{C}$ for extended temp option
Humidity...................95\% RH non-condensing
Vibration.................. 20 g @ 5 to 2000 Hz
Shock.. 80 g @ 11 ms duration
Sealing IP50 standard; IP64, IP66 or IP67 optional

## MODEL 25SP FLANGE MOUNT (MA)



MODEL 25SP 2.5" SERVO MOUNT (MC)


MODEL 25SP 2.62" SERVO MOUNT (MG)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## ENCODER WIRING TABLE

For EPC-supplied mating cables, wiring table is provided with cable.
Trim back and insulate unused wires.

|  | Gland <br> Cable $^{\dagger}$ <br> Wire Color | 5-pin <br> M12** $^{* *}$ | 2-pin <br> M12** | 10-pin <br> MS | 7-pin <br> MS <br> HV,H5 | 7-pin MS <br> PU,PP, <br> OC,P5 | 6-pin MS <br> PU,PP, <br> OC,P5 | 9-pin <br> D-sub |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A | 9 |
| +VDC | Red | 1 | 2 | D | D | D | B | 1 |
| A | White | 4 | 1 | A | A | A | D | 2 |
| A' | Brown | -- | 3 | H | C | -- | -- | 3 |
| B | Blue | 2 | 4 | B | B | B | E | 4 |
| B' | Violet | -- | 5 | I | E | -- | -- | 5 |
| Z | Orange | 5 | 6 | C | -- | C | C | 6 |
| Z' | Yellow | -- | 8 | J | -- | -- | -- | 7 |
| Case | Green | -- | -- | G | G | G | F | 8 |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- |

*CE Option: Cable shield (bare wire) is connected to internal case.
${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.
${ }^{* *}$ CE Option: Use cable cordset with shield connected to M12 connector coupling nut.


An EPC Size 25 Encoder in a common application

EPC STANDARD WAVEFORM (B5)
Additional waveforms available. See below for other options.


NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES.
COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z}$ APPLY TO LINE DRIVER (HV \& H5) OUTPUTS ONLY.

## WAVEFORMS

Model 25SP: Choose any of these waveforms when ordering. May be changed using the Field Programming Software, USB programming module, and interface cable (see page 91 ).

Model 25SF: Choose any of these waveforms when ordering.


## FIELD PROGRAMMING SOFTWARE

With the easy to use, point-and-click interface, programming is quick and straight-forward. The number of possible configurations makes this Size 25 programmable shaft encoder incredibly versatile. Anywhere a Size 25 encoder goes, the Model 25SP can get the job done.

Available on USB drive or by download.
System requirements:

- Windows 7 or higher operating systems
- USB 2.0 port required for USB Programming Module (see below)
$\checkmark$ (PR - any resolution from 1 to 65,536
That's 262,144 counts using $4 x$ quadrature counting


## Waveform - choose from 32 options

See page 90 for waveform choices

## $\checkmark$ Output type - 6 different output types

All output types are 5 V to 30 V in/out except H 5 Line Driver and P5 Push-Pull output types, which are 5-30VDC in and 5VDC out.


USB PROGRAMMING KIT
Kit includes Field Programming Software, USB Programming Module, and 2-meter Interface Cable with specified connector. See Accessories for individual Interface Cables.


| CONNECTOR TYPE | ITEM \# |
| :--- | :--- |
| 6-pin MS | PR1-001-06 |
| 7-pin MS | PR1-001-07 |
| 10-pin MS | PR1-001-10 |
| 5-pin M12 | PR1-001-J |
| 8-pin M12 | PR1-001-K |
| 9-pin D-Sub | PR1-001-09 |
| Gland Cable | PR1-001-G |

## Incremental Shaft Encoders

## MODEL 25 SF



## FEATURES

Industry Standard Size 25 Package ( 2.5 " $\times 2.5$ " / 63.5 mm )
Resolutions from 1 to 65,536 CPR ( 262,144 quadrature counts)
Servo and Flange Mounting
Optical Technology for High Accuracy
Standard with Heavy-Duty Dual Bearings Rated Load of 80 lbs axial \& radial IP67 Sealing Available

The Model 25SF Size 25 Accu-CoderPro ${ }^{\text {TM }}$ shaft encoder offers the performance advantages of the programmable Model 25SP, but in an economical, fixed resolution version. The versatile Model 25SF offers 32 different waveforms options, six output types, and any resolution from 1 to 65,536 CPR. Specifically designed for the challenges of an industrial environment, the Model 25SF features a rugged, industrial housing and comes standard with dual bearings rated 80 lbs axial or radial. Offering shaft sizes up to 10 mm , multiple mounting options, and sealing up to IP67, this encoder can take on your most demanding application.

## COMMON APPLICATIONS

Motion Control Feedback, Conveyors, Elevator Controls, Machine Control, Food Processing, Process Control, Robotics, Material Handling, Textile Machines

MODEL 25SF ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 25SF SPECIFICATIONS

## Electrical

Input Voltage............ 4.75 to 30 VDC max. See Output Types for limitations
Input Current............ 100 mA max with no output load ( 65 mA typical)
Output Format.......... Incremental. See Waveforms on page 90 for options.
Output Types............ Line Driver* (HV) - 20 mA max per channel, $\max$ freq $1.0 \mathrm{MHz}, 5 \mathrm{VDC}$ max at $100^{\circ} \mathrm{C}$ or 24 VDC max at $85^{\circ} \mathrm{C}$
Line Driver* (H5) - 5-30 VDC in/5 VDC out, 20 mA max per channel, max freq 2.7 MHz , 5 VDC max at $100^{\circ} \mathrm{C}$.
Push-Pull (PP) - 20 mA max per channel, max frequency $1.0 \mathrm{MHz}, 5 \mathrm{VDC}$ max at $100^{\circ} \mathrm{C}$ or 24 VDC max at $85^{\circ} \mathrm{C}$.
Push-Pull (P5) - 5-30 VDC in/5 VDC out, 20 mA max per channel, max frequency $2.7 \mathrm{MHz}, 5 \mathrm{VDC}$ max at $100^{\circ} \mathrm{C}$.
Open Collector (OC) - 100 mA max per channel, 200 KHz max freq recommended Pull-Up (PU) - 2.2 K ohm internal resistors, 100 mA max per channel, 150 KHz max freq recommended, max temp $85^{\circ} \mathrm{C}$ at > 24 VDC *Meets RS 422 at 5 VDC supply
Index ........................ Once per revolution. EPC standard is $180^{\circ}$ gated to output A (waveform B5). See Waveforms on Model 25SP for options.
Max Frequency ......... 2.7 MHz subject to RPM restrictions for high resolution (CPR):
5000 RPM max for CPR 16385 to 32768 and 2500 RPM max for CPR 32769 to 65536 NOTE: Use 5 VDC Line Driver (H5 or HV output type) to obtain high frequencies.
Electrical Protection .. Overvoltage, reverse voltage, and output short circuit protected. NOTE: Sustained over or reverse voltage may result in permanent damage.
Min Edge Sep ........... 1 to 16384 CPR: $36^{\circ}$ electrical min, $63^{\circ}$ or better typical
16385 to 65536 CPR: $20^{\circ}$ electrical min, $36^{\circ}$ or better typical
Rise Time .................. Less than 1 microsecond
Accuracy Better than $0.013^{\circ}$ or 47 arc-sec from true position

## Mechanical

Max Shaft Speed...... 8000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Shaft Material .......... 303 Stainless Steel
Shaft Rotation .......... Bi-directional
Radial Shaft Load. .... 80 lb max. Rated load of 20 to 40 lb for rated life of $1.5 \times 10^{9}$ revs
Axial Shaft Load ....... 80 lb max. Rated load of 20 to 40 lb for rated life of $1.5 \times 10^{9}$ revs
Starting Torque ........ 1.0 oz-in typical with IP64 seal or no seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typical with IP67 shaft seal

Moment of Inertia ... $5.6 \times 10^{-4}$ oz-in-sec ${ }^{2}$
Housing .................... Black non-corrosive finish
Bearings...................Precision ABEC ball bearings
Weight....................... 20 oz typical

## Environmental

Operating Temp ....... $-20^{\circ}$ to $85^{\circ} \mathrm{C}$ for standard models $-40^{\circ}$ to $100^{\circ} \mathrm{C}$ for extended temp option
Humidity.................. $95 \%$ RH non-condensing
Vibration................... 20 g @ 5 to 2000 Hz
Shock... 80 g @ 11 ms duration
Sealing.. . IP50 standard; IP64, IP66 or IP67 optional

MODEL 25SF FLANGE MOUNT (MA)


MODEL 25SF 2.5" SERVO MOUNT (MC)


MODEL 25SF 2.62" SERVO MOUNT (MG)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

ENCODER WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | $\begin{aligned} & \text { 5-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 10-pin } \\ & \text { MS } \end{aligned}$ | 7-pin MS HV, H5 | $\begin{aligned} & \text { 7-pin MS } \\ & \text { PU,PP, } \\ & \text { OC,P5 } \end{aligned}$ | $\begin{gathered} \text { 6-pin MS } \\ \text { PU,PP, } \\ \text { OC,P5 } \end{gathered}$ | $\begin{aligned} & \text { 9-pin } \\ & \text { D-sub } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A | 9 |
| +VDC | Red | 1 | 2 | D | D | D | B | 1 |
| A | White | 4 | 1 | A | A | A | D | 2 |
| $\mathrm{A}^{\prime}$ | Brown | -- | 3 | H | C | -- | -- | 3 |
| B | Blue | 2 | 4 | B | B | B | E | 4 |
| $B^{\prime}$ | Violet | -- | 5 | 1 | E | -- | -- | 5 |
| Z | Orange | 5 | 6 | C | -- | C | C | 6 |
| Z' | Yellow | -- | 8 | J | -- | -- | -- | 7 |
| Case | Green | -- | -- | G | G | G | F | 8 |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- |

*CE Option: Cable shield (bare wire) is connected to internal case.
${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.
**CE Option: Use cable cordset with shield connected to M12 connector coupling nut.


## FEATURES

## Standard Size 25 Package ( $2.5^{\prime \prime} \times 2.5$ ") Up to 30,000 CPR <br> Standard and Industrial Housings <br> Servo and Flange Mounting IP67 Sealing Available

The Model 725 Accu-Coder ${ }^{\text {TM }}$ optical shaft encoder is specifically designed for the challenges of an industrial environment. Even with its tough, industrial package, this Size 25 encoder still has the performance to reach resolutions up to 30,000 cycles per revolution. The Model 725 offers both flange and servo mounting options, and is available in two distinctive housing styles: Standard Housing $(\mathrm{N})$ and Industrial Housing (I). The rugged Standard Housing isolates the internal electronics from the shock and stress of the outer environment, while the extra heavy-duty Industrial Housing features a fully isolated internal encoder unit. Isolating the unit prolongs bearing life by using an internal flexible mount to protect the encoder from severe axial and radial shaft loading. The Industrial Housing is the recommended solution for applications subject to continuous side loads, such as those that drive the encoder with a measuring wheel, pulley, or chain and sprocket.
COMMON APPLICATIONS
Ø2.5"
Motion Control Feedback, Conveyors, Elevator Controls, Machine Control, Food Processing, Process Control, Robotics, Material Handling, Textile Machines

MODEL 725 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


MODEL 725 CPR OPTIONS

| 0001* | 0002* | 0004* | 0005* | 0006* | 0007* | 0008* | 0010* | 0011* | 0012* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0014* | 0020 | 0021* | 0024* | 0025* | 0028* | 0030* | 0032* | 0033* | 0034* |
| 0035* | 0038* | 0040* | 0042* | 0045* | 0050* | 0060 | 0064* | 0100 | 0120 |
| 0125 | 0128* | 0144* | 0150* | 0160* | 0192* | 0200 | 0240* | 0250 | 0254* |
| 0256* | 0300 | 0333* | 0336* | 0360 | 0400 | 0500 | 0512 | 0600 | 0625* |
| 0635 | 0665* | 0720 | 0768* | 0800 | 0889 | 1000 | 1024 | 1200 | 1201*a |
| 1203*a | 1204*a | $1250^{\text {a }}$ | $1270^{\text {a }}$ | 1440 | 1500 | 1800 | 2000 | 2048 | $2400{ }^{\text {a }}$ |
| 2500 | $2540^{\text {a }}$ | $2880^{\text {a }}$ | $3000^{\text {a }}$ | $3600^{\text {a }}$ | $4000^{\text {a }}$ | 4096 ${ }^{\text {a }}$ | $5000^{\text {a }}$ | $6000^{\text {a }}$ | $7200^{\text {a }}$ |
| $7500^{\text {a }}$ | $9000^{\text {a }}$ | 10,000 ${ }^{\text {a }}$ | 10,240 ${ }^{\text {a }}$ | 12,000a | 12,500 ${ }^{\text {a }}$ | 14,400 ${ }^{\text {a }}$ | 15,000 ${ }^{\text {a }}$ | 18,000 ${ }^{\text {a }}$ | 20,000 ${ }^{\text {a }}$ |
| 20,480 | 25,000 | 30,000 ${ }^{\text {a }}$ |  |  |  |  |  |  |  |

## NOTES:

1 Available with Industrial Housing (I) only.
2 Low temperature option not available with resolutions of 3000 CPR or higher.
$30^{\circ}$ to $85^{\circ} \mathrm{C}$ for certain resolutions, see CPR Options.
4 Contact Customer Service for index gating options.
524 VDC max for high temperature option.
6 Line Driver not available with 5-pin M12 or 6-pin MS connector. Available with 7-pin MS connector only without Index Z.
7 Standard temperature, 60 to 3000 CPR only. Not available with 2540 CPR.
8 H5 and P5 outputs not available with CE option, or any End Mount MS connector.
9 Standard cable lengths only. For details, please refer to Technical Bulletin
TB116: Noise and Signal Distortion Considerations at encoder.com.
10 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin. Configuration Diagrams at encoder.com.
11 For Non-Standard Cable Lengths add a forward slash (/) plus cable length expressed in feet. Example: SG/6 $=6$ feet of cable.
12 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder. com.

## MODEL 725 SPECIFICATIONS

Electrical
Input Voltage...... 45 to 28 VDC max for temperatures 4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$
Input Current.. mA max with no output load
Input Ripple.. 100 mV peak-to-peak at 0 to 100 kHz Output Format.. Incremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the encoder mounting face See Waveform Diagrams.
Output Types............ Open Collector -100 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index $\qquad$ Occurs once per revolution. The index for units >3000 CPR is $90^{\circ}$ gated to Outputs A and B. See Waveform Diagrams.
Max Frequency ........ Up to 1 MHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity ......... Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2
Symmetry ................. 1 to 6000 CPR: $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical at 100 kHz output 6001 to 20,480 CPR: $180^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Quad Phasing to 6000 CPR: $90^{\circ}\left( \pm 22.5^{\circ}\right.$ ) electrical at 100 kHz output 6001 to 20,480 CPR: $90^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Min Edge Sep ........... 1 to 6000 CPR: $67.5^{\circ}$ electrical at 100 kHz output 6001 to 20,480 CPR: $54^{\circ}$ electrical >20,480 CPR: $50^{\circ}$ electrical
Rise Time $\qquad$ Less than 1 microsecond
Accuracy.. Instrument and Quadrature Error: For 200 to 1999 CPR, $0.017^{\circ}$ mechanical ( 1.0 arc minutes) from one cycle to any other cycle. For 2000 to 3000 CPR, $0.01^{\circ}$ mechanical ( 0.6 arc minutes) from one cycle to any other cycle. Interpolation error (units > 3000 CPR only) within $0.005^{\circ}$ mechanical. (Total Optical Encoder Error = Instrument + Quadrature + Interpolation)
Mechanical
Max Shaft Speed...... 8000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Shaft Material .......... 303 Stainless Steel
Shaft Rotation .......... Bi-directional
Radial Shaft Load. .... 80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Axial Shaft Load ....... 80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Starting Torque ........1.0 oz-in typical with IP64 seal or no seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typical with IP67 shaft seal

Moment of Inertia ... $5.2 \times 10^{-4}$ oz-in-sec ${ }^{2}$
Housing $\qquad$ Black non-corrosive finish
Bearings Precision ABEC ball bearings
Weight. 20 oz typical

## Environmental

Storage Temp ........... $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity.................. $95 \%$ RH non-condensing
Vibration.
Shock. $.20 \mathrm{~g} @ 58$ to 500 Hz

Sealing. IP50 standard; IP64, IP66 or IP67 optional

MODEL 725 2.5" SERVO MOUNT (S)


MODEL 725 2.5" SERVO MOUNT (Q)
Servo mount $(R)$ has been discontinued and replaced by servo mount $(Q)$


MODEL 725 2.62" SERVO MOUNT (L)


MODEL 725 FLANGE MOUNT (F)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## Incremental Shaft Encoders

## MODEL 725

MODEL 725 OPTIONAL 5PY MOUNTING (P)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01$ " unless otherwise specified.


The optional 5PY adapter is made of all aluminum construction and allows the Model 725 encoder to replace DC tachometer technology. The 5PY adapter is mechanically interchangeable with any 5PY tach generator.

## WAVEFORM DIAGRAMS



## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | 5-pin <br> M12** | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | 10-pin MS | $\begin{gathered} \text { 7-pin MS } \\ \text { HV,H5 } \end{gathered}$ | 7-pin MS PU,PP,OC,P5 | $\begin{aligned} & \text { 6-pin MS } \\ & \text { PU,PP,OC,P5 } \end{aligned}$ | 9-pin D-sub |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | A, F | 9 |
| +VDC | Red | 1 | 2 | D | D | D | B | 1 |
| A | White | 4 | 1 | A | A | A | D | 2 |
| $A^{\prime}$ | Brown | -- | 3 | H | C | -- | -- | 3 |
| B | Blue | 2 | 4 | B | B | B | E | 4 |
| $B^{\prime}$ | Violet | -- | 5 | 1 | E | -- | -- | 5 |
| Z | Orange | 5 | 6 | C | -- | C | C | 6 |
| Z' | Yellow | -- | 8 | J | -- | -- | -- | 7 |
| Case | Green | -- | -- | G | G | G | -- | 8 |
| Shield | Bare* | -- | -- | -- | -- | -- | -- | -- |

[^9]${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.
**CE Option: Use cable cord set with shield connected to M12 connector coupling nut.

## EPC SIZE 25 ENCODERS

A Step Above the Rest
Size 25 encoders ( 2.5 " diameter) are among the most popular encoders in the world. As a result, nearly every encoder manufacturer in the world makes them. The problem is, not every Size 25 encoder is built to the same exacting standards of quality and reliability as the Encoder Products Company's line of Size 25 encoders.

So, what's the problem? If you have used other Size 25 encoders, you have probably experienced reliability problems, such as sensor crashes and disk breakage. The typical construction of a Size 25 encoder uses a single set of closely spaced shaft bearings and a large-diameter (typically 2.0 ") glass disk mounted to the shaft. The glass disk is generally supported on the shaft hub by just $15 \%$ of the surface area and has a thickness of 0.030".

In addition, these units commonly require a relatively narrow air gap (typically 0.002 ") between the disk and sensor in order to properly calibrate the signal. Because of this combination, a small amount of side loading (force from installation requirements, vibration, shock, or other conditions) to move the shaft enough for the attached disk to make contact with the sensor or some other portion of the stationary PCB. The result is damage to the disk or sensor, or even disk breakage.

So what's the solution? When design engineers at EPC set out to design a better Size 25 encoder, their goal was to solve the typical problems.

The first goal was to make it more difficult for shaft movement from side load to cause damage. Using EPC's advanced sensor technology, the air gap between the disk and sensor

doubled from $0.002^{\prime \prime}$ to 0.004 ", and the disk diameter was reduced from 2.0" to 1.3".

The next goal was to increase the durability of the disk itself. Disk thickness was more than doubled (from 0.030 " to 0.062 "), manufactured using EPC's proprietary process, and supported by $30 \%$ of the disk surface area.

Finally, it was time to improve the resistance to side load movement altogether, so the Size 25s were given dual heavyduty bearings, generously spaced to disperse the load over a larger portion of the shaft.

EPC Models 725,25 SF, and 25 SP all share these features, and are all rugged encoders that can work in the most challenging environments. Review the chart below to note the differences among these models and help you determine which one is right for your application.

| Model \# | Max CPR | Max Frequency | Number of <br> Waveform Options | Bearing Load | Maximum <br> Seal Rating |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 725 | 30,000 | 1 MHz | 5 | Dual bearings rated <br> $80 l b s$ axial or radial | IP67 |
| 25 SF | 65,536 | 2.7 MHz | 32 | Dual bearings rated <br> $80 l b s$ axial or radial | IP67 |
| 25 SP | $65,536^{*}$ | 2.7 MHz | $32^{*}$ | Dual bearings rated <br> $80 l b s ~ a x i a l ~ o r ~ r a d i a l ~$ | IP67 |

Options are programmable with Field Programming Software.

## For the TRULY tough environment

The Model 7251 with the industrial 725 housing option is an encoder that is as robust as possible within its price category. Using the improvements developed for our standard Size 25s, EPC's engineering team developed the "encoder-within-an-encoder" design. In addition, the internal encoder is mounted to the 725 I's housing using EPC's pioneering flex mount, further isolating the internal optics and electronics from outside forces.


## Incremental Shaft Encoders

MODEL 758

$\varnothing 58$ mm

## FEATURES

## Standard Size 58 Mounting ( 58 mm Diameter) Up to 30,000 CPR <br> 80 lb Max. Axial and Radial Shaft Loading High Temperature Option ( $100^{\circ} \mathrm{C}$ ) IP67 Sealing Available

The Model 758 Size 58 Accu-Coder ${ }^{\text {TM }}$ is a heavy duty, extremely rugged, reliable, yet compact European standard size 58 millimeter diameter encoder, designed for harsh factory and plant floor environments. Shaft loading is no problem for the double-shielded ball bearings; their 80 lb load rating ensures a long operating life. With the optional heavy-duty shaft seal, the Model 758 is rated IP67. Two European standard mounting options are available: Clamping Flange (20 Type) or Synchro Flange (26 Type). The Model 758 is the perfect replacement encoder for units requiring the European mount.
COMMON APPLICATIONS
Motion Control Feedback, Machine \& Elevator Controls, Food Processing, Robotics, Material Handling, Conveyors, Textile Machines

MODEL 758 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


MODEL 758 CPR OPTIONS

| 0001* | 0002* | 0004* | 0005* | 0006* | 0007* | 0008* | 0010* | 0011* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0012* | 0014* | 0020 | 0021* | 0024* | 0025* | 0028* | 0030* | 0032* |
| 0033* | 0034* | 0035* | 0038* | 0040* | 0042* | 0045* | 0050* | 0060 |
| 0064* | 0100 | 0120 | 0125 | 0128* | 0144* | 0150* | 0160* | 0192* |
| 0200 | 0240* | 0250 | 0254* | 0256* | 0300 | 0333* | 0336* | 0360 |
| 0400 | 0500 | 0512 | 0600 | 0625* | 0635 | 0665* | 0720 | 0768* |
| 0800 | 0889 | 1000 | 1024 | 1200 | 1201*a | 1203*a | 1204*a | $1250^{\text {a }}$ |
| $1270^{\text {a }}$ | 1440 | 1500 | 1800 | 2000 | 2048 | $2400{ }^{\text {a }}$ | 2500 | $2540^{\text {a }}$ |
| $2880{ }^{\text {a }}$ | $3000^{\text {a }}$ | $3600^{\text {a }}$ | $4000^{\text {a }}$ | 4096a ${ }^{\text {a }}$ | $5000^{\text {a }}$ | $6000^{\text {a }}$ | $7200{ }^{\text {a }}$ | $7500^{\text {a }}$ |
| $9000^{\text {a }}$ | 10,000 ${ }^{\text {a }}$ | 10,240a | $12,000^{\text {a }}$ | 12,500 ${ }^{\text {a }}$ | 14,400 ${ }^{\text {a }}$ | 15,000 ${ }^{\text {a }}$ | 18,000 ${ }^{\text {a }}$ | 20,000 ${ }^{\text {a }}$ |
| 20,48 | 25,000a | 30,000 ${ }^{\text {a }}$ |  |  |  |  |  |  |

*Contact Customer Service for High Temperature Option (H).
aHigh Temperature Option (H) limited to $85^{\circ} \mathrm{C}$ maximum for these CPR options.
New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available CPR values. Special disk resolutions are available upon request. A one-time NRE fee may apply.

NOTES:
1 The shaft on 20 Type mountings includes a 15.58 mm flat. The shaft on 26 Type mountings is provided without a flat.
Low temperature option not available with resolutions of 3000 CPR or higher. $0^{\circ}$ to $85^{\circ} \mathrm{C}$ for certain resolutions, see CPR Options. Contact Customer Service for index gating options. 24 VDC max for high temperature option. H5 and P5 outputs are not available with CE option, or any End Mount MS Connector. Standard temperature, 60 to 3000 CPR only. Not available with 2540 CPR.
8 Line Driver Outputs not available with 5 -pin M12 connector. Available with 7 -pin MS connector only without Index Z.
9 Standard cable lengths only. For details, please refer to Technical Bulletin TB116: Noise and Signal Distortion Considerations at encoder.com.
10 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
11 For Non-Standard Cable Lengths add a forward slash (/) plus cable length expressed in feet. Example: $\mathrm{SG} / 6=6$ feet of cable.
12 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL 758 SPECIFICATIONS

## Electrical

Input Voltage............ 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$
Input Current ........... 100 mA max with no output load Input Ripple.............. 100 mV peak-to-peak at 0 to 100 kHz
Output Format ......... Incremental - Two square waves in quadrature with channel $A$ leading $B$ for clockwise shaft rotation, as viewed from the encoder mounting face. See Waveform Diagrams.
Output Types............ Open Collector - 100 mA max per channe Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index........................ Occurs once per revolution. The index for units $>3000 \mathrm{CPR}$ is $90^{\circ}$ gated to Outputs A and B. See Waveform Diagrams.
Max Frequency ........ Up to 1 MHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2
Symmetry................. 1 to 6000 CPR: $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical at 100 kHz output
6001 to 20,480 CPR: $180^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Quad Phasing .......... 1 to 6000 CPR: $90^{\circ}\left( \pm 22.5^{\circ}\right)$ electrical at 100 kHz output
6001 to 20,480 CPR: $90^{\circ}\left( \pm 36^{\circ}\right)$
Min Edge Sep ........... 1 to 6000 CPR: $67.5^{\circ}$ electrical at 100 kHz output 6001 to 20,480 CPR: $54^{\circ}$ electrical >20,480 CPR: $50^{\circ}$ electrical
Rise Time Less than 1 microsecond

Accuracy................... Instrument and Quadrature Error For 200 to 1999 CPR, $0.017^{\circ}$ mechanical (1.0 arc minutes) from one cycle to any other cycle. For 2000 to 3000 CPR, $0.01^{\circ}$ mechanical ( 0.6 arc minutes) from one cycle to any other cycle. Interpolation error (units > 3000 CPR only) within $0.005^{\circ}$ mechanical. (Total Optical Encoder Error = Instrument + Quadrature + Interpolation)

## Mechanical

Max Shaft Speed...... 8000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Shaft Rotation .......... Bi-directional
Radial Shaft Load ..... 80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Axial Shaft Load ....... 80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Starting Torque ........ 1.0 oz-in typical with IP64 seal or no seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typical with IP67 shaft seal

Moment of Inertia ... $5.2 \times 10^{-4} \mathrm{oz}-\mathrm{in}-\mathrm{sec}^{2}$
Housing ................... Black non-corrosive finish
Bearings...................Precision ABEC ball bearings
Weight..................... 11 oz typical

## Environmental

Storage Temp ...........-25 to $85^{\circ} \mathrm{C}$
Humidity................... $98 \%$ RH non-condensing
Vibration.................. 20 g @ 58 to 500 Hz
Shock.
75 g @ 11 ms duration
Sealing......................IP50 standard; IP64, IP66 or IP67 optional

MODEL 758 CLAMPING FLANGE 20 TYPE (A)


MODEL 758 SYNCHRO FLANGE 26 TYPE (B)


All dimensions are in millimeters with a tolerance of $\pm 0.17 \mathrm{~mm}$ unless otherwise specified.

## WAVEFORM DIAGRAMS

Open Collector and Pull-Up


Line Driver and Push-Pull


NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z}$ FOR HV AND H5 OUTPUTS ONLY.

WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Gland Cable ${ }^{\dagger}$ Wire Color | 5-pin <br> M12** | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 10- } \\ & \text { pin } \\ & \text { MS } \end{aligned}$ | 7-pin MS HV,H5 | $\begin{aligned} & \text { 7-pin } \\ & \text { MS } \\ & \text { PU,PP } \\ & \text { P5,0C } \end{aligned}$ | $\begin{aligned} & 12- \\ & \text { pin } \\ & \text { M23 } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 | F | F | F | 10 |
| +VDC | Red | 1 | 2 | D | D | D | 12 |
| A | White | 4 | 1 | A | A | A | 5 |
| $A^{\prime}$ | Brown | -- | 3 | H | C | -- | 6 |
| B | Blue | 2 | 4 | B | B | B | 8 |
| $B^{\prime}$ | Violet | -- | 5 | 1 | E | -- | 1 |
| Z | Orange | 5 | 6 | c | -- | C | 3 |
| Z' | Yellow | -- | 8 | J | -- | -- | 4 |
| Shield | Bare* | -- | - | -- | -- | -- | -- |
| +VDC <br> Sense | -- | -- | -- | -- | -- | -- | 2 |
| Com Sense | -- | -- | -- | -- | -- | -- | 11 |
| Case | Green | -- | -- | G | G | G | 9 |

*CE Option: Cable shield (bare wire) is connected to internal case.
$\dagger_{\text {Standard cable is }} 24$ AWG conductors with foil and braid shield.
${ }^{*}$ *CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

## Stainless Steel Encoders

MODEL 802 S


FEATURES

## Industry Standard Size 20 (2" Diameter) Stainless Steel Package Flange and Servo Mounting <br> Up to 30,000 CPR <br> 80 lb Maximum Axial and Radial Shaft Loading IP67 Sealing Available

The Model 802S Accu-Coder™ is a heavy duty, industry standard Size 20 (2.0" diameter) encoder specifically designed for harsh factory and plant floor environments. The Model 802S is available with a variety of flange and servo mounting styles, making it easy to use in a broad range of applications. Its heavy duty, double-shielded ball bearings are rated at 80 pounds maximum axial and radial shaft load, ensuring long operating life. This ultra-rugged yet compact encoder is housed in a Type 316 Stainless Steel enclosure, making it ideal for applications where contamination or exposure to caustic chemicals is a concern. Even with its tough exterior, the Model 802S provides the precise, reliable output you've come to expect from Accu-Coder ${ }^{\text {TM }}$.
COMMON APPLICATIONS
ø2.0"
Food Processing, Oil, Gas \& Chemical Processing, Material Handling, Conveyors, Robotics, Elevator Controls, Textile Machines

MODEL 802S ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 802S CPR OPTIONS

| 0001* | 0002* | 0004* | 0005* | 0006* | 0007* | 0008* | 0010* | 0011* | 0012* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0014* | 0020 | 0021* | 0024* | 0025* | 0028* | 0030* | 0032* | 0033* | 0034* |
| 0035* | 0038* | 0040* | 0042* | 0045* | 0050* | 0060 | 0064* | 0100 | 012 |
| 0125 | 0128* | 0144* | 0150* | 0160* | 0192* | 0200 | 0240* | 0250 | 0254* |
| 0256* | 0300 | 0333* | 0336* | 0360 | 0400 | 0500 | 0512 | 0600 | 0625* |
| 0635 | 0665* | 0720 | 0768* | 0800 | 0889 | 1000 | 1024 | 1200 | $1201 * 2$ |
| 1203*a | 1204*a | $1250^{\text {a }}$ | $1270{ }^{\text {a }}$ | 1440 | 1500 | 1800 | 2000 | 2048 | $2400^{\text {a }}$ |
| 2500 | $2540{ }^{\text {a }}$ | $2880^{\text {a }}$ | $3000{ }^{\text {a }}$ | $3600^{\text {a }}$ | $4000^{\text {a }}$ | $4096{ }^{\text {a }}$ | $5000^{\text {a }}$ | $6000^{\text {a }}$ | $7200^{\text {a }}$ |
| $7500^{\text {a }}$ | $9000^{\text {a }}$ | $10,000^{\text {a }}$ | $10,240^{\text {a }}$ | 12,000 | $12,500^{\text {a }}$ | $14,400^{\text {a }}$ | $15,000^{\text {a }}$ | $18,000^{\text {a }}$ | 20,000 ${ }^{\text {a }}$ |
| 20,480 ${ }^{\text {a }}$ | 25,000 ${ }^{\text {a }}$ | 30,000 ${ }^{\text {a }}$ |  |  |  |  |  |  |  |
| *Contact Customer Service for High Temperature Option. <br> aHigh Temperature Option (H) limited to $85^{\circ} \mathrm{C}$ maximum for these CPR options. |  |  |  |  |  |  |  |  |  |
| New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available CPR values. Special disk resolutions are available upon request A one-time NRE fee may apply. |  |  |  |  |  |  |  |  |  |

## NOTES:

1 Contact Customer Service for additional options.
2 Shaft with Size 25 Mounting Adapter, J or K mounting only.
3 Low temperature option not available with resolutions of 3000 CPR or higher.
$4 \quad 0^{\circ}$ to $85^{\circ} \mathrm{C}$ for certain resolutions, see CPR Options.
5 Contact Customer Service for non-standard index gating options.
624 VDC max for high temperature option.
7 Line Driver Outputs not available with 5-pin M12 connector.
8 Standard temperature, 60 to 3000 CPR only. Not available with 2540 CPR.
9 CE not available with H5/P5 output type options.
10 Standard cable lengths only. For details, please refer to Technical Bulletin TB116: Noise and Signal Distortion Considerations at encoder.com.
11 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
12 For non-standard cable lengths, add a forward slash (/) plus cable length expressed in feet. Example: $\mathrm{G} / 6=6$ feet of cable.
13 M12 connector available on side mount option only.
14 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL 802S SPECIFICATIONS

Electrical
Input Voltage............ 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$
Input Current ........... 100 mA max with no output load Input Ripple.............. 100 mV peak-to-peak at 0 to 100 kHz Output Format..... Incremental - Two square waves in quadrature with channel A leading B for clockwise shaft rotation, as viewed from the encoder mounting face. See Waveform Diagrams.
Output Types ............ Open Collector - 100 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index......................... Occurs once per revolution. The index for units $>3000$ CPR is $90^{\circ}$ gated to Outputs A and B. See Waveform Diagrams.
Max Frequency ........ Up to 1 MHz .
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2
Symmetry................. 1 to 6000 CPR: $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical at 100 kHz output 6001 to 30,000 CPR: $180^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Quad Phasing ........... 1 to 6000 CPR: $90^{\circ}\left( \pm 22.5^{\circ}\right)$ electrical at 100 kHz output 6001 to 30,000 CPR: $90^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Min Edge Sep ........... 1 to 6000 CPR: $67.5^{\circ}$ electrical at 100 kHz output
6001 to 20,480 CPR: $54^{\circ}$ electrical $>20,480$ CPR: $50^{\circ}$ electrical
Rise Time Instrument and Quadrature Error: For 200 to 1999 CPR, $0.017^{\circ}$ mechanical ( 1.0 arc minutes) from one cycle to any other cycle. For 2000 to 3000 CPR, $0.01^{\circ}$ mechanical ( 0.6 arc minutes) from one cycle to any other cycle. Interpolation error (units $>3000$ CPR only) within $0.005^{\circ}$ mechanical. (Total Optical Encoder Error = Instrument + Quadrature + Interpolation)

## Mechanical

Max Shaft Speed...... 8000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Radial Shaft Load ..... 80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Axial Shaft Load ....... 80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Starting Torque ........ 1.0 oz-in typical with IP64 seal or no seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typical with IP67 shaft seal

Moment of Inertia ... $5.2 \times 10^{-4} \mathrm{oz}$-in-sec ${ }^{2}$
Housing ....................Type 316 Stainless Steel
Bearings...................Precision ABEC ball bearings
Weight....................... 1.5 lb typical

## Environmental

Storage Temp ............ $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity.................. $98 \%$ RH non-condensing
Vibration................... 20 g @ 58 to 500 Hz
Shock.. 75 g @ 11 ms duration
Sealing IP50 standard; IP64, IP66, IP67 optional

## MODEL 802S SERVO MOUNT (S)



MODEL 802S FLANGE MOUNT (F)


MODEL 802S SIZE 25 (2.5") SERVO MOUNT (J)


MODEL 802S SIZE 25 (2.5") FLANGE MOUNT (K)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | Gland <br> Cable ${ }^{\dagger}$ <br> Wire Color | $\begin{aligned} & \text { 5-pin } \\ & \text { M12** } \end{aligned}$ | $\begin{aligned} & \text { 8-pin } \\ & \text { M12** } \end{aligned}$ | *CE Option: Cable Shield (bare wire) is connected to internal |
| :---: | :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 |  |
| +VDC | Red | 1 | 2 | case. |
| A | White | 4 | 1 | conductors with foil and braid |
| $A^{\prime}$ | Brown | -- | 3 | shield. |
| B | Blue | 2 | 4 | with shield connected to M12 |
| B' | Violet | -- | 5 | connector coupling nut. |
| Z | Orange | 5 | 6 |  |
| Z' | Yellow | -- | 8 |  |
| Case | Green | -- | -- |  |
| Shield | Bare* | -- | -- |  |



WAVEFORM DIAGRAMS
Line Driver and Push-Pull


NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS Ā, B, Z̄ F FOR HV OR H5 OUTPUTS ONLY.
Open Collector and Pull-Up


## Stainless Steel Encoders

MODEL 858 S


## FEATURES

## Industry Standard Size 58 ( 58 mm Diameter) Stainless Steel Package Up to 30,000 CPR <br> 80 lb Maximum Axial and Radial Shaft Loading <br> $100^{\circ} \mathrm{C}$ Operating Temperature Available IP67 Sealing Available

The Model 858S European Size 58 Accu-Coder ${ }^{T M}$ is a heavy duty, extremely rugged, reliable encoder, in a 316 stainless steel package. Its compact design is well suited for harsh factory and plant floor environments that call for a metric solution. The double-shielded ball bearings are rated at 80 pound maximum axial and radial shaft loading, to ensure a long operating life. Shock rating is 75 g for 11 milliseconds duration. With the optional heavy-duty shaft seal installed, the Model 858 S is rated at IP67. Two European standard mounting options are available, the Clamping Flange (20 Type), or the Synchro Flange (26 Type).
COMMON APPLICATIONS
Food Processing, Oil, Gas \& Chemical Processing, Material Handling, Conveyors, Robotics, Elevator Controls, Textile Machines

MODEL 858S ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 858S CPR OPTIONS

| 0001* | 0002* | 4* | 05* | 0006* | 0007* | 0008* | 0010* | 00 | 00 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0014* | 20 | 0021* | 0024* | 0025* | 0028 | 0030* | 0032* | 0033 | 003 |
| 0035* | 0038* | 0040* | 0042 | 0045 | 0050 | 006 | 006 | 010 | 0120 |
| 0125 | 0128* | 144* | 0150* | 0160* | 200 | 0240* | 0250 | 025 | 0256* |
| 0300 | 0333* | 0336* | 0360 | 0400 | 500 | 0512 | 060 | 0625 | 0635 |
| 0665* | 0720 | 0768* | 0800 | 0889 | 1000 | 102 | 120 | 1201 | 1203* |
| 1204* ${ }^{\text {a }}$ | $1250^{\text {a }}$ | $1270^{\text {a }}$ | 1440 | 1500 | 1800 | 2000 | 2048 | $2400^{\text {a }}$ | 2500 |
| $2540{ }^{\text {a }}$ | $2880^{\text {a }}$ | $3000^{\text {a }}$ | $3600^{\text {a }}$ | 4000 ${ }^{\text {a }}$ | 4096 ${ }^{\text {a }}$ | $5000^{\text {a }}$ | $6000^{\text {a }}$ | $7200^{\text {a }}$ | 750 |
| $9000{ }^{\text {a }}$ | 10,000 ${ }^{\text {a }}$ | 10,240 ${ }^{\text {a }}$ | $12,000^{\text {a }}$ | 12,500 ${ }^{\text {a }}$ | 14,400 ${ }^{\text {a }}$ | 15,000 ${ }^{\text {a }}$ | 18,000 ${ }^{\text {a }}$ | 20,000 ${ }^{\text {a }}$ | 20,480 |
| 25,000 ${ }^{\text {a }}$ | 30,000 ${ }^{\text {a }}$ |  |  |  |  |  |  |  |  |
| *Contact Customer Service for High Temperature Option. aHigh Temperature Option (H) limited to $85^{\circ} \mathrm{C}$ maximum for these CPR options. |  |  |  |  |  |  |  |  |  |
| New CPR values are periodically added to those listed. Contact Customer Service to determine all currently available CPR values. Special disk resolutions are available upon request. A one-time NRE fee may apply. |  |  |  |  |  |  |  |  |  |

upon request. A one-time NRE fee may apply.

## NOTES:

1 The shaft on 20 Type mountings includes a 15.58 mm flat. The shaft on 26 Type mountings is provided without a flat.
2 Low temperature option not available with resolutions of 3000 CPR or higher.
$30^{\circ}$ to $85^{\circ} \mathrm{C}$ for certain resolutions, see CPR Options.
4 Contact Customer Service for non-standard index gating options.
524 VDC max for high temperature option.
6 Line Driver Outputs not available with 5-pin M12 connector.
7 Standard temperature, 60 to 3000 CPR only. Not available with 2540 CPR.
8 CE not available with H5/P5 output type options.
9 Standard cable lengths only. For details, please refer to Technical Bulletin TB116: Noise and Signal Distortion Considerations at encoder.com.
10 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
11 For non-standard cable lengths, add a forward slash (I) plus cable length expressed in feet. Example: $\mathrm{G} / 6=6$ feet of cable.
12 M12 connector available on side mount option only.
13 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

## MODEL 858S SPECIFICATIONS

## Electrical

Input Voltage............ 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$
Input Current ........... 100 mA max with no output load Input Ripple.............. 100 mV peak-to-peak at 0 to 100 kHz
Output Format......... Incremental - Two square waves in quadrature with channel $A$ leading $B$ for clockwise shaft rotation, as viewed from the encoder mounting face. See Waveform Diagrams.
Output Types ............Open Collector - 100 mA max per channel Pull-Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel Push-Pull - 20 mA max per channe Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index........................ Occurs once per revolution. The index for units $>3000$ CPR is $90^{\circ}$ gated to Outputs A and B. See Waveform Diagrams.
Max Frequency .........Up to 1 MHz .
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity......... Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2
Symmetry................. 1 to 6000 CPR: $180^{\circ}\left( \pm 18^{\circ}\right)$ electrical at 100 kHz output 6001 to 30,000 CPR: $180^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Quad Phasing ........... 1 to $6000 \mathrm{CPR}: 90^{\circ}\left( \pm 22.5^{\circ}\right)$ electrical at 100 kHz output 6001 to 30,000 CPR: $90^{\circ}\left( \pm 36^{\circ}\right)$ electrical
Min Edge Sep ........... 1 to 6000 CPR: $67.5^{\circ}$ electrical at 100 kHz output
6001 to 20,480 CPR: $54^{\circ}$ electrical >20,480 CPR: $50^{\circ}$ electrical
Rise Time. Less than 1 microsecond
Accuracy Instrument and Quadrature Error: For 200 to 1999 CPR, $0.017^{\circ}$ mechanical (1.0 arc minutes) from one cycle to any other cycle. For 2000 to $3000 \mathrm{CPR}, 0.01^{\circ}$ mechanical ( 0.6 arc minutes) from one cycle to any other cycle. Interpolation error (units > 3000 CPR only) within $0.005^{\circ}$ mechanical. (Total Optical Encoder Error = Instrument + Quadrature + Interpolation)

## Mechanical

Max Shaft Speed...... 8000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Radial Shaft Load ..... 80 lb max. Rated load of 20 to 40 lb for bearing life of $1.5 \times 10^{9}$ revolutions
Axial Shaft Load ....... 80 lb max. Rated load of 20 to 40 lb for bearing life $1.5 \times 10^{9}$ revolutions
Starting Torque ........ 1.0 oz-in typical with IP64 seal or no seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typical with IP67 shaft seal

Moment of Inertia ... $5.2 \times 10^{-4} \mathrm{oz}$-in-sec ${ }^{2}$
Housing ....................Type 316 Stainless Steel
Bearings.....................Precision ABEC ball bearings
Weight..................... 1.5 lb typical

## Environmental

Storage Temp ............ $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Humidity...................98\% RH non-condensing
Vibration.................. 20 g @ 58 to 500 Hz
Shock....................... 75 g @ 11 ms duration
Sealing. IP50 standard; IP64, IP66, IP67 optional

MODEL 858 CLAMPING FLANGE 20 TYPE (A)


MODEL 858 SYNCHRO FLANGE 26 TYPE (B)


All dimensions are in millimeters with a tolerance of $\pm 0.17 \mathrm{~mm}$ unless otherwise specified.

WAVEFORM DIAGRAMS


NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALSA, B, Z̄ FOR HV AND H5 OUTPUTS ONLY.

Open Collector and Pull-Up


NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. INDEX IS POSITIVE GOING.

WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland Cable $^{\dagger}$ <br> Wire Color | 5-pin <br> M12 $^{* *}$ | 8-pin <br> M12** |
| :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 |
| +VDC | Red | 1 | 2 |
| A | White | 4 | 1 |
| A' $^{\prime}$ | Brown | -- | 3 |
| B | Blue | 2 | 4 |
| B' | Violet | -- | 5 |
| Z | Orange | 5 | 6 |
| Z' | Yellow | -- | 8 |
| Shield | Bare* | -- | -- |
| Case | Green | -- | -- |

*CE Option: Cable Shield (bare wire) is connected to internal case.
${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.
**CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

## Stainless Steel Encoders

## MODEL 865 T


ø6.5"

## FEATURES

## A C-Face Thru-Bore Encoder with Stainless Steel Housing Fits NEMA Size 56C Thru 184C Motor Faces (4.5" AK) <br> Slim Profile - Only 1.00" Deep <br> Incorporates Opto-ASIC Technology <br> Resolutions to 4096 CPR

The Model 865T C-Face encoder is a rugged, high resolution encoder designed to mount directly on NEMA C-Face motors. Both sides of the encoder are C-Face mounts, allowing additional C-Face devices to be mounted to this encoder. Unlike many C-Face kit type encoders, the Model 865T contains precision bearings and an internal flex mount, virtually eliminating encoder failures and inaccuracies induced by motor shaft runout or axial endplay. The advanced Opto-ASIC design provides advanced noise immunity necessary for many industrial applications. This encoder is ideal for applications using induction motors and flux vector control. The 1.00" thick model 865 T provides speed and position information for drive feedback in a slim profile. The thrubore design allows fast and simple mounting of the encoder directly to the accessory shaft or to the drive shaft of the motor, using the standard motor face (NEMA sizes 56C - 184C). The tough Type 316 Stainless Steel housing resists the corrosion and hazards of a caustic industrial environment.
COMMON APPLICATIONS
Motor Feedback, Velocity \& Position Control, Conveyors, Variable Speed Drives, Mixing \& Blending Motors, Assembly \& Specialty Machines

MODEL 865T ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 865T SPECIFICATIONS

Electrical
Input Voltage............ 4.75 to 28 VDC max for temperatures up to $70^{\circ} \mathrm{C}$
4.75 to 24 VDC for temperatures between $70^{\circ} \mathrm{C}$ and $100^{\circ} \mathrm{C}$
Input Current ........... 100 mA max with no output load Input Ripple.............. 100 mV peak-to-peak at 0 to 100 kHz
Output Format......... Incremental - Two square waves in quadrature with channel $A$ leading $B$ for clockwise shaft rotation, as viewed from the mounting face. See Waveform Diagrams.
Output Types.................Open Collector - 100 mA max per channe Pull Up - Open Collector with 2.2 K ohm internal resistor, 100 mA max per channel
Push-Pull - 20 mA max per channel Line Driver - 20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index........................ Once per revolution 0001 to 0474 CPR: Ungated 0475 to 4096 CPR: Gated to output A See Waveform Diagrams.
Max Frequency ........ 200 kHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Noise Immunity........ Tested to BS EN61000-4-2; IEC801-3; BS EN61000-4-4; DDENV 50141; DDENV 50204; BS EN55022 (with European compliance option); BS EN61000-6-2; BS EN50081-2

Quadrature............... $67.5^{\circ}$ electrical or better is typical,
Edge Separation $54^{\circ}$ electrical minimum at temperatures $>99^{\circ} \mathrm{C}$

Rise Time $\qquad$ Less than 1 microsecond

## Mechanical

Max Shaft Speed...... 6000 RPM. Higher shaft speeds may be achievable, contact Customer Service.
Bore Tolerance. +0.0015"/-0.000"
User Shaft Tolerances
Radial Runout ....... 0.005"

$$
\text { Axial Endplay......... }+0.050
$$

Moment of Inertia ... $3.3 \times 10^{-3}$ oz-in-sec ${ }^{2}$ typical Housing $\qquad$ Type 316 Stainless Steel Weight. 6 lb typical

## Environmental

| Storage Temp ........... $-25^{\circ}$ to $100^{\circ} \mathrm{C}$ |  |
| :---: | :---: |
| Humidity.................98\% RH non-condensing |  |
| Vibration................. 10 g @ 58 to 500 Hz |  |
| Shock...................... 50 g @ 11 ms duration |  |
| Sealing....................IP66 when mounted between two |  |
|  | C-Face devices with supplied gasket kit, or with H1 cover. IP50 if not installed in either manner. |

## MODEL 865T CONNECTOR OPTIONS



Model 865T shown with M12 connector option. Specify 5-pin or 8-pin using Ordering Guide.

MODEL 865T OPTIONAL HOUSING COVER (H2)


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified.

## WAVEFORM DIAGRAMS

Line Driver and Push-Pull


CLOCKWISE ROTATION AS VIEWED FROM THE MOUNTING FACE NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALSA $\bar{A}, \bar{B}, \bar{Z}$ F FOR HV OUTPUT ONLY

Open Collector and Pull-Up


> CLOCKWISE ROTATION AS VIEWED FROM THE MOUNTING FACE

NOTE: ALL DEGREEREFERENCES ARE ELECTRICAL DEGREES INDEX IS POSITIVE GOINGS

WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Gland <br> Cable $^{\dagger}$ <br> Wire Color | 5-pin <br> M12* <br> PU, PP, OC | 8-pin <br> M12 $^{*}$ |
| :---: | :---: | :---: | :---: |
| Com | Black | 3 | 7 |
| +VDC | Red | 1 | 2 |
| A | White | 4 | 1 |
| A' $^{\prime}$ | Brown | -- | 3 |
| B | Blue | 2 | 4 |
| B' $^{\text {M }}$ | Violet | -- | 5 |
| Z | Orange | 5 | 6 |
| Z' | Yellow | -- | 8 |
| Shield | Bare | -- | -- |

*CE Option: Use cable cordset with shield connected to M12 connector coupling nut.
Standard cable is 24 AWG conductors with foil and braid shield.

## Incremental Module and Modular Encoders

## MODEL 30 M



Ø30 mm/1.181"

## FEATURES

Large Air Gap and Tolerance to Misalignment
Resolutions of 1 to 1024 CPR ( 4096 PPR with Quadrature Counting)
Optional 2-Pole to 32-Pole Commutation
Sealing Options to IP69K
Operating Temperature Range $-40^{\circ}$ to $120^{\circ} \mathrm{C}$
Easy Alignment and Installation
The Model 30M is a compact, incremental encoder module with advanced magnetic sensing and signal processing technology. Featuring resolutions from 1 to 1024 CPR, commutation channels, several output types and two supply voltage options, it can be configured for a wide range of industrial, commercial and consumer feedback applications. With a non-contact magnetic sensor and optional sealing up to IP69K, the Model 30M can be applied in environments where dirt, dust and liquids are present.

## COMMON APPLICATIONS

Servo/stepper motor feedback, Mobile equipment speed and steering sensing, Timber processing machinery, Studio lighting and stage equipment control, Rotary valve position monitoring and control, Solar panel positioning, Vending machines, Punch presses, Tank level monitoring, Robotics

## MODEL 30M ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 30M SPECIFICATIONS

Electrical
Input Voltage............ 5 VDC $\pm 10 \%$ Fixed Voltage 4.5 to 28 VDC ( 4.5 to 20 VDC over $105^{\circ} \mathrm{C}$ )

Input Current ............ 80 mA max, 50 mA or less typical with no output load
Output Format......... Two square waves in quadrature with channel A leading B for clockwise magnet rotation as viewed from the encoder mounting face. Index gated to $A$ and $B$.
Output Types............ Open Collector
Open Collector with Differential Outputs Differential Line Driver (Meets RS422 at 5 VDC) Push-Pull All outputs 20 mA max per channel
Max Frequency ........ 350 kHz
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Min Edge Sep ........... $20^{\circ}$ electrical typical @ $25^{\circ} \mathrm{C}$
Accuracy... Typically within $\pm 0.7^{\circ}$ mechanical from true position. Accuracy improves at nominal air gap with minimized magnet runout, offset and endplay.
Mechanical/Environmental
Operating Temp ....... $-40^{\circ} \mathrm{C}$ to $120^{\circ} \mathrm{C}$; reduced to $110^{\circ} \mathrm{C}$ max above 200 KHz with 20 V input and $20 \mathrm{~mA} /$ channel output
Air Gap.. $\qquad$ 0.022 " nominal recommended

User Shaft Tolerances


## WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires

| Function | 8-pin <br> M12 | 8-pin <br> Header | 16-pin <br> Header |
| :---: | :---: | :---: | :---: |
| Com | 7 | 4 | 8 |
| +VDC | 2 | 2 | 6 |
| A | 1 | 8 | 12 |
| A' $^{\prime}$ | 3 | 6 | 10 |
| B | 4 | 5 | 9 |
| B' | 5 | 7 | 11 |
| Z | 6 | 1 | 5 |
| Z' | 8 | 3 | 7 |
| U | -- | -- | 2 |
| U' | -- | -- | 1 |
| V | -- | -- | 14 |
| V' | -- | -- | 13 |
| W | -- | -- | 4 |
| W' | -- | -- | -3 |

## 8-PIN MOLEX HEADER OPTION (C)



## 16-PIN MOLEX HEADER OPTION (V)



## 8-PIN M12 OPTION (K)



WAVEFORM DIAGRAMS


INDEX $\bar{Z}$


NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES. WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z} F O R$ HV OUTPUT ONLY.


## Incremental Module and Modular Encoders

## MODEL 30 MT



Ø30 mm/1.181"

FEATURES
Large Air Gap and Tolerance to Misalignment
Resolutions of 1 to 1024 CPR (4096 PPR with Quadrature Counting)
Sealing Options to IP69K
Operating Temperature Range $-40^{\circ}$ to $120^{\circ} \mathrm{C}$
Easy Alignment and Installation
The Model 30MT Accu-Coder ${ }^{\text {TM }}$ is a compact, incremental encoder module with advanced magnetic sensing and signal processing technology. With a built-in alignment feature, the threaded housing allows for quick, accurate air-gap setting. Featuring resolutions from 1 to 1024 CPR, several output types, and a wide range for supply voltage, it can be configured for a variety of industrial, commercial and consumer feedback applications. The noncontact magnetic sensor and optional sealing up to IP69K allows the Model 30MT to be applied in environments where dirt, dust and liquids are present.

## COMMON APPLICATIONS

Motor Feedback, Mobile Equipment Speed and Steering Sensing, Timber Processing Machinery, Studio Lighting and Stage Equipment Control, Rotary Valve Position Monitoring and Control, Solar Panel Positioning, Vending Machines, Punch Presses, Tank Level Monitoring, Robotics

MODEL 30MT ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 30MT SPECIFICATIONS

ELECTRICAL
Input Voltage............ 4.5 to 28 VDC ( 4.5 to 20 VDC over $105^{\circ} \mathrm{C}$ )
Input Current ........... 80 mA max, 50 mA or less typical with no output

Output format......... Two square waves in quadrature with channel A leading B for clockwise magnet rotation as viewed from the encoder mounting face. Index gated to $A$ and $B$.
Output Types............Open Collector
Open Collector with Differential Outputs Differential Line Driver (Meets RS422 at 5 VDC) Push-Pull
All outputs 20 mA max per channel
Max Frequency .. 350 kHz
Electrical Protection .. Reverse voltage and output short circuit protected.
Min Edge Sep ........... $20^{\circ}$ electrical typical @ $25^{\circ} \mathrm{C}$
$\qquad$ Typically within $\pm 0.7^{\circ}$ mechanical from true position. Accuracy improves at nominal air gap with minimized magnet runout, offset and endplay.

MECHANICAL/ENVIRONMENTAL
Operating Temp ....... $-40^{\circ} \mathrm{C}$ to $120^{\circ} \mathrm{C}$; reduced to $110^{\circ} \mathrm{C}$ max above 200 KHz with 20 V input and $20 \mathrm{~mA} /$ channel output
Air Gap ....................0.022" nominal recommended
User Shaft Tolerances


MECHANICAL DRAWING


WAVEFORM DIAGRAMS
 OPTIONAL COMPLEMENTARY SIGNALS $\bar{A}, \bar{B}, \bar{Z} F O R$ HV OUTPUT ONLY.

WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable. Trim back and insulate unused wires.

| Function | 8-pin <br> M12 |
| :---: | :---: |
| Com | 7 |
| +VDC | 2 |
| A | 1 |
| $A^{\prime}$ | 3 |
| B | 4 |
| $B^{\prime}$ | 5 |
| Z | 6 |
| $Z^{\prime}$ | 8 |

## UNIVERSAL MOUNTING ADAPTOR

 Stock \#176672Provides the following mounting patterns, $2 x$ @ 180́:

Ø1.142 [Ø29.0] B.C.
$\varnothing 1.280$ [ $\varnothing 32.5$ ] B.C.
Ø1.500 [Ø38.1] B.C.
$\varnothing 1.575$ [ $\varnothing 40.0$ ] B.C.
Ø1.811 [Ø46.0] B.C


NOTE: ALL HOLES ARE $\varnothing 0.125$ [ $\varnothing 3.2$ ] THRU, $2 \times$ @180 .

## Incremental Module and Modular Encoders

## MODELS $30 M$ \& $30 M T$ ACCESSORIES

## PREFERRED INSTALLATION

Contact EPC Application Support for assistance with additional installation options.


## OVER SHAFT MAGNET HOLDERS

| STOCK \# | $\phi$ ID | $\phi O D$ | $B L$ | $L$ |
| :---: | ---: | :---: | :---: | :---: |
| $176596-01$ | $3 / 16^{\prime \prime}\left(0.1875^{\prime \prime}\right)$ | 0.365 | 0.375 | 0.580 |
| $176597-01$ | $5 \mathrm{~mm}\left(0.1969^{\prime \prime}\right)$ | 0.365 | 0.375 | 0.580 |
| $176598-01$ | $6 \mathrm{~mm}\left(0.2362^{\prime \prime}\right)$ | 0.490 | 0.375 | 0.580 |
| $176599-01$ | $1 / 4^{\prime \prime}(0.2500 \prime)$ | 0.490 | 0.375 | 0.580 |
| $176600-01$ | $5 / 16^{\prime \prime}\left(0.3125^{\prime \prime}\right)$ | 0.490 | 0.475 | 0.680 |
| $176601-01$ | $8 \mathrm{~mm}(0.3150 \prime)$ | 0.490 | 0.475 | 0.680 |
| $176602-01$ | $3 / 8^{\prime \prime}(0.3750 \prime)$ | 0.615 | 0.475 | 0.680 |
| $176603-01$ | $10 \mathrm{~mm}(0.3937 \prime)$ | 0.615 | 0.475 | 0.680 |
| $176604-01$ | $1 / 2^{\prime \prime}(0.5000 \prime)$ | 0.740 | 0.750 | 0.955 |
| $176605-01$ | $14 \mathrm{~mm}(0.5512 \prime))$ | 0.740 | 0.750 | 0.955 |
| $176606-01$ | $5 / 8^{\prime \prime}(0.6250 \prime)$ | 0.865 | 0.750 | 0.955 |



## PRESS IN/ON MAGNET HOLDER

Stock \# 176607-01


Press In/On Magnet Holder

## MATING CABLES/CORDSETS

| Molex Mating Cables (24 AWG Wires) |  |
| :--- | :--- |
| Stock \# | Description |
| $\mathbf{0 7 5 2 3 0}$ | 8-pin Molex Mating Connector w/ 24" Cable |
| $\mathbf{0 7 5 2 3 2}$ | 16-Pin Molex Mating Connector w/ 24" Cable |


| M12 Mating Cordsets |  |
| :--- | :--- |
| Stock \# | Description |
| $\mathbf{0 7 5 1 0 0}$ | 8-Pin M12 Mating Cordset, 0.5 Meters |
| $\mathbf{0 7 5 1 0 1}$ | 8-Pin M12 Mating Cordset, 2 Meters |
| $\mathbf{0 7 5 1 0 2}$ | 8-Pin M12 Mating Cordset, 4 Meters |
| $\mathbf{0 7 5 1 0 3}$ | 8-Pin M12 Mating Cordset, 6 Meters |
| $\mathbf{0 7 5 1 0 4}$ | 8-Pin M12 Mating Cordset, 10 Meters |

## WHEN TO CHOOSE A MAGNETIC ENCODER MODULE

Magnetic encoder modules can be used in a wide range of applications, including, but certainly not limited to, the following:

- Servo/stepper motor feedback
- Mobile equipment speed and steering sensing
- Timber processing machinery
- Studio lighting and stage equipment control
- Rotary valve position monitoring and control
- Solar panel positioning
- Vending machines
- Punch presses
- Tank level monitoring
- Robotics


The Model 30M Incremental Magnetic Encoder Module has 3 connector options.

There are many points to consider when trying to determine if an encoder module is the best solution for your application.

1. You need an encoder with a bearingless design. In the vast majority of applications, an encoder with bearings is the best choice, because it provides an easier installation and a more stable platform for the encoder to run on. However, there are instances where a bearingless encoder is a better option:

- In your application, there are factors that are hard on bearings. Magnetic encoder modules tend to be more tolerant to shock and vibration - factors that typically shorten bearing life. If your encoder will be subjected to factors that are hard on bearing life, a magnetic encoder module might be the right encoder solution for your application.
- You need an encoder that can work in a high-speed application. An encoder's bearings often limit operational speed to 12,000 RPMs or less. If you need to run at higher speeds, a bearing-less module might be the solution.
- Cost is a major factor. Since encoder modules have no bearings and associated support parts, they often cost less and can be more economical. If cost is a factor, an encoder module might be the right solution.

2. You have limited space. It can happen for different reasons. Maybe the encoder was overlooked in the design phase, and you suddenly find yourself with very little space for a key component in your configuration. Maybe the constraints of your machine's design simply won't allow more space. In any case, magnetic encoder modules tend to be compact in size, but - when designed well - will still give you the accurate feedback and motion control you need.
3. You need versatile mounting options. The "magnetic" in "magnetic encoder module" gives you some options you may not have with typical encoders. Even with the tolerance for a large air gap and tolerance for misalignment, you may still have a tricky installation that requires a creative solution. Both the Model 30M and the Model 30MT have been designed with that in mind, and they are easy to mount and install.


The Model 30MT Incremental Magnetic Encoder Module comes with a threaded housing.
4. You need a heavy-duty seal on your encoder. Not all magnetic encoder modules offer heavy-duty sealing options, so be sure to check the IP Ratings (see page 137 for more information). If you need protection from washdown, you cannot settle for IP50. Conversely, if your encoder will be fairly well protected, it might not make sense to pay for a higher IP Seal than you need. EPC's Model 30M and Model 30MT are compact magnetic encoder modules with sealing options up to IP69K and an operating temperature range of $-40^{\circ}$ to $120^{\circ} \mathrm{C}$, so it can handle the most extreme industrial environments.

With a large air gap and tolerance to misalignment, up to 1024 CPR (4096 PPR with Quadrature Counting), optional 2,4 or 8 pole commutation, and easy alignment and installation, the Model 30 M or the threaded Model 30MT are excellent solutions when you need a magnetic encoder module. Contact EPC today and you'll talk to real engineers who can help you incorporate the 30M or 30MT into your application.

## Incremental Modules and Modular Encoders

## MODEL 121



Ø2.1"
Patent \#6,608,300B2

## FEATURES

Simple, Hassle Free Mounting
Accepts Larger Shafts up to $5 / 8$ " (or 15 mm )
Up to 12 Pole Commutation Available
$0^{\circ}$ to $100^{\circ} \mathrm{C}$ Operating Temperature Available Patented Design

## Includes IP50 Dust Seal Kit

EPC has taken the performance of modular encoders to a new level with the Model 121 Auto-Aligning Modular Encoder. This new and innovative design requires no calibration, gapping or special tools for hassle-free installation. The Model 121 incorporates the latest Opto-ASIC technology for enhanced performance. Common problems with other modular encoder designs are warping and deflection, caused by their extensive use of plastic, both of which are virtually eliminated by the Model 121's all metal construction. For brushless servo motor applications, the Model 121 can be specified with three commutation tracks to provide motor feedback. The optional $100^{\circ}$ C temperature capability allows servo motors to operate at higher power outputs and duty cycles.
COMMON APPLICATIONS
Servo Motor Control, Robotics, Specialty Assembly Machines, Digital Plotters, High Power Motors

MODEL 121 ORDERING GUIDE
Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


## MODEL 121 SPECIFICATIONS

Electrical
Input Voltage 5 VDC $+10 \%$ Fixed Voltage
Input Current........... $130 \mathrm{~mA} \max$ (< 100 mA typical) with no output loadwith no output load
Output Format.. cremental - Two square waves in quadrature with channel $A$ leading $B$ for clockwise shaft rotation, as viewed from the mounting face. Index optional.
Output Types............. Open Collector - 20 mA per channel max Push-Pull - 20 mA per channel max Line Driver -20 mA max per channel (Meets RS 422 at 5 VDC supply)
Index......................... Once per revolution gated to channel A. Contact Customer Service for additional gating options.
Max Frequency ........ 100 kHz standard, 200 kHz , and 300 kHz optional
Electrical Protection .. Reverse voltage and output short circuit protected. NOTE: Sustained reverse voltage may result in permanent damage.
Quadrature............... $67.5^{\circ}$ electrical or better is typical, $54^{\circ}$
Edge Separation..........electrical minimum at temperatures $>99^{\circ} \mathrm{C}$
Accuracy.................. Within $0.1^{\circ}$ mechanical from one cycle to any other cycle, or 6 arc minutes
Commutation............ Optional - three $120^{\circ}$ electrical phase tracks for commutation feedback. ( $4,6,8$, or 12 poles. Others available upon request.)
Comm. Accuracy ...... $1^{\circ}$ mechanical
Mechanical
Max. Shaft Speed...... Determined by maximum frequency response
Bore Tolerance ......... $+0.0007^{\prime \prime}$ (max) -0.0000 " (Based on H7 bore fit for g6 shaft Class LC5 per ANSI B-4.1 standard)
User Shaft Tolerance
Radial Runout .......0.002" max
Axial End Play........ $\pm 0.015^{\prime \prime}$ for CPR <= 512
$\pm 0.010$ " for CPR 513 to 1250 $\pm 0.005^{\prime \prime}$ for CPR > 1250
Moment of Inertia ... $2.5 \times 10^{-4}$ oz-in-sec ${ }^{2}$
Max. Acceleration ... $5 \times 10^{5} \mathrm{rad} / \mathrm{sec}^{2}$
Housing .....................All Metal Aluminum and Zinc Alloy
Weight. 4 oz typical

## Environmental

Storage Temp ........... $-25^{\circ}$ to $100^{\circ} \mathrm{C}$
Humidity.................... $98 \%$ RH non-condensing
Vibration................... 10 g @ 58 to 500 Hz
Shock..
$.50 \mathrm{~g} @ 11$ ms duration

MODEL 121 AUTO-ALIGNING MODULAR (A)


All dimensions are in inches with a tolerance of +0.005 " or +0.01 " unless otherwise specified. Metric dimensions are given in brackets [mm].


## WAVEFORM DIAGRAMS



NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES WAVEFORM SHOWN WITH OPTIONAL COMPLEMENTARY SIGNALS A, B, Z FOR HV OUTPUT ONLY.


CW ROTATION OF SHAFT AS VIEWED
LOOKING AT THE ENCODER FACE.
NOTE: ALL DEGREE REFERENCES ARE ELECTRICAL DEGREES.

WIRING TABLE
For EPC-supplied mating cables, refer to wiring table provided with cable.
Trim back and insulate unused wires.

| Function | Flying Leads Cable ${ }^{\dagger}$ Wire Color |
| :---: | :---: |
| Com | Black |
| +VDC | White |
| A | Brown |
| $\mathrm{A}^{\prime}$ | Yellow |
| B | Red |
| $\mathrm{B}^{\prime}$ | Green |
| Z | Orange |
| Z' | Blue |
| U | Violet |
| U' | Gray |
| V | Pink |
| V' | Tan |
| W | Red/Green |
| W' | Red/Yellow |
| Shield | Bare* |
| *CE Option: Cable shield (bare wire) is connected to internal case. <br> ${ }^{\dagger}$ Standard cable for non-commutated models is 24 AWG For commutated units, conductors are 28 AWG. |  |

## DOES YOUR ENCODER SIGNAL NEED SOME HELP?

## One Is Better than Four: One Unit Can Convert, Split, Repeat and Test Your Encoder Signal

Generally, when you hook up your encoder, it's already configured to provide the correct digital outputs. Those outputs then feed directly to a counter, controller, or other device. In some applications, however, the encoder signal needs optimization to reach the receiving device over long distances. Or you need to provide the encoder signal to more than one device. Or you need to change the type of output signal. That's where EPC's RX/TX products come in: product variations are available to convert, repeat, or split the signal (see pages 118 - 120).

Our RX/TXD, however, combines all of these capabilities into a compact DIN rail mountable unit - plus, it can test your signal. The RX/TXD all-in-one:

- Can be configured as a level changer, signal converter, line repeater, splitter, or tester.

- Splits one input signal into two or three outputs.
- Has LED indicators for encoder power and signal presence.
- Accommodates a variety of digital signal types (RS422, NPN, PNP, TTL, etc.) and voltages (5VDC or 5-24VDC) as both input and output options, allowing for use with all EPC encoders.
- Is compact and lightweight. The DIN Rail mountable PC/ABS housing makes for easy and versatile installation.
- Has LED indicators for encoder power and signal presence.
- Is easy to use. All connections can be made via easily accessible screw terminals to a detachable 17-pin connector.


## When to Use the RX/TXD

## Signal Converter

In many retrofit or upgrade projects, your encoders may need to interface with newer devices - and they may have mismatched input requirements. That's when the RX/TXD's level changer/conditioner capability is ideal. For example, a 24 VDC open collector output can be converted to a 5VDC RS422 compatible differential line-driver - an output type better suited for long cable runs or electrically noisy environments. It keeps your signal clean and consistent.

## Signal Splitter

When a single encoder has to provide signals to multiple devices, the RX/TXD can split one signal into two or three identical outputs. Using the splitter capability can eliminate the need for multiple encoders, which gives you greater design flexibility.

## Signal Repeater

When your encoder signal needs to transmit over long distances, the RX/TXD can be configured as a signal repeater. This not only eliminates the risk of voltage drop, it also ensures your signal integrity.


All inputs and outputs may not be present, depending on the RX/TXD version.

When you're troubleshooting a closed-loop control system, you need to know if the encoder is functioning properly so you don't waste time looking at the wrong components. The RXITXD does that for you; it has a series of LED lights on the front panel that tell you if the power is on, and if it is still receiving a signal.

The RX/TXD also accommodates voltages in a regulated range of 5-24VDC or fixed 5VDC as both input and output options, as well as a variety of digital signal types, including RS422, NPN, PNP, and TTL (and more - contact us for more options).

## Get it FAST

As with all our products, EPC's standard lead time on the RX/TXD is just 4 to 6 business days, with expedite options available. And of course, it's covered by EPC's industry-leading 3-year warranty. View the datasheet on pages 116 - 117, or go to encoder.com to configure and download a 3D model to drop into your application drawing.

For more information on how the RXITXD can fit into your application, contact EPC today. When you call EPC, you'll talk to real engineers and encoder experts who can answer your toughest, most technical encoder questions. Give us a call.

## Accessories

## R X / TXD receiver-transmitter unit versatile encoder interface



FEATURES<br>DIN Rail Mount<br>Level Changes from Vcc to 5V<br>Signal Conditioner or Repeater for Distance Transmission 2 or 3 Way Splitter/Level Changer<br>Encoder Tester/Verifier

This lightweight DIN rail mountable unit, Line Driver and Line Receiver is composed of a PC/ABS self-extinguishing material blend. Configurable as a level changer, line repeater, splitter or encoder tester, the RX/TXD will accept TTL, RS422, RS485, PP, NPN, NPN OC, or PNP encoder inputs at 5V, or HTL, PP, NPN, NPN OC \& PNP at 5-24V. It will provide up to three outputs in any combination of TTL, RS422, RS485, PP, at 5V, or HTL, PP at 5-24V. A series of LEDs on the front panel indicates power and signal presence. Connections are made via the easily accessible screw terminals as standard. This device may be used as both a Line Driver and Line Receiver.

## RX/TXD ORDERING GUIDE

Blue type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.


[^10]
## RX/TXD SPECIFICATIONS

## Electrical

Input Voltage............ 5 V to 24 V Max
Current
Consumption............ 250 mA Typical
Repeater Output
Voltage ..................... 5 V or Vcc
Frequency
Response.................Up to 800 Khz
Output Current ........ 30 mA / Channel Max

## Mechanical

Weight. $\qquad$ 250g
Enclosure C/ABS, IP20
Terminal Screw Type 30/12 AWG

## RX/TXD RECEIVER-TRANSMITTER



All inputs and outputs may not be present, depending on the $\mathrm{RX} / T \mathrm{XD}$ version.


## Accessories

## RX / TX CONVERTER



## RX/TX CONVERTER <br> ORDERING INFORMATION <br> (Specify stock \# when ordering)

Differential $=A, A^{\prime}, B, B^{\prime}, Z, Z^{\prime}$
Single Ended $=A, B, Z$

| Stock \# | Channel 1 |  | Channel 2 |  |
| :---: | :---: | :---: | :---: | :---: |
|  | INPUT | OUTPUT | INPUT | OUTPUT |
|  | Differential Line Reciever MAX 3095 | Single Ended Push Pull Output 7272 | Single <br> Ended <br> 7272 | Differential Line Driver 7272 |
| 100020-1 | 5 V | Vcc | $5 \mathrm{~V}, \mathrm{OC}^{1}$ | Vcc |
| 100020-2 | 5 V | Vcc | $5 \mathrm{~V}, \mathrm{OC}^{1}$ | 5 V |
| 100020-3 | 5 V | Vcc | $5 \mathrm{~V}^{2}$ | Vcc |
| 100020-4 | 5 V | Vcc | $5 \mathrm{~V}^{2}$ | 5 V |
| 100020-5 | $6-12 \mathrm{~V}$ | Vcc | $5 \mathrm{~V}, \mathrm{OC}^{1}$ | Vcc |
| 100020-6 | 6-12V | Vcc | $5 \mathrm{~V}, \mathrm{OC}^{1}$ | 5 V |
| 100020-7 | 6-12V | Vcc | $5 \mathrm{~V}^{2}$ | Vcc |
| 100020-8 | 6-12V | Vcc | $5 \mathrm{~V}^{2}$ | 5 V |
| 100020-9 | 13-24V | Vcc | $5 \mathrm{~V}, \mathrm{OC}^{1}$ | Vcc |
| 100020-10 | $13-24 \mathrm{~V}$ | Vcc | $5 \mathrm{~V}, \mathrm{OC}^{1}$ | 5 V |
| 100020-11 | $13-24 \mathrm{~V}$ | Vcc | $5 \mathrm{~V}^{2}$ | Vcc |
| 100020-12 | 13-24V | Vcc | $5 \mathrm{~V}^{2}$ | 5 V |

${ }^{1}$ OC- Open Collector input designed with a 2 k pull-up resistor for an open collector output encoder or device.
${ }^{2}$ Inputs can be from devices with pull-up, push-pull or TTL type outputs.
${ }^{3} \mathrm{~V}$ cc should range between 5-24 VDC

## FEATURES

The RX/TX Converter converts a Push-Pull or NPN encoder output to an RS422 compatible differential Line Driver output. In addition, it will also convert Line Driver/RS422 encoder output to single ended signals (Push-Pull) for compatibility with certain PLC's.
Each converter has two independent channels: Channel 1 is equipped with a differential Line Receiver on the input. It then converts these differential signals ( $A, A^{\prime}, B, B^{\prime}, Z, Z^{\prime}$ ) to Push-Pull output signals ( $A, B, Z$ ), with an amplitude equivalent to Vcc.
Channel 2 will convert single ended signals from a Push-Pull or NPN Open Collector encoder to Differential Line Driver signals. Differential Line Driver signals include complementary outputs $A^{\prime}, B^{\prime}$, and $Z^{\prime}$ which offer greater immunity to electrical noise, signal distortion, and interference, especially with long cable runs.

## APPLICATIONS

To provide differential signals for data transmission over long distances between a push-pull, or NPN open collector transmitter and receiver. To enable devices with different output/input circuits to be connected. To properly terminate differential signals to eliminate/reduce signal distortions.

## SPECIFICATIONS

| Supply Source (Vcc) ................... 5 to 24 VDC |  |
| :---: | :---: |
| Current Consumption................ 20 mA max (plus encoder and output load requirements) |  |
| Max Frequency......................... Up to 1 MHz |  |
| Enclosure.................................IP54 (dust proof) |  |
| Earth Circuit ............................. Grounded to Case |  |
| Input Voltage ............................ Channel 1: 24 VDC Max Diff |  |
| Channel 2: 5 VDC Max |  |
| Output Voltage .......................... Channel 1: Vcc |  |
|  | Channel 2: 5 VDC or Vcc |
| Output Current......... | ... $30 \mathrm{~mA} /$ Channel Max |



All dimensions are in inches with a tolerance of $+0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified. Metric dimensions are given in brackets [mm].

## RX/TX REPEATER



RX/TX REPEATER ORDERING INFORMATION
(Specify stock \# when ordering)
Differential $=A, A^{\prime}, B, B^{\prime}, Z, Z^{\prime}$
For differential signals only

|  | INPUT | OUTPUT |
| :---: | :---: | :---: |
| Stock \# | Differential Line <br> Receiver - MAX 3095 | Differential Line <br> Driver 7272 |
| $100020-13$ | 5 V | 5 V |
| $100020-14$ | 5 V | $\mathrm{Vcc}^{2}$ |
| $100020-15$ | $6-12 \mathrm{~V}$ | 5 V |
| $100020-16$ | $6-12 \mathrm{~V}$ | $\mathrm{Vcc}^{2}$ |
| $100020-17$ | $13-24 \mathrm{~V}$ | $5 \mathrm{~V}-$ |
| $100020-18$ | $13-24 \mathrm{~V}$ | $\mathrm{Vcc}^{2}$ |

${ }^{1}$ Vcc should range between 5-24 VDC.
${ }^{2}$ Outputs will be equivalent to voltage applied to Vcc (Pin P1-15)

## FEATURES

The RX/TX Repeater retransmits signals from an encoder output in order to drive signals over a longer distance with reduced noise and distortion free waveforms. The input is equipped with a Differential Line Receiver and a Differential Line Driver. It takes the differential signals ( $A, A^{\prime}, B, B^{\prime}, Z, Z^{\prime}$ ) , squares the signals up, and then repeats the signals at the outputs.

Benefits are greater immunity from electrical noise, signal distortion, and interference, especially with long cable runs. The output signal can be 5 VDC or an amplitude equivalent to Vcc.

## APPLICATIONS

Repeat differential signals for data transmission over long distances. To properly terminate differential signals to eliminate/reduce signal distortions. Increase output current drive capability in order to drive multiple receivers

## SPECIFICATIONS

Supply Source (Vcc)......... 5 to 24 VDC
Current Consumption ..... 20 mA max (plus encoder and output load requirements)
Max Frequency ............... Up to 1 MHz
Enclosure........................ IP54 (dust proof)
Earth Circuit ................... Grounded to Case
Input Voltage................... 24 VDC Max Diff
Output Voltage................ 5 VDC or Vcc
Output Current ............... $30 \mathrm{~mA} /$ Channel Max


All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01^{\prime \prime}$ unless otherwise specified. Metric dimensions are given in brackets [mm].

## Accessories

## RX/TX SPLITTER



## RX/TX SPLITTER ORDERING INFORMATION

(Specify stock \# when ordering)
Differential $=A, A^{\prime}, B, B^{\prime}, Z, Z^{\prime}$
Single Ended $=A, B, Z$

| Stock \# | INPUT TYPE | INPUT VOLTAGE <br> (From Encoder) | CH1 | CH. 2 |
| :---: | :---: | :---: | :---: | :---: |
| 100020-20 | Differential | 5 V | 5 V | 5 V |
| 100020-21 | Differential | 5 V | Vcc | Vcc |
| 10002022 | Differential | 5 V | Vcc | 5 V |
| 100020-23 | Differential | 6-12V | 5 V | 5 V |
| 100020-24 | Differential | 6-12V | Vcc | Vcc |
| 100020-25 | Differential | 6-12V | Vcc | 5 V |
| 100020-26 | Differential | $13-24 \mathrm{~V}$ | 5 V | 5 V |
| 100020-27 | Differential | $13-24 \mathrm{~V}$ | Vcc | Vcc |
| 100020-28 | Differential | $13-24 \mathrm{~V}$ | Vcc | 5 V |
| 100020-29 | Single Ended | 5 Voc | 5 V | 5 V |
| 100020-30 | Single Ended | 5-24V OC | Vcc | Vcc |
| 100020-31 | Single Ended | 5 V 0 C | Vcc | 5 V |
| 100020-32 | Single Ended | 5 V PP, PU, TTL | 5 V | 5 V |
| 100020-33 | Single Ended | $5-24 \mathrm{~V}$ PP, PU, TTL | Vcc | Vcc |
| 100020-34 | Single Ended | 5 V PP, PU, TTL | Vcc | 5 V |

${ }^{1}$ Choose an input channel of signal type differential or single ended that is to be split into two output channels. These input signals are typically from an incremental encoder. Refer to the block diagram below for the input and output signal flow.
${ }^{2}$ For OC type inputs, 2 K ohm resistors are used for pull-up internally.
${ }^{3}$ The output channels may be used in the differential mode ( $\mathrm{A}, \mathrm{A}^{\prime}, \mathrm{B}, \mathrm{B}^{\prime}, \mathrm{Z}, \mathrm{Z}^{\prime}$ ) or as $A, B, Z(P P)$ referenced to circuit common.
${ }^{4} \mathrm{~V}$ cc is the RXTX Splitter supply voltage and ranges from 5 to 24 VDC.
${ }^{5}$ Single ended input voltage must be less than or equal to the output voltage (Vcc or 5 V ), Whichever is applicable.
${ }^{6} \mathrm{~V}$ Vc $(5-24 \mathrm{VDC})$ or a PCB generated 5 V is supplied to the output drivers (channels).

## FEATURES

The RX/TX Splitter has one input and two separate output channels. There are two different types of inputs available. One input type is a differential line receiver where differential input signals ( $A, A^{\prime}, B, B^{\prime}, Z, Z^{\prime}$ ) are split into two identical differential output channels. Alternatively, the input can be configured for a single ended Push-Pull, NPN, Open Collector, or Pull-Up encoder ( $A, B, Z$ ), which will split the signal into two independent differential line driver outputs ( $A, A^{\prime}, B, B^{\prime}, Z, Z^{\prime}$ ). Refer to the block diagram below for the signal flow through the device. Line Driver signals include complementary outputs $A^{\prime}, B^{\prime}$, and $Z^{\prime}$, and offer greater immunity from electrical noise, signal distortion, and interference especially with long cable runs. The output signal can be approximately 5 VDC or a voltage amplitude equivalent to the RXTX supply (Vcc).
To order, choose the type of input (differential or single ended), the expected encoder signal voltage and the voltage output options. Use the RXTX Splitter ordering guide below to establish the stock number.

## APPLICATIONS

To split differential, or single ended signals for data transmission over long or short distances to two different devices. To properly terminate differential signals to eliminate/reduce signal distortion. To increase output current drive capability in order to drive multiple receivers. To split the input signal and provide the two output channel drivers with differing voltage outputs.

## SPECIFICATIONS

Supply Source (Vcc)......... 5 to 24 VDC
Current Consumption ..... 20 mA max (plus encoder \& output load requirements)
Max Frequency ............... Up to 1 MHz
Enclosure......................... IP54 (dust proof)
Earth Circuit ................... Grounded to Case
Input Voltage................... 24 VDC Max Diff
Output Voltage.......................... 5 VDC or Vcc
Output Current. $\qquad$ $.30 \mathrm{~mA} /$ Channel Max


NOTES UNLESS OTHERWISE SPECIFIED

1. TERMINATE CABLE SHIELD/DRAIN WIRES TO THE CASE EERMINAL OF P1 AND P2, IFAPPLICABLE. BARE CONDUCTORS MUST BE ELECTRICALLY INSULATED FROM THE CIRCUIT
BOARD WITH A NONCONDUCTIVE SIEEVE SUCH BOARD WITH A NONCONDUCTIVE SLEEVE SUCH A
HEAT SHRINK TUBING. ECOMMENDED CABLE
COMPLEMENTARY ENCO R DFFRENTIAL LOW CAPACITANCE, TWISTED-SHIELDED PAIR: SEE ACCESSORIES SECTION FOR 4XXC CABLES/CONNECTORS, 4XXC CABLES MUST HAVE OUTER INSULATION STRIPPED OFF IN ORDER TO FIT THROUGH CABLE ENTRY GLANDS.
2. SEE CONFIGURATION ORDERING GUIDE FOR INPUT/OUTPUT

P2-14 (VCc) or P2-15 (5V) CAN BE XS MODEL NUMBER
. P2-14 (VCC) Or P -15 (5V) CAN BE USED TO POWER ENCODER.
5. P1-15 (5-24VDC IN (VCC)) IS FOR CUSTOMER SUPPLIED

POWERTO OPERATE RXTX


## ENCODER POWER SUPPLY

## FEATURES



A clean source of dedicated power for your encoder is an important factor when designing a reliable system. Now available from EPC are small, easily mounted DIN Rail power supplies specifically chosen to power encoders. Designed for space efficiency, these compact power supplies are available in 5,12 , or 24 VDC.
Easy to see LED indicators show the power supply is working properly. Screw type terminals easily accommodate wires from AWG 24 to 14 while snap-on DIN-Rail mounting (TS35/7.5 or TS35/15) allows the unit to sit safely and firmly on the rail with no tools required even to remove. The shock proof housing is both UL and CE approved. These supplies have been tested to work with all our Accu-Coders ${ }^{T M}$.

## SPECIFICATIONS

## Electrical

Nominal Input Voltage......... 100 to 240 Vac / 47 to 63 Hz Input Voltage Range ............. 90 to $265 \mathrm{Vac} / 47$ to 63 Hz or 120 to 370 VDC
Frequency. $\qquad$ 100 kHz min
Inrush Surge Current............ < 10 A @ 115Vac, < 18A @ 230 Vac Input Fuse $\qquad$ .T2A / 250 Vac

| EPS-5V | EPS-12V | EPS-24V |
| :---: | :---: | :---: |
| Nominal Output Voltage .......... 5 VDC | 12 VDC | 24 VDC |
| Tolerance .............................. 1 \% | $\pm 1$ \% | $\pm 1$ \% |
| Nominal Output Current......... 3 A | 1.5 A | 0.75 A |
| Efficiency .............................. > 75\% | > 77 \% | > 77 \% |
| Ripple and Noise .................... 50 mV | 50 mV | 50 m |

## Mechanical

Dimensions ................................... 3.54" L x 0.89" W x 4.5" D
( $90 \mathrm{~mm} \mathrm{~L} \times 22.5 \mathrm{~mm} \mathrm{~W} \times 115 \mathrm{~mm}$ D)
Connection Type $\qquad$ Screw Clamp Connection Mounting $\qquad$ DIN-Rail TS35/7.5 or TS35/15

ENCODER POWER SUPPLY ORDERING INFORMATION
(Specify stock \# when ordering)
Differential $=A, A^{\prime}, B, B^{\prime}, Z, Z^{\prime}$
Single Ended $=A, B, Z$

## Stock \#

100043.................................. 12 V Output (EPS-5V)
100044..................
100045. .12 V Output (EPS-12V)
24V Output (EPS-24V)

## Approvals and Standards

UL/cUL...UL 508 / UL 1310 Listed, Class 2 TUV........EN 60950
CE .........EN 50081-1 / EN 55022 Class B, EN 61000-3-2 EN 61000-3-3, EN 50082-1 / EN 55024
FCC ........Class B

## PROGRAMMABLE ENCODER ACCESSORIES

## USB PROGRAMMING KIT

Kit includes software, USB Programming Module, and 2-meter Interface Cable with specified connector. See Accessories for individual Interface Cables.


## USB PROGRAMMING MODULE

PR1-001.
USB Programming Module

## PROGRAMMING INTERFACE CABLE (2 METER)

| 075233-02 | 10-Pin MS Style Interface Cable |
| :---: | :---: |
| 075234-02 | 7-Pin MS Style Interface Cable |
| 075235-02 | 6-Pin MS Style Interface Cable |
| 075236-02 | 5-Pin M12 Interface Cable |
| 075237-02 | 8-Pin M12 Interface Cable |
| 075238-0 | 9-Pin D-Sub Interface Cable |
| 075240-02 | Gland Interface Cable |



## CONNECTORS \& CABLES

## MATING CONNECTORS

| Stock \# | Description |  |
| :---: | :---: | :---: |
| 080014. | MS3106A14S-6S-619 | 6-pin MS |
| 080174. | MS3106A16S-1S-618 | 7-pin MS |
| 080113. | MS3106A18-1S-618. | 10-pin MS |
| 080325-0 | AIM 40-9709S ......... | 9-pin D-sub Miniature |
| 080359. |  | 12-pin M23 |
| 080364. |  | 16-pin 23, CE |
| 080365. |  | 16-pin M23 |
| 080023. | KPT06F14-19S | 19-pin Bayonet |
| 080376-01 |  | 10-pin Industrial Clamp |
| 080021.. | KPT06F12-10S | 10-pin Bayonet |

## ELECTRICAL CABLE

Stock \# $\quad$ Description

070063............................... High Temperature Cable
070264...............................Cable for Absolute Encoders - Models 925 and 958

## PRE-WIRED CABLE AND MATING CONNECTOR ASSEMBLIES

To order a pre-wired cable and connector assembly complete the boxes to indicate the connector style, cable length, and output configuration.
INCREMENTAL ENCODER CABLE ASSEMBLIES
(Cable is 24 AWG foil and braid shielded and is rated to $105^{\circ} \mathrm{C}$ )


ABSOLUTE ENCODER CABLE ASSEMBLIES
(Cable is 28 or 30 AWG foil and braid shielded and is rated to $70^{\circ} \mathrm{C}$ )


## MOLEX HEADER CORDSETS for use with Model 30M

| Stock \# | Description | Length |
| :---: | :---: | :---: |
| 075230... | . 8-pin Molex Mating Connector . | 24 inches |
| 075232. | . 16-pin Molex Mating Connector | 24 inches |

M 12 ( 12 M M) CORDSETS (Always use a shielded cordset)

8-CONDUCTOR CORDSETS (FOR USE WITH 8-PIN M12 CONNECTORS)

| Shield not connected to Coupling Nut |  |  |
| :---: | :---: | :---: |
| Stock \# | Description | Length |
| 075100.. | RKC8T-0.5/S618 | 0.5 Meters (1.64 ft) |
| 075101. | .RKC 8T-2/S618. | 2 Meters (6.56 ft) |
| 075102. | .RKC 8T-4/S618. | 4 Meters ( 13.12 ft ) |
| 075103. | .RKC 8T-6/S618. | 6 Meters (19.69 ft.) |
| 075104. | .RKC 8T-10/S618 | 10 Meters (32.81 ft) |
| Shield connected to Coupling Nut (use for CE option) |  |  |
| Stock \# | Description | Length |
| 075200. | RKS 8T-2. | 2 Meters (6.56 ft) |
| 075201. | RKS 8T-4. | 4 Meters (13.12 ft) |
| 075202. | RKS 8T-6..... | 6 Meters (19.69 ft) |
| 075203. | RKS 8T-10.... | 10 Meters (32.81 ft) |

## 3, 4, AND 5-CONDUCTOR CORDSETS (FOR USE WITH 5-PIN M12 CONNECTORS)

Shield not connected to Coupling Nut

| Stock \# | Description | Length |
| :---: | :---: | :---: |
| 075205. | 3-Conductor RK 4T-1/S618 | 1 Meter (3.28 ft) |
| 075206. | 4-Conductor RK 4.4T-1/S618. | . 1 Meter (3.28 ft) |
| 075204. | .5-Conductor RK 4.5T-1/S618. | . 1 Meter (3.28 ft) |
| Shield connected to Coupling Nut (use for CE option) |  |  |
| Stock \# | Description | Length |
| 075211. | 5-Conductor | 1 Meter (3.28 ft) |

## CONNECTORS \& CABLES

## POWER AND COMMUNICATION CABLES FOR ETHERNET ENCODERS



## BORE \& SHAFT ACCESSORIES

## BORE ADAPTORS

INDIVIDUAL BORE ADAPTORS

| Stock \# | Description |  |
| :---: | :---: | :---: |
| 176252. | .. 1.000" ID Bore Adaptor for Model 25T |  |
| 176253. | .. 7/8" ID Bore Adaptor for Model 25T |  |
| 176254.. | .. 5/8" ID Bore Adaptor for Model 25T |  |
| 176255.. | .. 25 mm ID Bore Adaptor for Model 25T |  |
| 176256.. | .. 24 mm ID Bore Adaptor for Model 25T |  |
| 176257.. | .. 20 mm ID Bore Adaptor for Model 25T |  |
| 176258.. | .. 19 mm ID Bore Adaptor for Model 25T |  |
| $176277 .$. | .. 3/4" ID Bore Adaptor for Model 25 T |  |
| 176283. | .. 1/2" ID Bore Adaptor for Model 25T |  |
| 176313. | .. 14 mm ID Bore Adaptor for Model 25T |  |
| 176315. | .. 15 mm ID Bore Adaptor for Model 25T |  |
| 176325.. | .. 12 mm ID Bore Adaptor for Model 25T |  |
| 176328.. | .. 1/4" ID Bore Adaptor for Model 25T |  |
| 176329.. | .. 6 mm ID Bore Adaptor for Model 25T |  |
| 176335.. | .. 8 mm ID Bore Adaptor for Model 25T |  |
| 176336. | .. 10 mm ID Bore Adaptor for Model 25T | Various Bore |
| 176337.. | .. 11 mm ID Bore Adaptor for Model 25T | Adaptors |
| 176338.. | . 5/16" ID Bore Adaptor for Model 25T |  |
| 176339.. | .. 3/8" ID Bore Adaptor for Model 25T |  |

BORE ADAPTOR KITS

## Stock\# <br> Description

260-BK97............................ Small Metric Bore Adaptor Kit for 260. Includes 6, 8, \& 10 mm
260-BK98..................... Large Metric Bore Adaptor Kit for 260. Includes 11, 12, \& 14 mm
260-BK99....................... Inch Standard Bore Adaptor Kit for 260. Includes $0.250 ", 0.375$
and 0.500"

FIELD REPLACEABLE SEALS
Stock \#
161247
Description
161248
Feld Replaceable IP66 seal for 725, 925, IND12 \& TR3
Field Replaceable IP67 seal for 725, 925, TR3
10120
Field Replaceable IP67 seal for 702, 802, 758, 858
161264
Field Replaceable IP66 seal for 702, 802, 758, 858

## ACCESSORIES FOR MAGNETIC ENCODER MODULES

OVER SHAFT MAGNET HOLDERS

| Stock\# | Description |  |
| :---: | :---: | :---: |
| 176596-01. | 3/16" Bore ID |  |
| 176597-01 | 5 mm Bore ID |  |
| 176598-01 .......... | 6mm Bore ID |  |
| 176599-01 ........ | 1/4" Bore ID |  |
| 176600-01 ........ | 5/16" Bore ID |  |
| 176601-01 .......... | 8mm Bore ID |  |
| 176602-01 ........ | 3/8" Bore ID | $\cdots$ |
| 176603-01 .......... | 10 mm Bore ID |  |
| 176604-01. | 1/2" Bore ID | Over Shaft |
| 176605-01.. | 14 mm Bore ID | Magnet Holder |
| 176606-01 .......... | 5/8" Bore ID |  |
| MAGNET |  |  |
| Stock\# | Description |  |
| 030141............... | Raw Magnet |  |

PRESS IN/ON MAGNET HOLDER

Stock\#
176607-01
Description
Press In/On Magnet Holder ( 0.250 " bore/0.125" shaft)


Press In/On Magnet Holder

## SHAFTS

Stock \#
Stock \# $\quad$ Description
176407. $\qquad$ 10:1 Tapered Shaft with Internal Threads 10:1 Tapered Shaft without Internal Threads 176154-01
....................... Model TR1 Replacement Pivot Shaft Kit, 1/4-20 Threaded 176155-01 $\qquad$ Model TR1 Replacement Pivot Shaft Kit, M6 Threaded
176224-01

## SHAFT COUPLINGS

| Stock \# | Length | From shaft size | To shaft s |
| :---: | :---: | :---: | :---: |
| 161307.. | 1.00" | 0.250". | 0.250" |
| 161308. | 1.00 " | 6 mm | 6 mm |
| 161309. | 1.00 " | 6 mm | 0.250" |
| 161314. | 1.00" | 6 mm | 0.375' |
| 161313. | 1.00" | 0.250". | 0.375" |
| 161317.. | 1.00 " | 0.375". | 0.375" |
| 161319. | 1.50" | 0.375" | 0.500" |

 Couplings

MAGNETIC COUPLINGS

| Stock \# | Description |  |
| :---: | :---: | :---: |
| 176282-01 | For Models 260 \& 25 T with a $5 / 8 \prime\left(0.625^{\prime \prime}\right)$ bore |  |
| 176409-01 .........For Models 260 \& 25T with |  |  |
|  | a 3/8" (0.375") bore | Magnetic |
|  |  | Couplings |

## MOUNTING BRACKETS \& OPTIONS

## MOUNTING BRACKETS

Pivot Brackets

## Stock \#

| ) | Single Pivot for Cube Housing* |
| :---: | :---: |
| 176430-02 ........................... | Spring Loaded Single Pivot for Cube Housing* |
| 176431-01 (Replaces 140040). | Double Pivot for Cube Housing* |
| 176431-02 | Spring Loaded Double Pivot for Cube Housing* |
| 176727-01 | Single Pivot Bracket for Size 25 Shaft Encoders* |
| 176727-02 | Spring Loaded Single Pivot Bracket for Size 25 Shaft Encoders* |
|  | Spring Loaded Pivot Mounting Bracket for 702, 725, and 925 |

*Mounting bracket included.
Spring Loaded Pivot Mounting Bracket for 702, 725, and 925

Tru-Trac ${ }^{\text {TM }}$ Optional Mounting Brackets

## Stock \#

140104. 

.........................................................Angled Mounting Bracket for Models TR1 Tru-Trac ${ }^{\text {TM }}$ and TR2 Tru-Trac™
176389-01 $\qquad$ Mounting Plate and Pivot Arm Kit for Model TR3 Tru-Trac ${ }^{\text {TM }}$
176391-01 Double Pivot Bracket Kit for Model TR3 Tru-Trac ${ }^{\text {TM }}$

LCE Optional Mounting Plate
Stock \#
176064-01
Attaches to Standard or Industrial LCE in three different orientations
Foot Mounting Plates \& Brackets
Stock \#
140122.

Use with Clamping Flange 20 Type - 758, 858, 958
176396-01 $\qquad$ Heavy Duty Mounting Plate Kit for HD Cube Housing

## Uni-Brackets

Adapts the Model 260 or Model 702 Flex-Mount to fit a standard motor mount with a mounting bolt circle up to $5.875^{\prime \prime}$ ", such as a NEMA 4.5" AK mount or IEC equivalent.

Stock \#
175997-01 Uni-Bracket Kit

MOUNTING OPTIONS


Heavy Duty Mounting Plate \#176396-01


Foot Mount Bracket \#140122


Three Point Anti-Rotation Flex Mount \#140114-01


Angled Mounting Bracket \#140104

\#175997-01

## MOTOR KITS/COVERS/GASKET KITS

## MOTOR KITS

Model 25 T Encoder with 5-28 VDC Input, A/B/Z Line Driver Outputs, 10 -pin MS Style connector, $-20^{\circ}$ to $105^{\circ} \mathrm{C}$ Temp, IP66 Sealing, SG Tether Arm Kit, 10-pin MS Mating Connector, and 56C Protective Cover.

| MK | 5/8 |
| :---: | :---: |
| MK-56C-25T-002 | 5/8" Bore 2048 CPR |
| MK-56C-25T-003 | ..5/8" Bore 4096 CPR |
| MK-56C-25T-004 | .. 1.0" Bore 1024 CPR |
| MK-56C-25T-005 | .. 1.0" Bore 2048 CPR |
| MK-56C-25T-006 | .. 1.0" Bore 4096 CPR |

Model 25 T Encoder with 5-28 VDC Input, $\mathrm{A} / \mathrm{B} / \mathrm{Z}$ Line Driver Outputs, 10 -pin Bayonet connector, $-20^{\circ}$ to $105^{\circ} \mathrm{C}$ Temp, IP66 Sealing, SG Tether Arm Kit, 10-pin Bayonet Mating Connector and 56C Protective Cover.

| MK-56C-25T-051 | . 18 Bore 1024 CPR |
| :---: | :---: |
| MK-56C-25T-052 | .5/8" Bore 2048 CPR |
| MK-56C-25T-053 | .5/8" Bore 4096 CPR |
| MK-56C-25T-054 | 1.0" Bore 1024 CPR |
| MK-56C-25T-055 | 1.0" Bore 2048 CPR |
| MK-56C-25T-056 | 1.0" Bore 4096 CPR |

## PROTECTIVE COVERS




Motor Kit for Model 25 T


Uni-Cover
\#175996


770 Protective Cover \#770-000-02

771 Protective Cover \#771-000-07

## TRU-TRAC ${ }^{\text {TM }}$ \& LINEAR ENCODER ACCESSORIES

## LINEAR CABLE ACCESSORIES

50 "Linear Cable Adaptor for standard or industrial cube housings. Mounting hardware is included for easy installation directly over the shaft of your existing cube encoder. See Technical Bulletin TB-517 for specific installation instructions.

Stock \#
LCA01............................... 5 50 " Linear Cable Adaptor for Standard Cube Housing with $1 / 4$ " shaft LCA02. 50 " Linear Cable Adaptor for Industrial Cube Housing with $3 / 8^{\prime \prime}$ shaft 176064-01 Optional Mounting Plate and hardware for cube style Linear Cable Encoders

## TR2 RACKS \& ACCESSORIES



LCE Linear Cable Adaptor
\#LCA01
Stock \#
140104.............................. Angle Mounting Bracket
176216.............................. 12" for Stainless Steel
176217.............................. 24" for Stainless Steel
176218.............................. 36" for Stainless Steel
176219.............................. Spacer Block for Stainless Steel
161546.............................. 2 meter Flexible Rack
161548................................. Flexible Rack Clamps 10 pk (with M4 $\times 0.7 \times 1 \mathrm{~mm}$ ) Phillips Pan Head Machine Screws
161547.............................. 1 meter Guide Rail for Flexible Rack (does not work with 176220 gear) 176220.............................. 40 Tooth Pinion Gear for use with Stainless Steel Rack 176302.............................. 40 Tooth Pinion Gear for use with Flexible Rack

For lengths over 36 ", order multiple pieces of rack or the flexible plastic option. A spacer block must be used to accurately join two or more pieces of rack. At encoder.com, see Technical Bulletins TB-522: TR2 - Tru-Trac ${ }^{\text {TM }}$



## BRACKETS WITH MEASURING WHEELS

For most linear measurement applications, our line of Tru-Trac ${ }^{\text {TM }}$ encoders are a great option (see pages 26 - 35 ). These integrated linear measurement solutions are easy to install and deliver reliable, accurate feedback for applications such as cut-to-length, spooling, length measurement, and print registration. Occasionally, though, there is a linear measurement application that requires something our Tru-Trac ${ }^{\text {TM }}$ encoders don't offer. Maybe you need absolute feedback. Maybe you need additional bearing load. Maybe you need the encoder to be programmable. If your application calls for any of those options, we have another solution: a bracket that turns a Size 25 shaft encoder into a linear measurement solution.

## Get Absolute Feedback

Our new bracket is specifically designed to fit our Size 25 shaft encoders, and that includes our absolute Model A25SB (see page 20), a multi-turn absolute encoder. The Model A25SB is ideal for industrial applications that require an encoder with the capability of absolute positioning output, even in power-off scenarios. Offering either SSI or CANopen communication protocols, the Model A25SB features absolute feedback with resolution up to 16 bits single turn and 43 bits multi-turn.

## Need Additional Bearing Load?

For applications requiring additional bearing load, the Model 725I AccuCoder ${ }^{\text {TM }}$ (see page 97) features an extra-heavy-duty industrial housing. In addition to the rated bearing load of 80 lbs , the fully isolated encoder-within-an-encoder design provides an additional layer of protection by using an internal flexible mount and independent set of bearings to further protect the encoder from the effects of severe axial and radial shaft loading.

## Program Your Encoder for Your Application



Single Pivot Bracket for Size 25 Shaft Encoders: \#176727-01 Spring-Loaded Single Pivot Bracket for Size 25 Shaft Encoders: \#176727-02
Mounting bracket is included with both options. Also available as a kit with a Model 25SP programmable encoder. Call our Sales Department for more information.

If you need resolutions beyond 10,000 CPR, the programmable Model 25SP Accu-CoderPro ${ }^{\text {TM }}$ is your answer (see page 88). Like the Model 7251 , this shaft encoder is also designed for the challenges of an industrial environment and offers the same variety of shaft sizes, a range of connectors, and sealing up to IP67. However, the Model $25 S P$ offers programmable output type, waveform, and resolution. There are 6 output options, 32 waveforms to choose from, and you can choose any resolution from 1 to 65,536 CPR - that's 262,144 counts using $4 x$ quadrature counting. The Model 25SP AccuCoderPro ${ }^{\text {TM }}$ comes standard with dual bearings rated 80 lbs axial or radial, and offers up to IP67 sealing. Some configurations are in stock and ready to ship.

## Two Options for Your Bracket

Both types of bracket allow for convenient mounting of an encoder and measuring wheel over the surface being measured, and both allow the assembly to adjust pitch for variations in material height.
The Single Pivot Bracket is gravity loaded and uses the combined weight of the encoder, measuring wheel, and bracket to provide surface torsion.

The Spring Loaded Single Pivot Bracket uses a spring-loaded bracket, which provides an adjustable surface torsion. This allows the encoder and measuring wheel to be mounted in almost any orientation, even upside down.

For more information on choosing the right measuring wheel, see page 35 . If you're which linear measurement solution is right for your application, give us a call. When you call EPC, you talk to real engineers and encoder experts who can help you specify the right encoder solution for your application.

## MEASURING WHEELS

## LINEAR MEASURING WHEELS

Faced Measuring Wheels

| Stock \# | Circumference | Rim Type Bore | Width |
| :---: | :---: | :---: | :---: |
| 161428 (TR3) | 12" | 60 Polyurethane ...............3/8" | 0.75" |
| 161442 (TR3) | . 300 mm ......... | . 60 Polyurethane ...............3/8" | 0.75 " |
| 161336... | . 12". | 80 Polyurethane ..............1/4" | 0.70" |
| 161337. | 12" | . 80 Polyurethane ...............3/8" | 0.70" |
| 161360 (TR1) | .6" | . 85 Polyurethane ...............1/4" | 0.25" |
| 161399 (TR1) | . 200 mm | . 85 Polyurethane ...............1/4" | 0.25" |
| 161338.. | .12". | . 90 Polyurethane ...............1/4". | 0.70" |
| 161339. | .12" | . 90 Polyurethane ...............3/8" | 0.70" |
| 161349. | .12" | . 90 Polyurethane ...............5/8" | 0.70" |
| 161370. | . 6 " | . Knurled ..........................1/4" | 0.4" |
| 161376. | . 6 " | . Knurled ..........................3/8" | 0.4" |
| 161401 (TR1) |  | . Knurled ..........................1/4" | 0.25" |
| 161332.......... | .12" | . Knurled ..........................1/4" | $1^{\prime \prime}$ |
| 161333. | .12" | . Knurled ..........................3/8" | 1" |
| 161362. | .12" | . Knurled ..........................1/4" | 0.4" |
| 161379. | . 12". | . Knurled ..........................3/8" | 0.4" |
| 161432 (TR3) | 12" | Knurled ..........................3/8" | 0.75 " |
| 161361......... | . 1/3 Meter | . Knurled ..........................1/4" | 10 mm |
| 161380. | .. 1/3 Meter. | . Knurled ..........................3/8" | 10 mm |
| 161371. | . 200 mm | . Knurled ..........................1/4" | 10 mm |
| 161400 (TR1) | . 200 mm | . Knurled ..........................1/4" | 0.25" |
| 161424 (TR1) | . 200 mm | . Knurled ..........................1/4". | 0.25" |
| 161372. | .300 mm . | . Knurled ..........................1/4" | 10 mm |
| 161377. | . 300 mm | . Knurled ..........................3/8" | 10 mm |
| 161443 (TR3) | . 300 mm | Knurled ..........................3/8" | 0.75" |
| 161373. | . 400 mm | . Knurled ..........................1/4" | 10 mm |
| 161378. | . 400 mm | . Knurled ..........................3/8" | 10 mm |
| 161374. | . 500 mm | . Knurled ..........................1/4" | 20 mm |
| 161381. | . 500 mm | . Knurled ..........................3/8" | 20 mm |
| 161423 (TR1) |  | . Knurled Hard Anodized .....1/4" | . 0.25 " |
| 161419... | .12" | . Knurled Hard Anodized .....3/8" | 0.4" |
| 161436 (TR3) | .12" | . Knurled Hard Anodized .....3/8" | 0.75" |
| 161438 (TR3).. | . 300 m | . Knurled Hard Anodized .....3/8" | 0.75" |
| 161420.......... | .12" | Knurled Hard Anodized .....3/8" | 1" |
| 161310. | .12" | . 65 Polyurethane ..............1/4" | 1" |
| 161331. | 12" | . 65 Polyurethane ...............3/8" | 1" |
| 161346. | .12" | . 65 Polyurethane ..............1/4" | 1/2" |
| 161347. | 12" | 65 Polyurethane ...............3/8" | 1/2" |
| 161344. | . $1 / 3$ Meter.... | . 65 Polyurethane ..............1/4". | 5/8" |
| 161359 | 1/3 Meter | 65 Polyurethane $3 / 8$ " | 5/8" |

Rubber Insert Measuring Wheels

| Stock \# | Circumference | \# of Inserts | Bore | Width |
| :---: | :---: | :---: | :---: | :---: |
| 161363. | 200 mm |  | .1/4"... | 10 mm |
| 161382. | 200 mm . | 1. | .3/8" | . 10 mm |
| 161364. | 300 mm | 1. | .1/4" | 10 mm |
| 161384. | 300 mm | 1. | .3/8" | . 10 mm |
| 161365. | .400 mm . | 1. | .1/4" | . 10 mm |
| 161385. | 400 mm | 1. | .3/8" | . 10 mm |
| 161366. | 500 mm . | 2. | .1/4" | . 20 mm |
| 161388. | 500 mm . | 2 | .3/8" | . 20 mm |
| 161369. | 1/3 Meter. | 1. | .1/4" | . 10 mm |
| 161387. | 1/3 Meter | 1. | .3/8" | . 10 mm |
| 161367. | 6". | 1. | .1/4" | . 10 mm |
| 161383.... | 6". | 1. | .3/8" | . 10 mm |
| 161368... | 12". | 1. | .1/4" | . 10 mm |
| 161386... | 12" | 1............ | .3/8" | 10 mm |

For more inofrmation on how to choose the right measuring wheel for your application, see page 35.

Measuring Wheel Dimensions

| Rim Facing | Circumference | (A) Rim Width |
| :---: | :---: | :---: |
| Knurled | 12" | $1{ }^{17}$ |
| Rubber | 12 " | $1{ }^{1 \prime}$ |
| 80 Polyurethane | 12 " | 0.70" |
| 90 Polyurethane | 12 " | 0.70" |
| Rubber | 12 " | 1/2" |
| Knurled | $1 / 3$ meter | $5 / 8$ " or 1 " |
| Rubber | $1 / 3$ meter | $5 / 8$ " or 1 " |
| Urethane | $1 / 3$ meter | $1^{1 \prime}$ |
| Temperature Specifications |  |  |
| $\frac{\text { Rubber Faced }}{-40^{\circ} \mathrm{F} \text { to }+275^{\circ} \mathrm{F}}$ | $\frac{\text { Urethane Faced }}{-40^{\circ} \mathrm{F} \text { to }+155^{\circ} \mathrm{F}}$ |  |
| *90 polyurethane forms better for tra slightly softer 80 p recommendations may vary dependi Customer Service | is a more durable acking rough or h polyurethane mate are only guidelin ng on your applic for specification | terial and perfibers than the . The above Performance n. Contact stance. |

may vary depending on your application. Contact Customer Service for specification assistance.


Typical Measuring Wheel


## Recommended Use for Measuring Wheels

| KNURLED FACED |  |
| :---: | :---: |
| Course Fabric | Carpet |
| Cloth Tape | Foam |
| Rough Wood | Insulation |
| Rubber |  |

## 80 POLYURETHANE FACED*

 Soft Materials Smooth Materials

| RUBBER INSERT |  |
| :---: | :---: |
| Fine Fabric | Film |
| Paper | Foil |
| Cable | Metal (cease-free) |
| Hard Plastic |  |

## BRACKETS WITH MEASURING WHEELS

For most linear measurement applications, our line of Tru-Trac ${ }^{\text {TM }}$ encoders are a great option (see pages $26-35$ ), but sometimes using a Cube Encoder (see pages $70-77$ ) with a bracket is the better choice. If you need help determining the best linear measurement solution for your application, give us a call. When you call EPC, you talk to real engineers and encoder experts who understand how encoders work, and can help you specify the right encoder solution for your application.

## Single Pivot Bracket or Spring Loaded Single Pivot Bracket

The Single Pivot Bracket allows for convenient mounting of an encoder and measuring wheel over the surface being measured.

With the Single Pivot Bracket, the gravity-loaded bracket uses the combined weight of the encoder, measuring wheel, and bracket to provide surface torsion, while the single pivot action allows the assembly to adjust pitch for variations in material height.
The Spring Loaded Bracket provides an adjustable surface torsion, which allows the encoder and measuring wheel to be mounted in almost any orientation, even upside down.

For use with Standard and Industrial Cube housing options with single- or double-ended shafts. Right angle bracket and $5 / 8^{\prime \prime}$ diameter bar also included

Single Pivot Bracket Stock \#176389-01
Spring Loaded Single Pivot Bracket Stock \#176389-01


Spring Loaded Single Pivot Bracket

## Double Pivot Bracket or Double Loaded Single Pivot Bracket

The Double Pivot Bracket allows for convenient mounting of an encoder and measuring wheel over the surface being measured.
With the Double Pivot Bracket, gravity loaded bracket uses the combined weight of the encoder, measuring wheel and bracket to provide surface torsion, while the double pivot action allows the assembly to adjust both pitch and roll for variations in the surface being measured.
The Spring Loaded Double Pivot Bracket provides an adjustable surface torsion, which allows the encoder and measuring wheel to be mounted in almost any orientation, even upside down.
For use with Standard and Industrial Cube housing options with double-ended shafts. Right angle bracket and $5 / 8^{\prime \prime}$ diameter bar also included

Double Pivot Bracket Stock \#176431-01
Double Loaded Single Pivot Bracket Stock \#176389-01


Double Pivot Bracket without spring

## Technical Information

## CONNECTOR PIN CONFIGURATION DIAGRAMS

M23 STYLE CONNECTORS


BAYONET STYLE CONNECTORS


MS STYLE CONNECTORS


8-PIN
MOLEX HEADER


M12 STYLE CONNECTORS


CABLE GLAND



16-PIN MOLEX HEADER FOR THE 30M


## Technical Information

## QUADRATURE PHASING AND INDEX GATING OPTIONS

## Standard Quadrature Phasing -

A leads B during clockwise rotation when viewed from the shaft end or mounting face.

| If your model is. | And your output type is. | And you need. | For number of channels enter... | For waveform see... |
| :---: | :---: | :---: | :---: | :---: |
| $15,25,121$ 260, TR1, TR2, TR3 | $\begin{aligned} & \text { OC, PU, HV, OD, } \\ & \text { LO, PP } \end{aligned}$ | Single channel only | A | Figure 1 |
|  |  | Quadrature $A$ and $B$ | Q | Figure 2 |
|  |  | Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $A$ | R | Figure 3 |
|  |  | Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ and $B$ | R3 | Figure 4 |
|  |  | Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $A$ | R5 | Figure 5 |
|  |  | Quadrature $A$ and $B$ with inverted $90^{\circ}$ index gated to $A$ and $B$ | R7 | Figure 6 |
| $\begin{aligned} & 755 \mathrm{~A}, 702,725, \\ & 758,802 \mathrm{~S}, \\ & 858 \mathrm{~S} \end{aligned}$ | HV, PP | Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $A$ | R | Figure 3 |
|  |  | Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $B$ | R2 | Figure 7 |
|  |  | Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ and $B$ | R3 | Figure 4 |
|  |  | Quadrature $A$ and $B$ with ungated index centered on $A$ between $360^{\circ}$ and $180^{\circ}$ | R4 | Figure 8 |
|  |  | Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $A$ | R5 | Figure 5 |
|  |  | Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $B$ | R6 | Figure 9 |
|  |  | Quadrature $A$ and $B$ with inverted $90^{\circ}$ index gated to $A$ and $B$ | R7 | Figure 6 |
|  |  | Quadrature $A$ and $B$ with ungated inverted index centered on $A$ between $360^{\circ}$ and $180^{\circ}$ | R8 | Figure 10 |
| $\begin{aligned} & 755 \mathrm{~A}, 702,725, \\ & 758,802 \mathrm{~S}, \\ & 858 \mathrm{~S} \end{aligned}$ | OC, PU <br> Note: Interpolated units $C P R>3000$ will use HV/PP waveforms. | Quadrature $A$ and $B$ with ungated index centered on Alow between $360^{\circ}$ and $180^{\circ}$ | R | Figure 11 |
|  |  | Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $B$ low | R2 | Figure 12 |
|  |  | Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ low and $B$ low | R3 | Figure 13 |
|  |  | Quadrature $A$ and $B$ with ungated index centered on Alow between $360^{\circ}$ and $180^{\circ}$ | R4 | Figure 14 |
|  |  | Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $A$ low | R5 | Figure 15 |
|  |  | Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $B$ low | R6 | Figure 16 |
|  |  | Quadrature $A$ and $B$ with inverted $90^{\circ}$ index gated to $A$ low and $B$ low | R7 | Figure 17 |
|  |  | Quadrature $A$ and $B$ with ungated inverted index centered on $A$ low between $360^{\circ}$ and $180^{\circ}$ | R8 | Figure 18 |
| $\begin{aligned} & 770,771,775, \\ & 776,865 T \end{aligned}$ | HV, PP | Quadrature A and B | Q | Figure 2 |
|  |  | Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $A$ | R | Figure 3 |
|  |  | Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ and $B$ | R3 | Figure 4 |
|  |  | Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $A$ | R5 | Figure 5 |
|  |  | Quadrature $A$ and $B$ with inverted $90^{\circ}$ index gated to $A$ and $B$ | R7 | Figure 6 |
|  |  |  |  |  |
| $\begin{aligned} & 770,771,775, \\ & 776,865 \mathrm{~T} \end{aligned}$ | OC, PU | Quadrature $A$ and $B$ | Q | Figure 2 |
|  |  | Quadrature $A$ and $B$ with ungated index centered on $A$ low between $360^{\circ}$ and $180^{\circ}$ | R | Figure 11 |
|  |  | Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ low and $B$ low | R3 | Figure 13 |

## Reverse Quadrature Phasing -

$B$ leads A during clockwise rotation when viewed from the shaft end or mounting face.

| If your model is. | And your output type is... | And you need... | For number of channels enter... | For waveform see... |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { 15, 25, 121, } \\ & \text { 260, TR1, TR2, } \\ & \text { TR3 } \end{aligned}$ | $\begin{aligned} & \text { OC, PU, HV, } \\ & \text { OD, LO, PP } \end{aligned}$ | Reverse Quadrature $A$ and $B$ | K | Figure 19 |
|  |  | Reverse Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $B$ low | D | Figure 20 |
|  |  | Reverse Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ low and $B$ low | D3 | Figure 21 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $B$ low | D5 | Figure 22 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $90^{\circ}$ index gated to $A$ low and $B$ low | D7 | Figure 23 |
|  |  |  |  |  |
| $\begin{aligned} & 755 \mathrm{~A}, 702,725, \\ & 758,802 S, \\ & 858 S \end{aligned}$ | HV, PP | Reverse Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $B$ low | D | Figure 20 |
|  |  | Reverse Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $A$ low | D2 | Figure 24 |
|  |  | Reverse Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ low and $B$ low | D3 | Figure 21 |
|  |  | Reverse Quadrature $A$ and $B$ with ungated index centered on B low between $360^{\circ}$ and $180^{\circ}$ | D4 | Figure 25 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $B$ low | D5 | Figure 22 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $A$ low | D6 | Figure 26 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $90^{\circ}$ index gated to $A$ low and $B$ low | D7 | Figure 23 |
|  |  | Reverse Quadrature A and B with ungated inverted index centered on B low between $360^{\circ}$ and $180^{\circ}$ | D8 | Figure 27 |
|  |  |  |  |  |
| $\begin{aligned} & 755 \mathrm{~A}, 702,725, \\ & 758,802 \mathrm{~S}, \\ & 858 \mathrm{~S} \end{aligned}$ | OC, PU <br> Note: <br> Interpolated <br> units <br> CPR>3000 <br> will use HV/PP <br> waveforms. | Reverse Quadrature $A$ and $B$ with ungated index centered on $B$ low between $360^{\circ}$ and $180^{\circ}$ | D | Figure 28 |
|  |  | Reverse Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $A$ low | D2 | Figure 24 |
|  |  | Reverse Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ low and $B$ low | D3 | Figure 21 |
|  |  | Reverse Quadrature $A$ and $B$ with ungated index centered on $B$ low between $360^{\circ}$ and $180^{\circ}$ | D4 | Figure 25 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $B$ low | D5 | Figure 22 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $A$ low | D6 | Figure 26 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $90^{\circ}$ index gated to $A$ low and $B$ low | D7 | Figure 23 |
|  |  | Reverse Quadrature $A$ and $B$ with ungated inverted index centered on $B$ low between $360^{\circ}$ and $180^{\circ}$ | D8 | Figure 27 |
|  |  |  |  |  |
| $\begin{aligned} & 770,771,775, \\ & 776,865 T \end{aligned}$ | HV, PP | Reverse Quadrature $A$ and $B$ | K | Figure 19 |
|  |  | Reverse Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $B$ low | D | Figure 20 |
|  |  | Reverse Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ low and $B$ low | D3 | Figure 21 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $180^{\circ}$ index gated to $B$ low | D5 | Figure 22 |
|  |  | Reverse Quadrature $A$ and $B$ with inverted $90^{\circ}$ index gated to $A$ low and $B$ low | D7 | Figure 23 |
|  |  |  |  |  |
| $\begin{aligned} & 770,771,775, \\ & 776,865 T \end{aligned}$ | OC, PU | Reverse Quadrature $A$ and $B$ | K | Figure 19 |
|  |  | Reverse Quadrature $A$ and $B$ with $180^{\circ}$ index gated to $B$ low | D | Figure 20 |
|  |  | Reverse Quadrature $A$ and $B$ with $90^{\circ}$ index gated to $A$ low and $B$ low | D3 | Figure 21 |

## WAVEFORM DIAGRAMS



Figure 1: Single channel only


Figure 5: Quadrature $A$ and $B$ with inverted $180^{\circ}$ Index gated to $A$


Figure 2: Quadrature $A$ and $B$


Figure 6: Quadrature A and B with inverted $90^{\circ}$ Index gated to $A$ and $B$


Figure 10: Quadrature $A$ and $B$ with ungated inverted Index centered on A between $360^{\circ}$ and $180^{\circ}$

R4


[^11]

Figure 3: Quadrature A and B with $180^{\circ}$ Index gated to A

## R2



Figure 7: Quadrature $A$ and $B$ with $180^{\circ}$ Index gated to $B$


Figure 11: Quadrature $A$ and $B$ with ungated Index centered on A low between $360^{\circ}$ and $180^{\circ}$


Figure 15: Quadrature $A$ and $B$ with inverted $180^{\circ}$ Index gated to A low


Figure 4: Quadrature $A$ and $B$ with $90^{\circ}$ Index gated to $A$ and $B$

## R4



Figure 8: Quadrature $A$ and $B$ with ungated Index centered on A between $360^{\circ}$ and $180^{\circ}$


Figure 12: Quadrature A and B with $180^{\circ}$ Index gated to B low


Figure 13: Quadrature $A$ and $B$ with $90^{\circ}$ Index gated to A low and B low

## R6



Figure 9: Quadrature $A$ and $B$ with inverted $180^{\circ}$ Index gated to $B$


Figure 17: Quadrature $A$ and $B$ with inverted $90^{\circ}$ Index gated to $A$ low and $B$ low


Figure 21: Reverse Quadrature $A$ and $B$ with $90^{\circ}$ Index gated to $A$ low and $B$ low


Figure 25: Reverse Quadrature $A$ and $B$ with ungated Index centered on $B$ low between $360^{\circ}$ and $180^{\circ}$


Figure 18: Quadrature $A$ and $B$ with ungated inverted Index centered on A low between $360^{\circ}$ and $180^{\circ}$


Figure 22: Reverse Quadrature $A$ and $B$ with inverted $180^{\circ}$ Index gated to B low


Figure 26: Reverse Quadrature $A$ and $B$ with inverted $180^{\circ}$ Index gated to A low


Figure 19: Reverse Quadrature $A$ and $B$

## D7



Figure 23: Reverse Quadrature A and B with inverted $90^{\circ}$ Index gated to A low and B low


Figure 27: Reverse Quadrature $A$ and $B$ with ungated and inverted Index centered on B low between $360^{\circ}$ and $180^{\circ}$


Figure 20: Reverse Quadrature $A$ and $B$ with $180^{\circ}$ Index gated to B low


Figure 24: Reverse Quadrature $A$ and $B$ with $180^{\circ}$ Index gated to A low


Figure 28: Reverse Quadrature $A$ and $B$ with ungated Index centered on B low between $360^{\circ}$ and $180^{\circ}$

## Call Sales \& Customer Service at 800-366-5412

EPC is open for business from
8:00 am to 7:30 pm Eastern Time/ 5:00 am to $4: 30$ pm Pacific Time

## Technical Information

## ORDERING / TECHNICAL SUPPORT

## Lead Time

Standard lead time is 4 to 6 business days. Expedite Service is available upon request. Accessories are generally in stock and available for quick delivery. Contact Customer Service to confirm lead times. Single-piece orders for many of our products can ship the next business day. Contact Customer Service for details.

## Expedited Service

Express and expedite services are available for most product configurations should you need a product faster than the standard lead times allows. Contact Customer Service for details.

## Telephone Orders

All telephone orders must be confirmed by mail or fax. Please be sure the order is clearly marked "confirmation". Please check your purchase order against the acknowledgment that Encoder Products Company faxes to you. To ensure accuracy, a Customer Service Representative will check your confirmation against your order.

## Change Orders

To change an order, ask for a Customer Service Representative. For faster service, either have your purchase order number or Encoder Products Company's sales order number available. Service charges are assessed for some changes, including order cancellations. Contact Customer Service to determine applicable charges.

Orders will be shipped out by UPS or Federal Express. All shipments are F.O.B. factory. If you are a new OEM account or have a new OEM application, consignment or evaluation units may be available for up to 60 days. Contact Customer Service for complete details.

## Part Numbering

Encoder part numbers are found on the model datasheet at encoder.com. Use the appropriate Ordering Guide for your particular model. It is important to specify the complete part number. If you are reordering, the serial number of the unit being replaced will help speed the ordering process. Ordering with incomplete information may delay product delivery. In addition, Encoder Products Company cannot assume responsibility for errors when a part number is incomplete. If you need help creating a part number, contact Customer Service. Encoder Products

Company has distributors across the United States and Canada. Call 800-366-5412 and ask a Customer Service Representative for a distributor in your area.

## Technical Support

Our Technical Support professionals are available to assist you in your application needs - whether it's selecting the right encoder for your application, troubleshooting a new installation, or connecting your new encoder to your motion control system.

Encoder Products Company understands the importance of time when you have a machine down. Through our free Cross Reference and Retrofit Service, and thanks to a thorough library of specifications and dimensional information for a wide range of competitive encoders, EPC offers expert assistance for the cross-referencing and/or retrofit replacement of most domestic and foreign optical rotary encoders. In addition, serviceable replacements can often be found for encoders that use other technologies. As a final service, for those hard to find units, EPC can often suggest an alternative approach that will get you back up and running. We have provided an Expert Cross-Reference Service page on our website. It provides you with part numbers of competitors' encoders, and compares them with EPC encoders, so that you can begin the cross-referencing process.

Each Accu-Coder ${ }^{\text {TM }}$ manufactured by Encoder Products Company is backed by our industry-leading three--year warranty. If you experience a problem, call our trained professionals. We can often troubleshoot a problem over the phone and determine if a repair is needed. If it's necessary to return the encoder for repair, our technicians will perform a complete evaluation and recommend a course of action. In an emergency situation our technicians can often have your evaluation and repair completed, and ready for return shipment, within a matter of hours after receiving your encoder.

If your application calls for a solution that cannot be solved using off-the-shelf-products, EPC's Custom Design Service may be just what you need. Call Customer Service to put our expertise to work for you.

## WARRANTY/RETURNS/REPAIRS

## Warranty Policy:

Products manufactured by Encoder Products Company Inc. (EPC) are warranted against defects in materials and workmanship and are warranted to meet the performance specifications as listed in the current catalog and/or data sheet for the specific product being warranted. This warranty applies to all standard catalog product configurations, with the exception of units with a rated operating temperature exceeding $85^{\circ} \mathrm{C}$, for three (3) years following the date of shipment. For units with a rated operating temperature exceeding $85^{\circ} \mathrm{C}$, the warranty period shall be two (2) years following the date of shipment. During that period, EPC will, at its sole option, repair or replace, at no cost to the customer, products that prove to be defective, provided the defect or failure is not due to misuse or abuse of the product. Any unauthorized attempt to repair the product(s) by the customer, or any unauthorized modifications by the customer, can, at EPC's sole option, cause this warranty to become null and void. In addition, this warranty does not apply to products that have been subjected to abuse or operated in environments that exceed their design specifications. The customer is responsible for shipment of the defective product to the EPC factory. Any warranty service (consisting of time, travel, and expenses related to such services) performed other than at EPC's factory, shall be at the customer's expense.

Limitations:

[^12]OF SUITABILITY, COMPATIBILITY OR PERFORMANCE OF ANY SOFTWARE PROVIDED TO CLIENT AND MAY AT ITS OPTION REPLACE OR REPAIR ANY DEFECTIVE SOFTWARE. EPC RESERVES THE RIGHT TO UPDATE, REVISE AND AMEND ALL SOFTWARE AND TECHNICAL DATA OR CONTENTAT ANY TIME. EPC SHALL HAVE NO LIABILITY OF ANY KIND OR NATURE FOR ANY TECHNICAL ERRORS OR OMISSIONS IN ANY SOFTWARE OR TECHNICAL DATA.

## Return Policy

Only products currently stocked by EPC may be returned for restocking. Products that have been manufactured or configured to customer specifications are not stocked and may not be returned. Returned products are subject to a restocking fee of $\$ 25$ or $25 \%$ of the purchase price, whichever is greater, and must be returned within 30 days of the date shipped from EPC.

All products being returned must be $100 \%$ complete and must be packaged in ORIGINAL PACKAGING. All packaging materials, manuals, other accessories and documentation must be included in the original packaging. In the event that a return shipment received by us is improperly packaged, altered, or physically damaged, items sent for return consideration will be denied, and EPC's return policy will not be honored. All items will be inspected and tested upon receipt.

A Return Materials Authorization (RMA) number is required for any item returned for credit. RMA numbers may be obtained by contacting Customer Service in advance. RMA numbers will be issued to original purchaser only.

## Repair Services

Each Accu-Coder ${ }^{\text {TM }}$ manufactured by Encoder Products Company is backed by our industry-leading three year warranty. If you experience a problem, call our trained professionals. We can often troubleshoot a problem over the phone and determine if a repair is needed. If it's necessary to return the encoder for repair, our technicians will perform a complete evaluation and recommend a course of action. In an emergency situation, our technicians can often have your evaluation and repair completed, and ready for return shipment, within a matter of hours after receiving your encoder.

## SHAFT LOADING AND SEALING VS. BEARING LIFE EXPECTANCY

The mechanical life of an encoder is mainly determined by the life of the unit's bearings. Several factors affect bearing life, including shaft loading, heat, ingress, and rotational speed.

## Shaft Loading

Shaft loading is likely the top cause of premature bearing failure. There are two types of loading to consider: radial and axial.

- Radial loading is the perpendicular force applied to the shaft. Common causes of radial loading include misalignment of the shaft when mounted or use of items such as pulley and gears.
- Axial loading is the parallel force, or force applied along the same direction of the shaft. As radial and/or axial loading increases, bearing life shortens. For this reason, the minimum amount of shaft loading or misalignment should always be the goal when installing an encoder.


The Model 25SP Programmable Size 25 Shaft Encoder Comes standard with dual bearings rated 80lbs axial or radial. See page 88 for product details.

One important loading fact to remember: radial shaft loading increases as a linear function the further away from the bearing the force is applied, much the same way a longer wrench gives you greater leverage against a stubborn bolt. It is always best practice to place any unavoidable radial load as close to the bearings as possible.

## Heat

Heat is another factor affecting bearing. Excessive temperatures can thin out the grease in the bearings. As the grease thins, lubrication reduces and bearing wear increases.

## Ingress

Ingress is the introduction of foreign matter into the bearings. Ingress of foreign matter, whether it is in liquid or solid form, is another common cause of rapid bearing failure. Ball bearings are precision devices with critical internal clearances. Anything that disturbs these clearances will shorten the life of the bearing, often quite drastically. For this reason, many encoders are available with shaft seals that help guard the unit and bearings against the ingress of foreign substances.

All of the factors discussed above, combined with the speed of rotation, work together to determine bearing life. In a worst case condition that combines high shaft loading, high heat, and excessive foreign matter with high rotational speeds, bearing life will likely not be what would be expect to be within the range of typical. An encoder subjected to the same factors at lower rotational speeds might never cause any concern with the life expectancy of the bearings.


To realize the maximum life potential of an encoder, take the necessary precautions when installing the unit for proper shaft alignment, specify shaft seals (see page 137) when needed to protect from foreign materials, and do not subject the unit to any unnecessary heat.

If you still have questions about output, or anything else encoder-related, call EPC When you call EPC, you talk to engineers and encoder experts who can answer your toughest encoder questions. Call today to get the information you need.

## IP RATINGS AND SEALING OPTIONS FOR EPC ENCODERS

Encoder Products Company uses the international standard IP Code, International Protection Marking, IEC standard 605291, for specifying the sealing qualities of our units. The chart below explains what the different numerical designations define. Note that the designations build on the previous ones; that is, an IP69K rating means that unit is also protected against everything that a unit rated IP68, IP67, IP66, etc., is protected against.

EPC encoders offer the following sealing designations on our encoders:

IP50: Unit is not entirely protected from ingress of dust, but not enough dust can enter the unit to interfere with the unit's function. Unit is not protected from water/moisture.

All IP designations of IP60 or higher are protected completely against dust ingress; i.e., "dust-tight".

IP64: Dust-tight. Protected against water sprays from all directions, with limited ingress permitted.

IP65: Dust-tight. Protected against low-pressure jets of water in all directions, with limited ingress permitted.

IP66: Dust-tight. Protected against strongpressure jets of water in all directions, with limited ingress permitted.

IP67: Dust-tight. Protected against water immersion between 15 cm and 1 m for a duration of 30 minutes.

IP69K: Dust-tight. Protected against continuous immersion in water, and Protected against closerange, high pressure, high temperature spray downs.

For help determining which IP rating is right for the encoder in your application, contact our Technical Services Department at 1-800-366-5412.

[^13]| 1st Digit | Protection Against Solids | 2nd Digit | Protection Against Liquids |
| :---: | :---: | :---: | :---: |
| 0 | No Protection | 0 | No Protection |
| 1 |  | 1 | Protected against vertically falling drops of water |
| 2 |  | 2 | Protected against <br> direct sprays of water up to $15^{\circ}$ from the vertical |
| 3 | Protected against than 2.5 mm | 3 |  |
| 4 | Protected against solid objects greater than 1 mm | 4 |  Protected against <br> 1 directions - limited <br> ingress permitted  |
| 5 | Dust protected | 5 | Protected againstlow pressure jets ofwater from all directionslimited ingress permitted |
| 6 | Dust tight | 6 | Protected againststrong pressure jets of water from all directionslimited ingress permitted |
|  |  | 7 | Protected against water immersion between 15 cm and 1 m fora duration of 30 minutes |
|  |  | 8 | Protected against continuous immersion in water |
|  |  | 9K | Protected against closerange, high pressure, hightemperaturespray downs |

IP Ratings system

## Technical Information

## CE OPTION/CABLE CONSIDERATIONS

## the ce mark option

## Please read carefully before choosing the CE Mark option.

The CE (Conformite European) mark indicates that a product complies with the European Union (EU) directives, and will affect you only if your system is to be sold in Europe. CE does not describe the quality of a product, only that it complies with relevant EU directives and can be incorporated into systems sold in the European market.

Select encoder series manufactured by Encoder Products Company (EPC) are tested in accordance with harmonized standards to meet specific noise immunity and emission requirements for an industrial environment, so as to comply with European directives. These tests ensure that, when you order CE certified encoders from Encoder Products Company, they will operate without disturbing other equipment and without being disturbed themselves. Testing for CE certification is performed on encoders with 6 feet of cable or standard body mount connectors. These testing limitations should be taken into consideration any time the CE mark is ordered in combination with non-standard connectors or cable lengths in excess of 6 feet.

It should be understood that CE wiring techniques may cause severe ground loops if used with systems other than CE certified systems. Therefore, we strongly suggest that the CE encoder option only be used with CE wired systems, or in situations where the user has a clear understanding of the CE requirements. For markets other than the EU, Encoder Products Company maintains the strictest tests to ensure that non-CE units are shielded and grounded against electromagnetic phenomenon.

## CABLE CONSIDERATIONS

When the electrical signals are generated by an EPC Accu-Coder ${ }^{\text {TM }}$ encoder, they are electrically "clean" in the sense of being noise free. However, due to a number of factors, these signals can be degraded by the time they reach their intended destination Environmental factors, such as radiated and induced electrical noise, can introduce signal distortions. In addition, system design factors, such as cable capacitance (especially over long cable runs), impedance mismatches, poor cable quality, inadequate shielding, poor grounding, and poor cable termination can all contribute to signal loss and distortion.

## Cable Considerations

All cables have small amounts of capacitance between adjacent conductors. The amount of capacitance present is a direct function of the cable's length. As capacitance increases, it tends to round off the leading edge of the square wave signal, decreasing rise times. It can also distort the signal to the extent that errors are caused in the system. Signal distortion is not usually significant for lengths less than 30 ft (or 1000 picofarads). To minimize the distortion, a low capacitance cable (less than 35 picofarads per foot) is recommended. Cable lengths should also be as short as possible.

If it is necessary for the cable length to exceed 30 feet, the use of a Line Driver output (output option HV or H 5 in the Ordering Guide) along with differential type receiver circuitry is strongly recommended. A low capacitance twisted-shielded pair cable should be used whenever using differential signals with cable lengths in excess of 30 ft . Contact Customer Service for additional information. For high frequency applications (>200kHz), this type of cable may be needed for all lengths. EPC's standard cable has a braided and foil shield, but it is not twisted-shielded pair cable. Therefore, for high frequency applications, it is highly recommended that the user terminate the standard cable just outside the encoder, and then run a low capacitance twisted-shielded pair cable the remaining distance.

Proper cable termination is also extremely important with differential signals. You can try a simple, non-terminated configuration first. However, keep in mind that signal reflections may occur, resulting in severely distorted waveforms. For this type of signal distortion, parallel termination is recommended, which involves placing a resistor across the differential lines at the far (receiver) end of the line. This resistor should be approximately equivalent to, or up to $10 \%$ greater than, the characteristic impedance of the cable (Zo) [usually between $70-150 \mathrm{ohms}$ ]. This permits higher frequencies to be transmitted without significant distortion. Unfortunately, low valued resistors can increase the power dissipated by the Line Driver, and reduce the output signal level. In this case, a capacitor should be placed in series with the resistor. The capacitor value should be equal to the round trip delay of the cable divided by the cables Zo . Round trip delay is equal to the cable length multiplied by $1.7 \mathrm{~ns} / \mathrm{ft}$. (Note that the RC time constant of this type of termination can reduce the system frequency response.)

A parallel termination resistor of a larger value than given above can often provide adequate reduction of signal reflections, and still maintain adequate frequency response with low power dissipation. Experimentation in an application consisting of long cable runs will usually result in the best balance of all of these factors.

## Grounding Considerations

A common cause of signal distortion in systems is poor grounding. The following tips will help eliminate distortions due to grounding:

1. It is extremely important that cable shields are connected to the receiver/instrument (counter, PLC, etc.) ground.
2. Always make sure the motor/machine for which the encoder is mounted is properly grounded.
3. The encoder case should also be grounded with the following conditions:
a. DO NOT ground the encoder case through both the motor/machine and the cable wiring.
b. DO NOT allow the encoder cable wiring to ground the motor/machine exclusively. High motor/machine ground currents could flow through the encoder wiring, potentially damaging the encoder and associated equipment.

## GLOSSARY

## Absolute Encoder

An absolute encoder is a device that provides a unique code for each position, meaning that an absolute encoder provides both the indication that the position has changed and an indication of the absolute position of the encoder.

## Accuracy

Related to the incremental encoding disk. It is the difference between the theoretical position of one increment or bit edge and the actual position of the edge.

## Axial Loading

The force applied to a shaft end surface directed along the axis of rotation.

## Axial Load (maximum)

Maximum axial load is the maximum force that may be applied to the shaft without reducing the rated operating life or causing deviation from the rated performance.

## Bi-directional

Bi-directional refers to an encoder output code format from which direction of travel can be determined.

## CE (Conformite European or European Compliance)

Sets essential electromagnetic compatibility, within the European markets, for all electrical and electronic equipment that may interfere with other equipment, or that may be interfered by other equipment.

## Channel

Each channel is a unique incremental output of the encoder.

## Current Sinking Output

A logic form that requires current flow out of the input of the PLC or counter and back to the output of the encoder. The encoder "sinks" this current, which is "sourced" by the input circuitry. This is the most common output circuit configuration. It uses an NPN output transistor in the encoder.

## Current Sourcing Output

A logic form that requires current flow from the output of the encoder to the input of the counter or PLC. The encoder "sources" the current and the input circuitry of the counter or PLC "sinks" this current. This output circuit is seldom used. It usually requires a PNP output transistor in the encoder.

## Cycles Per Revolution

Called CPR. The number of increments on the disk of an incremental encoder. A one thousand increment encoder has a CPR of 1000.

## Differential Output

Differential output refers to the complementary outputs from a feedback device when the signals are excited by a Line Driver. Optimum performance is achieved when the receiver input impedance is matched to the line receiver output and transmission line.

## Disc

Typically made of glass, metal or plastic with precise position incremental lines. These lines are also known as increments. The number of increments determines the resolution or CPR of the encoder.

## Encoder (shaft type)

An encoder is an electro-mechanical device that translates mechanical motion (such as position, velocity, acceleration, speed, direction) into electrical signals.

## Frequency Response

The maximum frequency in cycles per second.

## Incremental Encoder

An incremental encoder is a device that provides a series of periodic signals due to mechanical motion. The number of successive cycles corresponds to the resolvable mechanical increments of motion.

## Index Reference

The index is a separate output generated by a special track which produces a single cycle (or transition change) at a unique position or positions such as center, home, zero, or reset point. Sometimes referred to as a marker pulse.

## IP Sealing

Encoder Products Company uses the international standard IP Code, International Protection Marking, IEC standard 60529, for specifying the sealing qualities of our units. The chart on page 137 explains what the different numerical designations define.

## Line Driver

A circuit that provides error-free output pulses in electrically noisy environments or over long transmission lines when used with a line receiver.

## Negative Going Pulse

When activated, the pulse goes low (logic 0 ) or in a negative direction. Do not be confused by "negative going" meaning the pulse goes negative in relationship to the signal common or reference level. These statements are for "positive logic" only. All shaft encoders are based on positive logic.

## Technical Information

## GLOSSARY

## Open Collector Output

When the signal is taken directly off the collector element of the output transistor, no Pull-Up is used. This is the electronic equivalent of a mechanical switch closure to common. The input device of the PLC or counter is effectively placed in a series circuit that includes the output transistor and input device, which is often an opto-isolator and the positive voltage supply. When the output transistor turns on, the circuit is completed and current will flow. The output signal cannot be observed unless the circuit is completed externally.

## Positive Going Pulse

In the low or logic 0 state, it is in the quiescent state. It goes high or logic 1 when activated. This is a transition in the "positive going" direction.

## Potato

A tuberous root credited with generating as much fame for the state of Idaho as their encoder prowess.

## Pulses Per Revolution

Number of pulses occurring in one revolution of the encoder shaft.

## Pulse Polarity

Either positive going or negative going. A pulse has two logic states: activated or inactivated. These two states are opposite. When the pulse is in its quiescent state (high or low), it is at one particular logic level ( 1 or 0 ). When the pulse hits or is in the activated state, this logic level reverses itself for the duration of the pulse.

## Pulse Width

The actual real time between the leading and trailing edge of a pulse. The pulse width of the output signal of most encoders is a $50 \%$ duty cycle on the clock outputs. Some models utilize a timed or "one shot" output. This provides a constant pulse width irrespective of the pulse repetition rate or shaft speed. The factors to be considered when determining pulse width specifications are: (1.) What is the minimum pulse width requirement of the counter or PLC? This information is available in the counter or PLC specifications. (2.) Pulse repetition rate versus pulse width. With a constant pulse width, the individual pulses become closer together as the pulse repetition rate or shaft speed increases. At some point the pulses will overlap and the output signal as a series of well defined pulses ceases. The pulse repetition rate varies inversely with the pulse width and vice versa.

## Pull-Up Resistor

When added inside the encoder between the positive voltage and the collector element of the output transistor, it becomes a "pull-up" circuit. This is also know as a pulse output.

## Push-Pull Output

An output circuit that will both sink and source current.

## Quadrature

A dual output encoder used for bi-directional motion control. One channel leads the other by $90^{\circ}$ electrical. By monitoring the phase shift of both channel $A$ and $B$, direction can be determined. Another benefit of a quadrature encoder is count multiplication. With an appropriate counter, resolution can be multiplied up to four times. For instance, using this technique an encoder with CPR of 1000 can provide a resolution of up to 4000 pulses per shaft revolution.

## Quadrature Error

Quadrature error is the phase error when the specified phase relationship between two channels is nominally $90^{\circ}$ electrical.

## Radial Load

The force applied at a specific point to the encoder shaft perpendicular to the axis of rotation.

## Radial Load (maximum)

The maximum force that may be applied perpendicularly to the shaft without reducing the rated operating life or causing deviation from the rated performance.

## Resolution

The number of increments on the encoder disk. For incremental encoders, resolution is defined as cycles per revolution.

## Shaft Runout

Amount of shaft movement while spinning.

## Single Channel

A single channel encoder produces one incremental output. They are often used for tachometry applications.

## Torque (running)

Running torque is the rotary force required to keep an encoder shaft turning. It is typically expressed in oz-in.

## Torque, Starting (breakaway)

Starting (breakaway) torque is the rotary force required to overcome static friction and cause the encoder shaft to begin rotating.

## Unidirectional

An encoder that generates a single stream of pulse counts regardless of direction of shaft rotation. Unidirectional encoders are not capable of determining direction of shaft rotation.


## $0$

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[^0]:    NOTES:
    Please refer to CANopen Interface Technical Reference Manual at encoder.com.
    2 Please refer to Technical Bulletin TB-529: Understanding EPC's SSI Encoders at encoder.com.
    3 Available with SSI only.
    4 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
    5 Available with CANopen only.

[^1]:    ${ }^{\dagger}$ Standard cable is 24 AWG conductors with foil and braid shield.

[^2]:    1 Please refer to CANopen Interface Technical Reference Manual at encoder.com.
    2 Please refer to Technical Bulletin TB-529: Understanding EPC's SSI Encoders at encoder.com.
    3 Available with SSI only.
    4 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
    5 Available with CANopen only.

[^3]:    NOTES:
    1 For non-standard cable lengths, add a forward slash (/) plus cable length expressed in feet. Example:
    G/6 $=6$ feet of cable.
    2 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

[^4]:    Ce Option: Cable shield (bare wire) is connected to internal case.
    †Standard cable is 24 AWG conductors with foil and braid shield.
    **CE Option: Use cable cordset with shield connected to M12 connector coupling nut.

[^5]:    All dimensions are in inches with a tolerance of $\pm 0.005^{\prime \prime}$ or $\pm 0.01$ " unless otherwise specified.

[^6]:    †Standard cable is 24 AWG conductors with foil and braid shield.

[^7]:    NOTES:
    1 Programmable feature using Field Programming Software, USB Programming Module, and Interface Cable. For more information, see EPC Field Programming Software User Guide at encoder.com.
    2 Open Collector (OC) and Pull-Up Resistor (PU) outputs not recommended for CPR > 8192 and/or frequencies $>150 \mathrm{KHz}$.
    3 If ordered with initial output type of either H5 or P5, encoder cannot be programmed to OC, PP, or HV output types.
    $4 \quad 7$-pin MS Connector does not provide Index Pulse Z when selected output is Line Driver (HV or H5).
    6 For non-standard English cable lengths enter ' $F$ ' plus cable length expressed in feet. Example: $F 06=6$ feet of cable. For non-standard metric cable lengths enter ' M ' plus cable length expressed in meters. Example: M06 = 6 meters of cable. Frequency above 300 kHz standard cable lengths only.
    7 Please refer to Technical Bulletin TB100: When to Choose the CE Mark at encoder.com.

[^8]:    Available with 0.250 " shaft only.
    Only available with 6 -pin MS or Screw Terminal Connector Types.
    Only available with $5 / 16^{\prime \prime}, 0.3125^{\prime \prime}$ shaft.
    Contact Customer Service for custom shaft lengths and diameters.
    Standard housing only.
    Standard or 5PY housing only.
    HD10 housing only.
    8 Not available for HD or EX housings.
    9 For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams at encoder.com.
    10 For non-standard cable lengths, add a forward slash (/) plus cable length expressed in feet. Example: $\mathrm{G} / 6=6$ feet of cable.
    For CPR > 2500. Standard cable length only.
    11 Screw terminals available for HD and EX housings. Solder terminals available for S and S 1 housings.

[^9]:    *CE Option: Cable shield (bare wire) is connected to internal case.

[^10]:    NOTES:
    124 V Maximum Voltage.
    2 Encoder/Sensor and output signal voltages are limited to the input voltage supplied. 5P Input Signal not available with 5-24Vcc option.
    3 TTL, RS422 \& RS485 Compatible.
    4 TTL, NPN (Sink), PNP (Source), PP.
    5 HTL Compatible.
    6 NPN (Sink), PNP (Source), PP.

[^11]:    Figure 14: Quadrature $A$ and $B$ with ungated Index centered on A low between $360^{\circ}$ and $180^{\circ}$

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[^13]:    ${ }^{1}$ See http://www.iec.ch/ for testing standards.

